

LECTURE 5

Single-Cycle
Datapath and Control

PROCESSORS

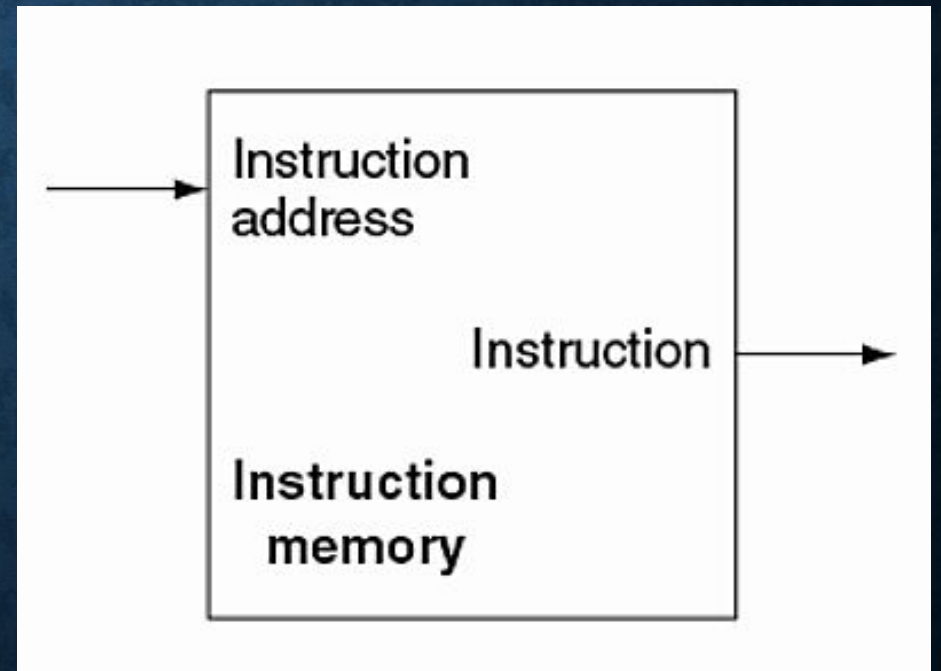
- *Datapath* and *control* are the two components that come together to be collectively known as the processor.
- Datapath consists of the functional units of the processor.
 - Elements that hold data.
 - Program Counter, Register File, Instruction Memory, etc.
 - Elements that operate on data.
 - ALU, adders, etc.
 - Buses for transferring data between elements.
- Control commands the datapath regarding when and how to route and operate on data.

MIPS

- To showcase the process of creating a datapath and designing a control, we will be using a subset of the MIPS instruction set. Our available instructions include:
 - `add, sub, and, or, slt`
 - `lw, sw`
 - `beq, j`

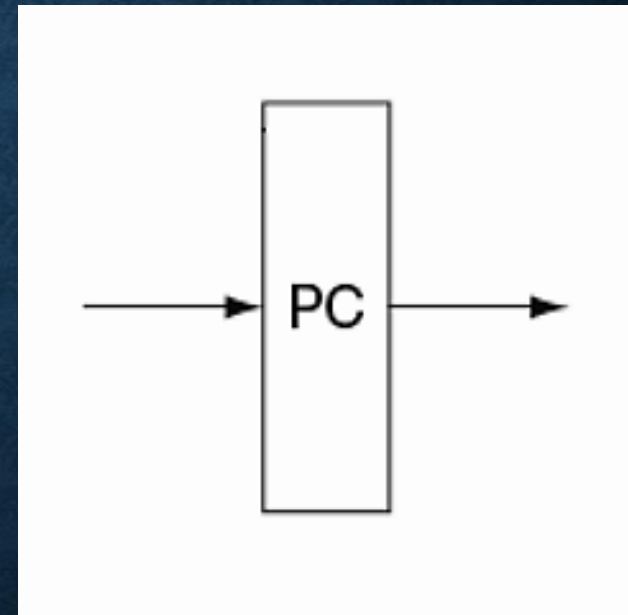
DATAPATH

- To start, we will look at the datapath elements needed by every instruction.
- First, we have *instruction memory*.
- Instruction memory is a state element that provides read-access to the instructions of a program and, given an address as input, supplies the corresponding instruction at that address.



DATAPATH

- Next, we have the *program counter* or *PC*.
- The PC is a state element that holds the address of the current instruction. Essentially, it is just a 32-bit register which holds the instruction address and is updated at the end of every clock cycle.
- The arrows on either side indicate that the PC state element is both readable and writeable.

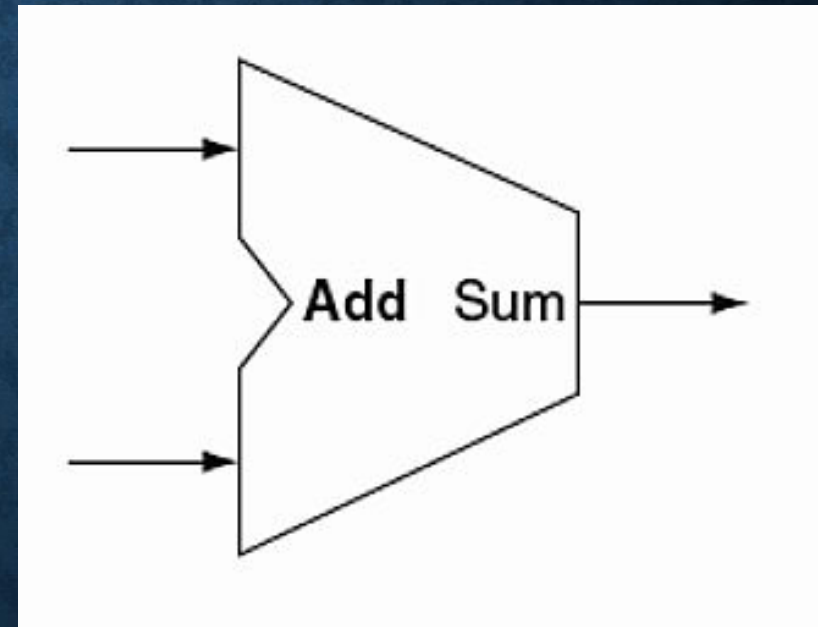


DATAPATH

- Lastly, we have the *adder*.

The adder is responsible for incrementing the PC to hold the address of the next instruction.

- It takes two input values, adds them together and outputs the result.

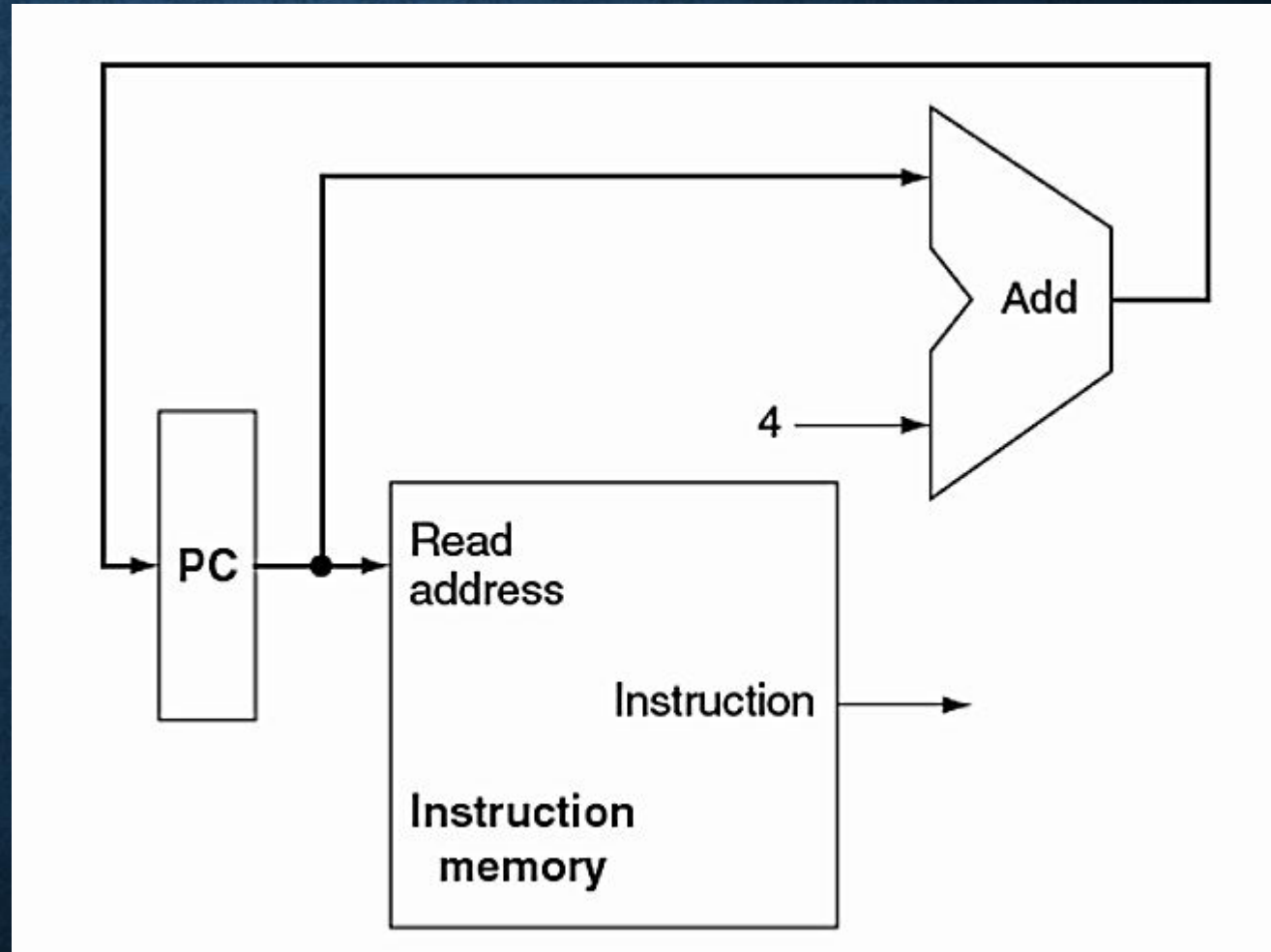


DATAPATH

- So now we have instruction memory, PC, and adder datapath elements. Now, we can talk about the general steps taken to execute a program.
- Use the address in the PC to fetch the current instruction from instruction memory.
- Determine the fields within the instruction (*decode* the instruction).
- Perform the operation indicated by the instruction.
- Update the PC to hold the address of the next instruction.

DATAPATH

- Use the address in the PC to fetch the current instruction from instruction memory.
- Determine the fields within the instruction (*decode* the instruction).
- Perform the operation indicated by the instruction.
- Update the PC to hold the address of the next instruction.



Note: we perform $PC+4$ because instructions are word-aligned.

R-FORMAT INSTRUCTIONS

- Now, let's consider R-format instructions. In our limited MIPS instruction set, these are *add*, *sub*, *and*, *or* and *slt*.
- All R-format instructions read two registers, *rs* and *rt*, and write to a register *rd*.

Name	Fields					
Field Size	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits
R format	op	rs	rt	rd	shamt	funct

op – instruction opcode.

rd – register destination operand.

rs – first register source operand.

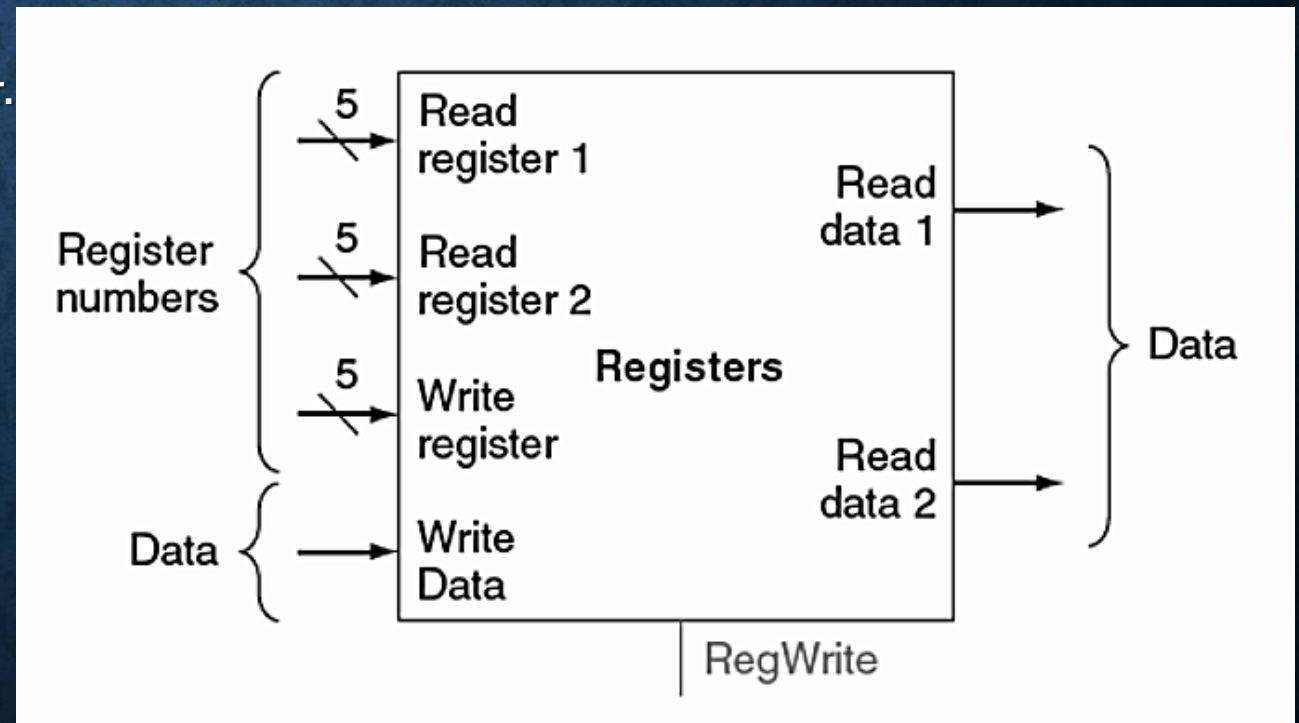
shamt – shift amount.

rt – second register source operand.

funct – additional opcodes.

DATAPATH

- To support R-format instructions, we'll need to add a state element called a *register file*. A register file is a collection readable/writeable registers.
- Read register 1 – first source register. 5 bits wide.
- Read register 2 – second source register. 5 bits wide.
- Write register – destination register. 5 bits wide.
- Write data – data to be written to a register. 32 bits wide.

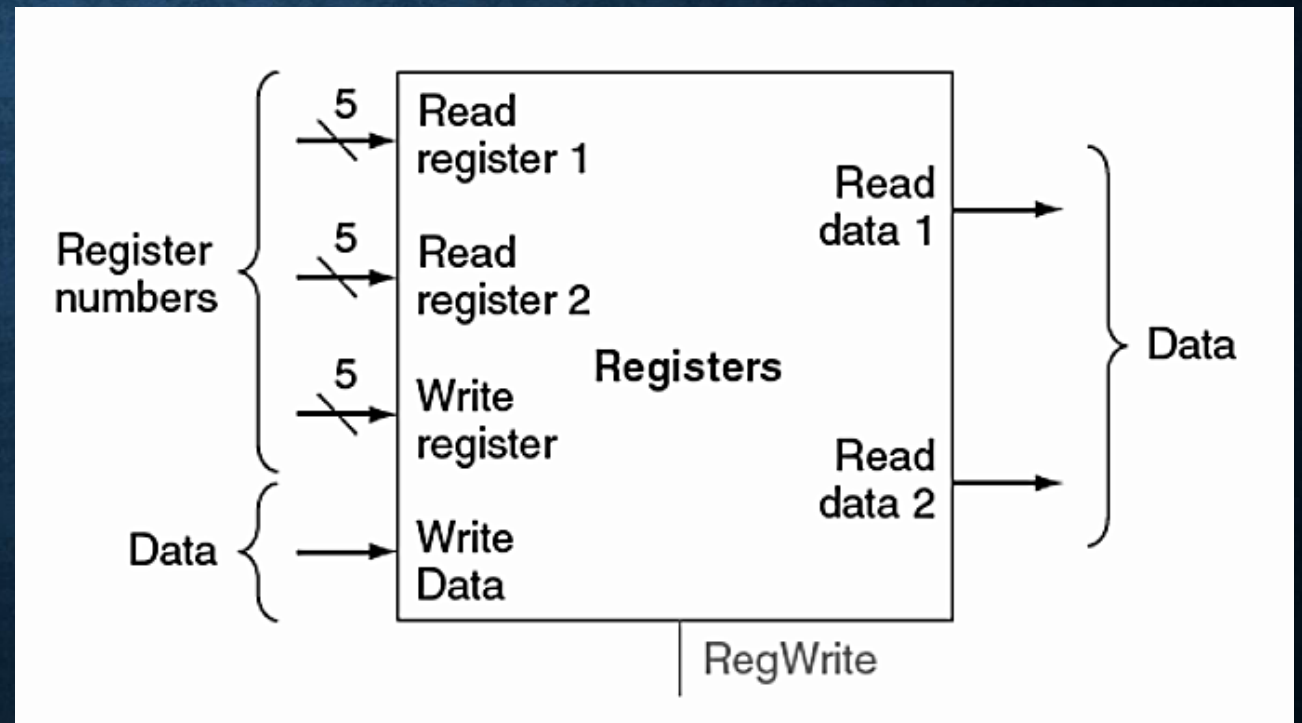


DATAPATH

- At the bottom, we have the `RegWrite` input. A writing operation only occurs when this bit is set.

The two output ports are:

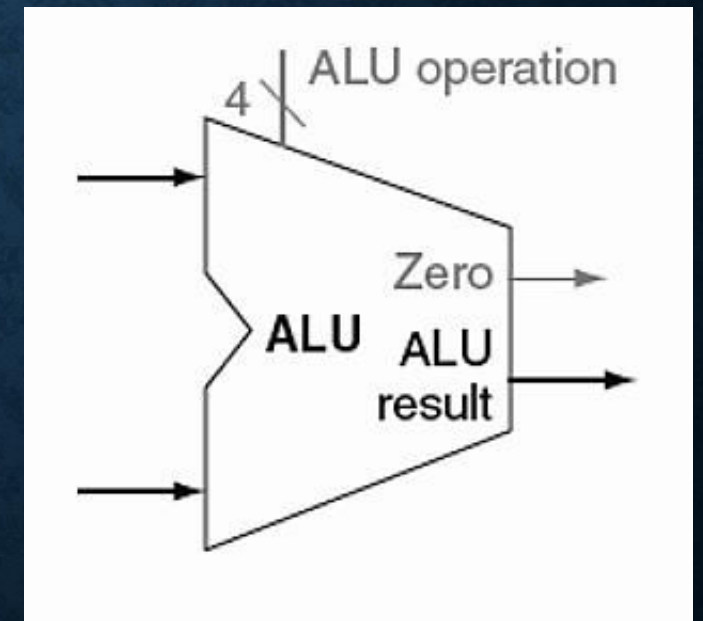
- Read data 1 – contents of source register 1.
- Read data 2 – contents of source register 2.



DATAPATH

- To actually perform R-format instructions, like `add` for example, we need to include the ALU element.
- The ALU performs the operation indicated by the instruction. It takes two inputs, the operands to perform the operation on, as well as a 4-bit wide operation selector value.

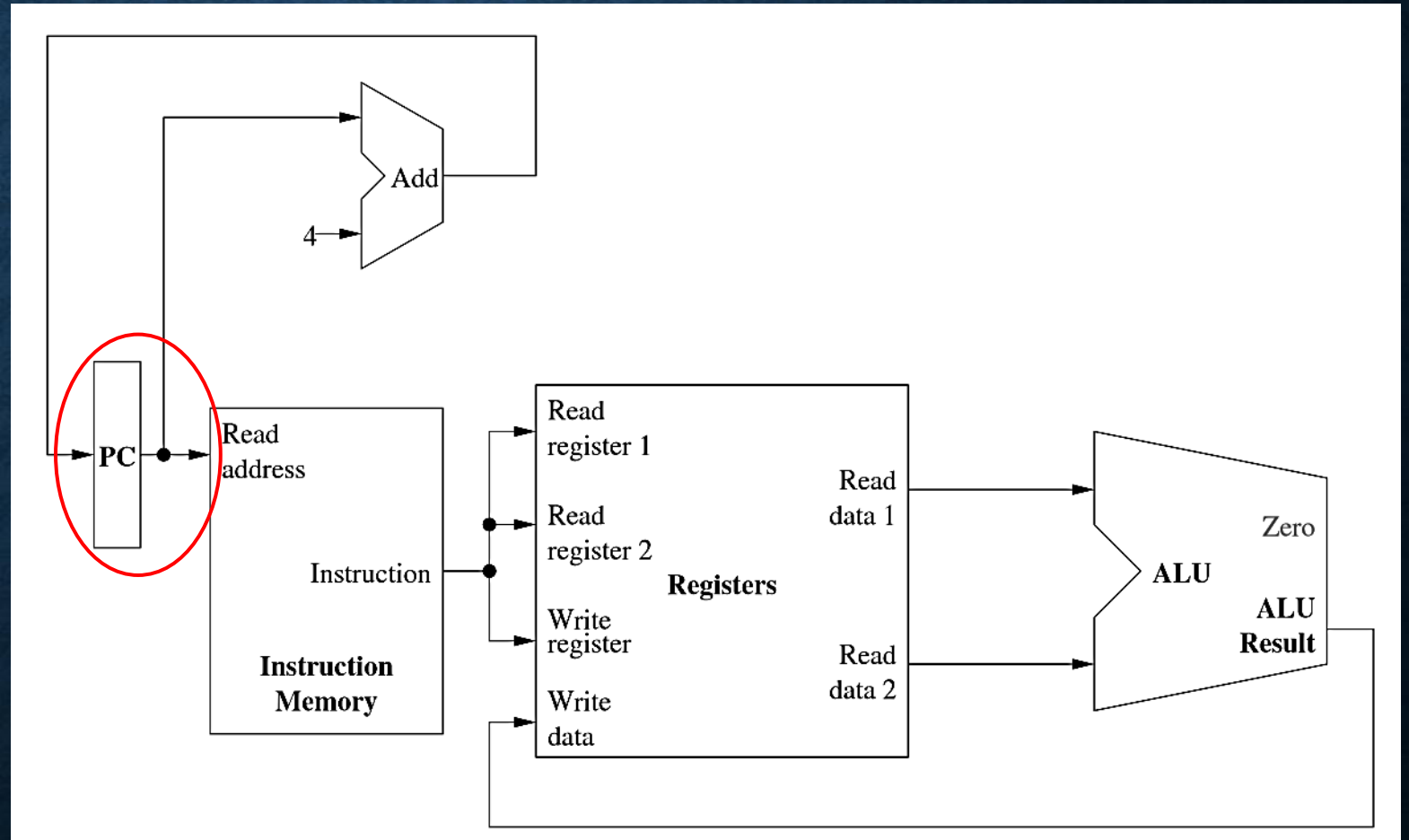
The result of the operation is the output value.
We have an additional output specifically for branching – we will cover this in a minute.



DATAPATH

Here is our datapath
for R-format instructions.

1. Grab instruction address
from PC.

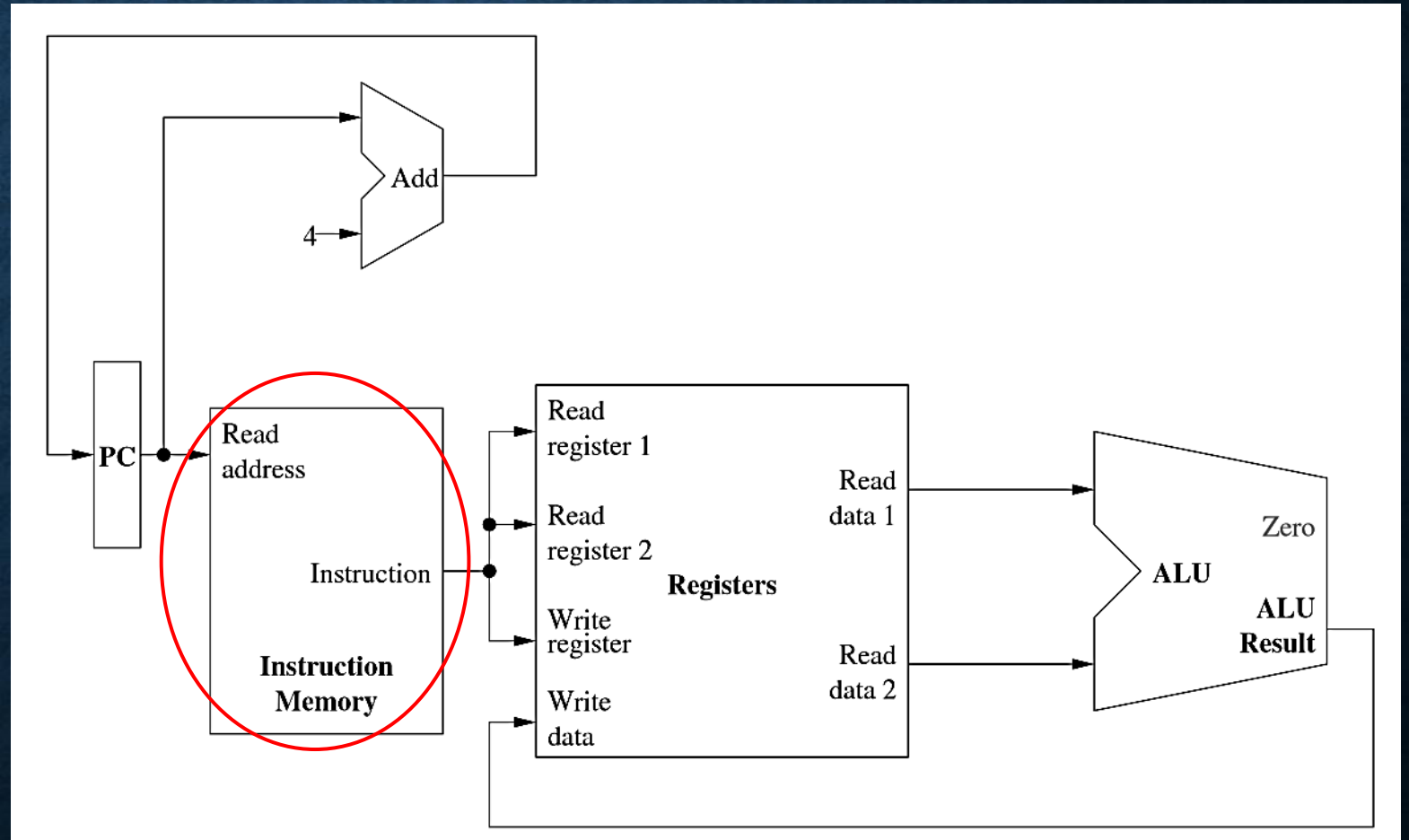


DATAPATH

Here is our datapath
for R-format instructions.

2. Fetch instruction from
instruction memory.

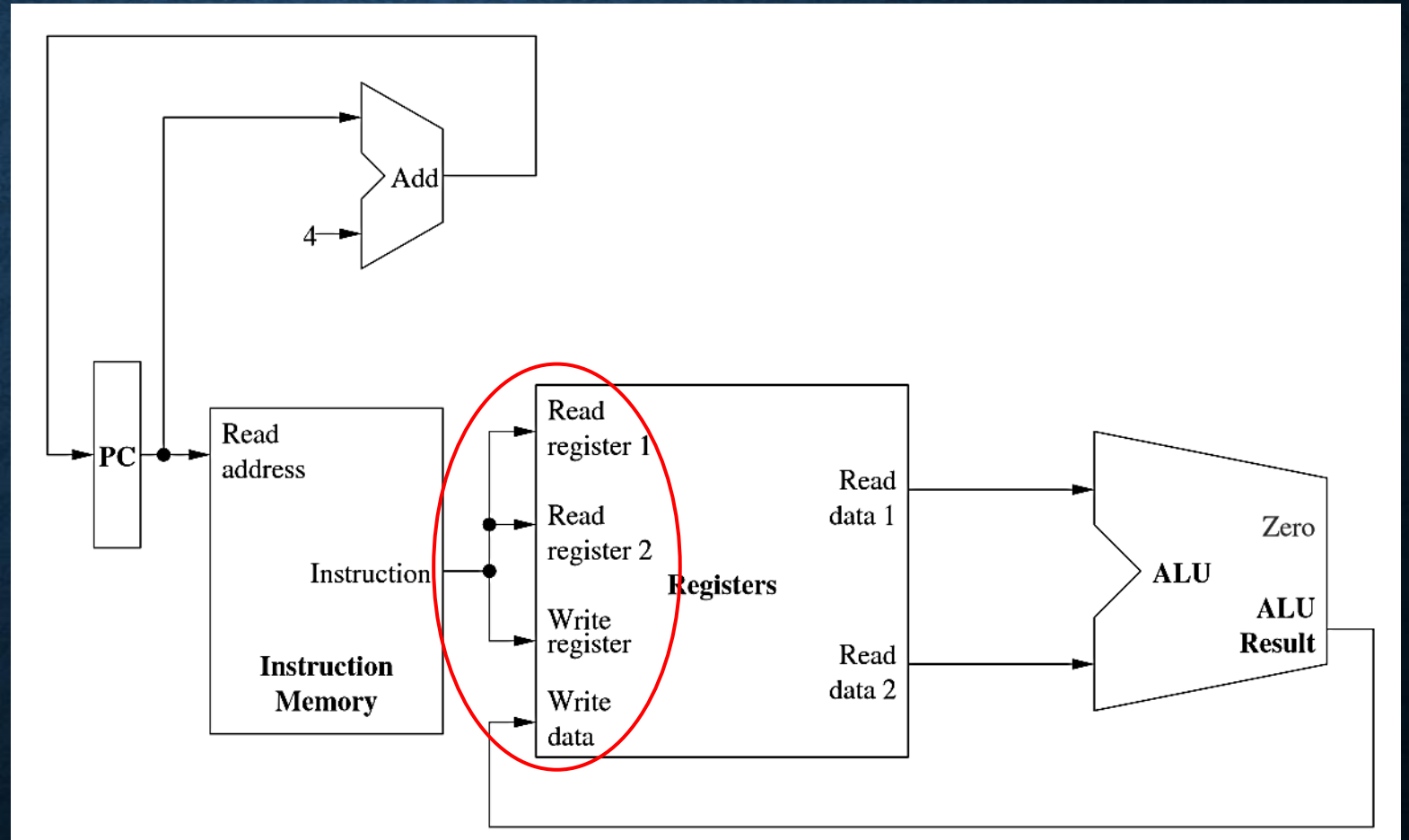
3. Decode instruction.



DATAPATH

Here is our datapath
for R-format instructions.

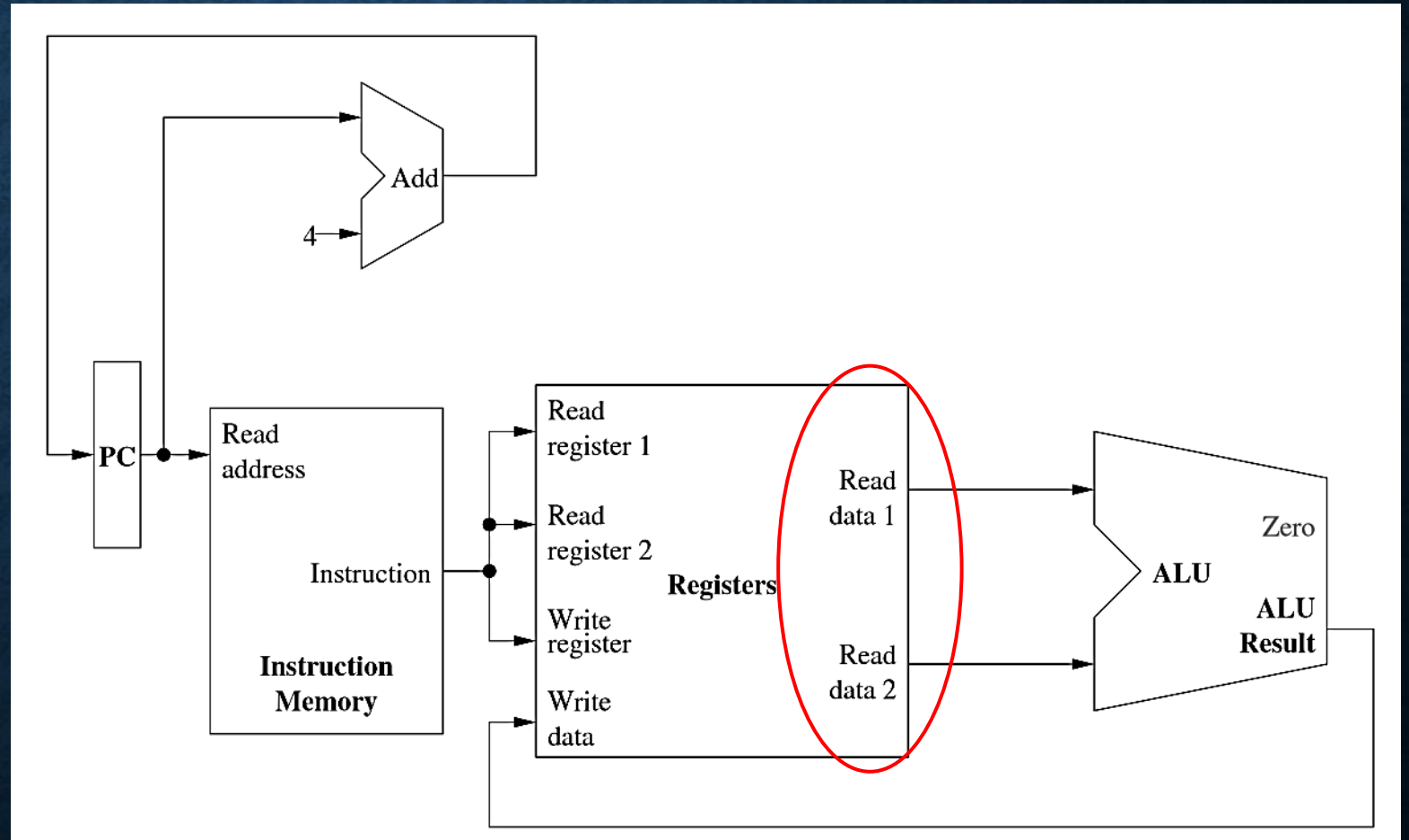
4. Pass `rs`, `rt`, and `rd` into
read register and write
register arguments.



DATAPATH

Here is our datapath
for R-format instructions.

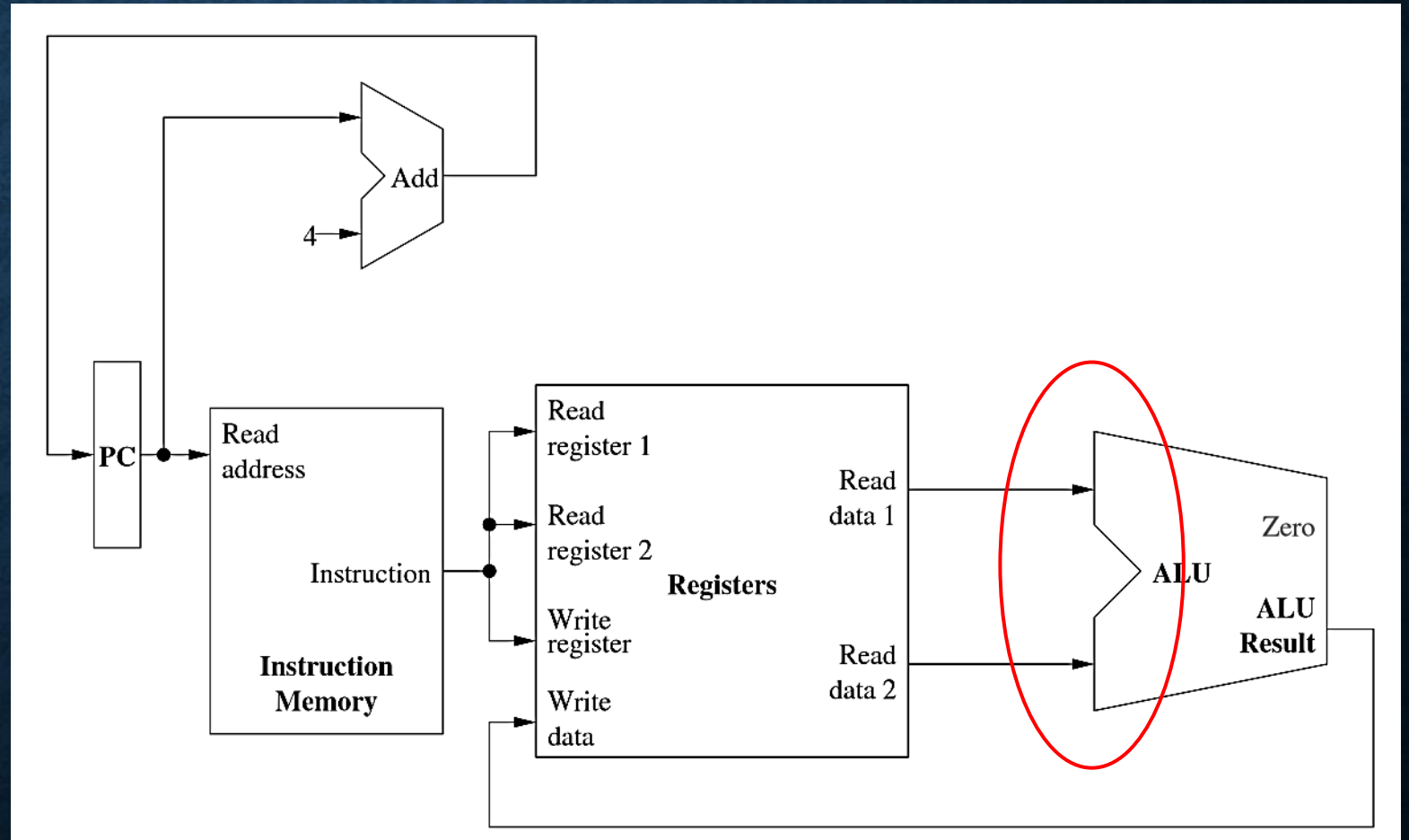
5. Retrieve contents of read
register 1 and read
register 2 (r_s and r_t).



DATAPATH

Here is our datapath
for R-format instructions.

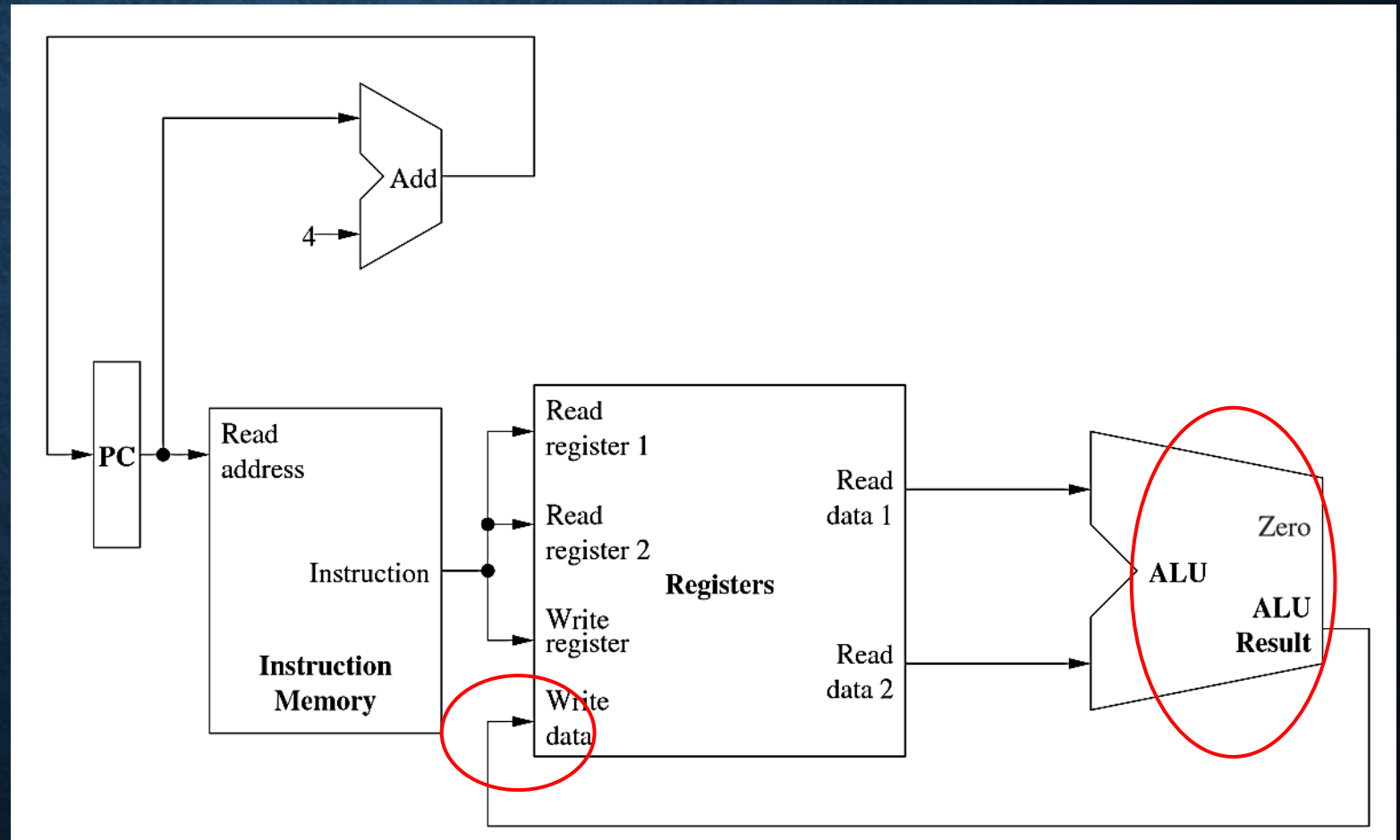
6. Pass contents of rs and
 rt into the ALU as
operands of the operation
to be performed.



DATAPATH

Here is our datapath
for R-format instructions.

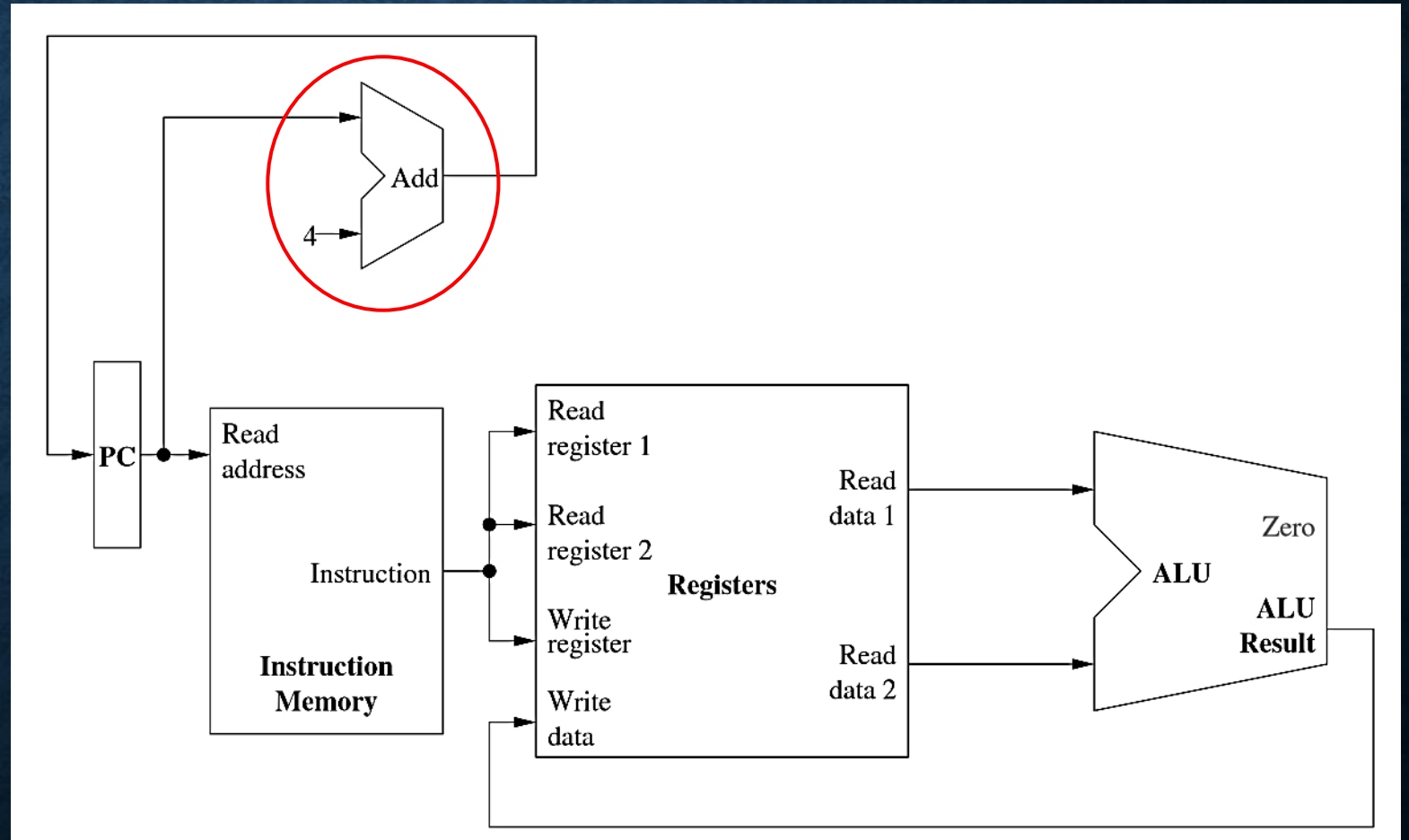
7. Retrieve result of operation
performed by ALU and
pass back as the write
data argument of the
register file (with the
RegWrite bit set).



DATAPATH

Here is our datapath
for R-format instructions.

8. Add 4 bytes to the PC
value to obtain the
word-aligned address
of the next instruction.



I-FORMAT INSTRUCTIONS

Now that we have a complete datapath for R-format instructions, let's add in support for I-format instructions. In our limited MIPS instruction set, these are `lw`, `sw`, and `beq`.

- The *op* field is used to identify the type of instruction.
- The *rs* field is the source register.
- The *rt* field is either the source or destination register, depending on the instruction.
- The *immed* field is zero-extended if it is a logical operation. Otherwise, it is sign-extended.

Name	Fields					
Field Size	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits
I format	op	rs	rt	immed		

DATA TRANSFER INSTRUCTIONS

- Let's start with accommodating the data transfer instructions – we'll get to beq in a bit. For lw and sw, we have the following format:

```
lw $rt, immmed($rs)
```

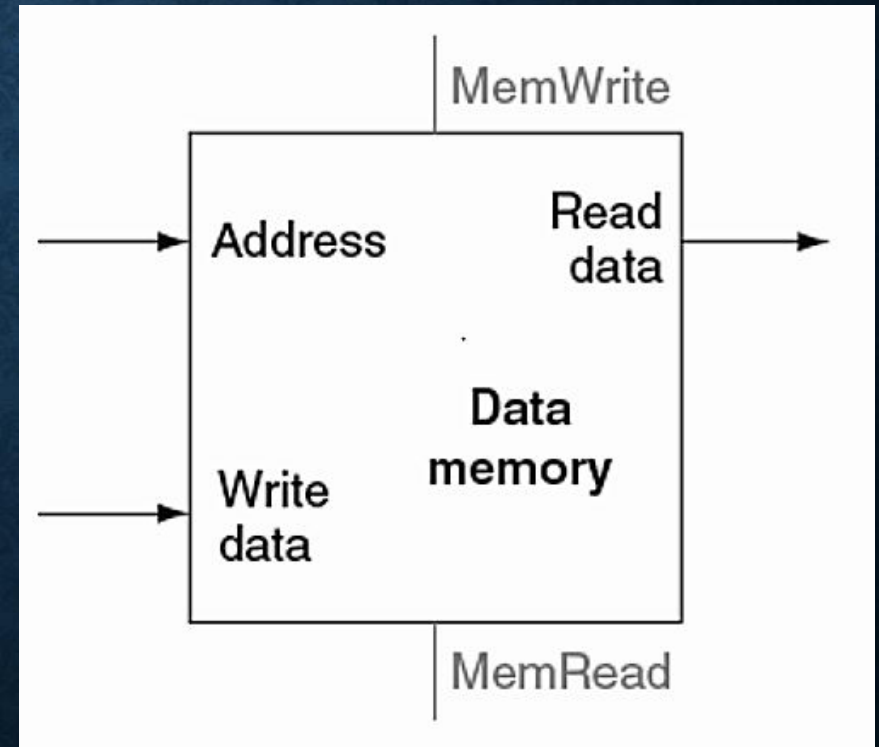
```
sw $rt, immmed($rs)
```

- The memory address is computed by *sign-extending* the 16-bit immediate to 32-bits, which is added to the contents of \$rs.
- In lw, \$rt represents the register that will be *assigned* the memory value. In sw, \$rt represents the register whose value will be *stored* in memory.

Bottom line: we need two more datapath elements to access memory and perform sign-extending.

DATAPATH

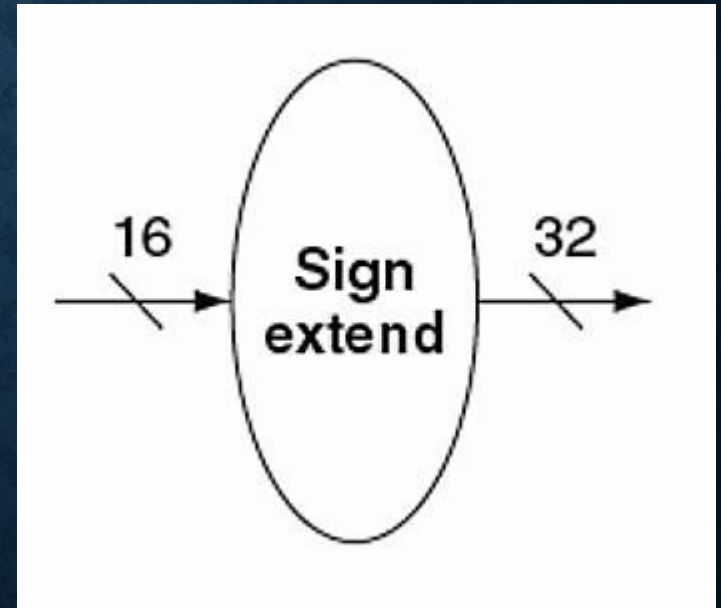
- The *data memory* element implements the functionality for reading and writing data to/from memory.
- There are two inputs. One for the address of the memory location to access, the other for the data to be written to memory if applicable.
- The output is the data read from the memory location accessed, if applicable.
- Reads and writes are signaled by MemRead and MemWrite, respectively, which must be asserted for the corresponding action to take place.



DATAPATH

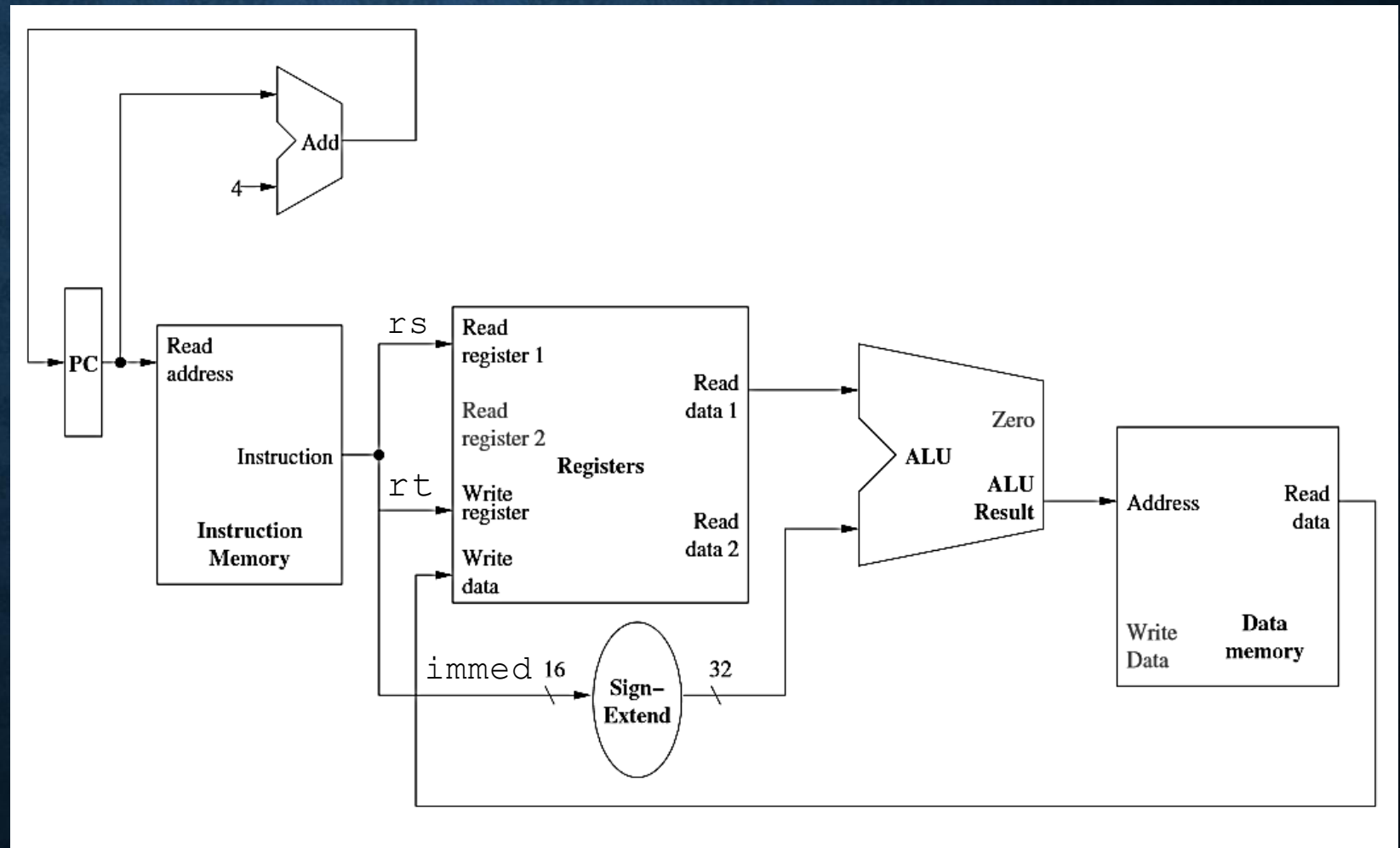
- To perform sign-extending, we can add a sign extension element.
- The sign extension element takes as input a 16-bit wide value to be extended to 32-bits.

To sign extend, we simply replicate the most-significant bit of the original field until we have reached the desired field width.



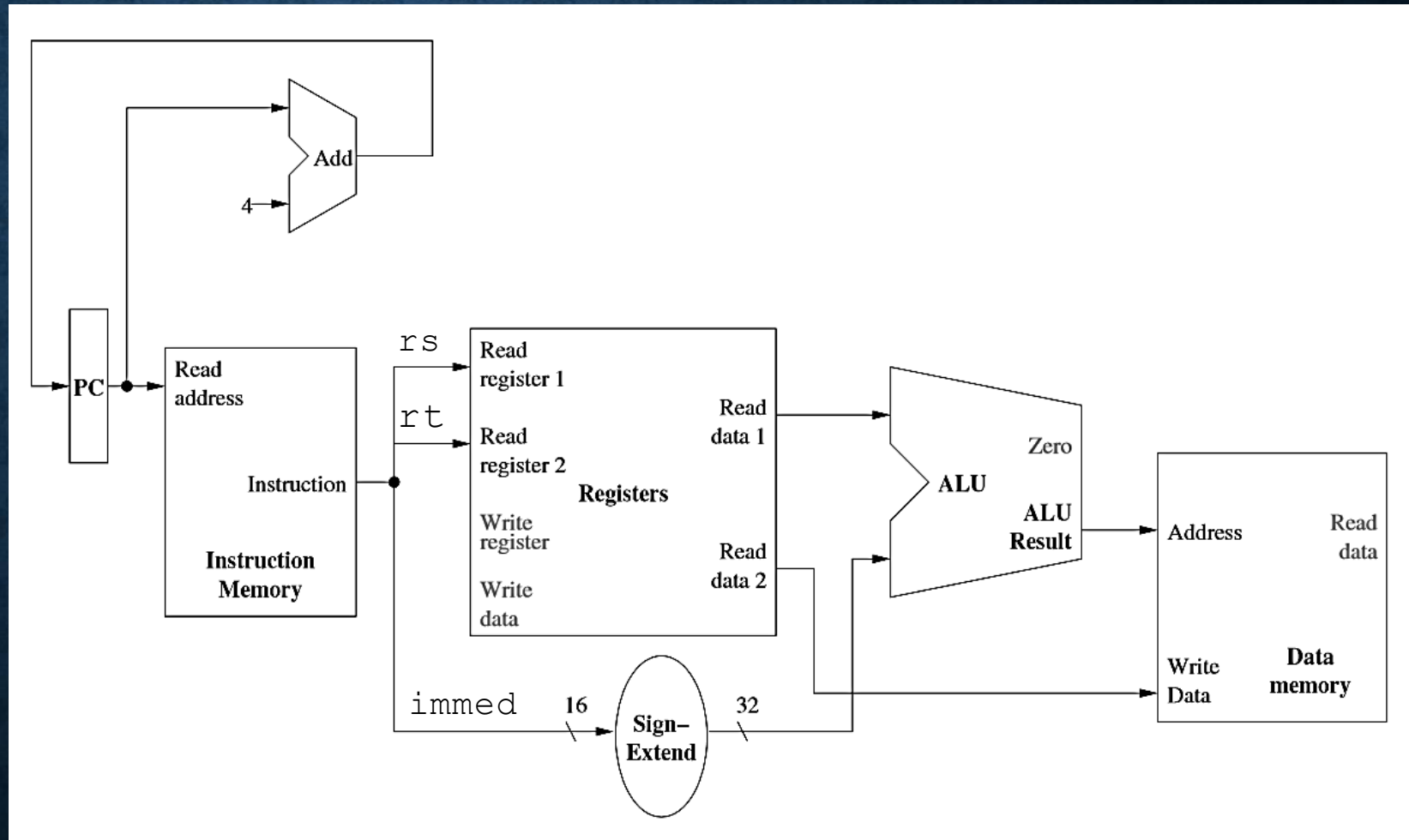
DATAPATH FOR LOAD WORD

- Here, we have modified the datapath to work only for the `lw` instruction.
`lw $rt, imm($rs)`
- The registers have been added to the datapath for added clarity.



DATAPATH FOR STORE WORD

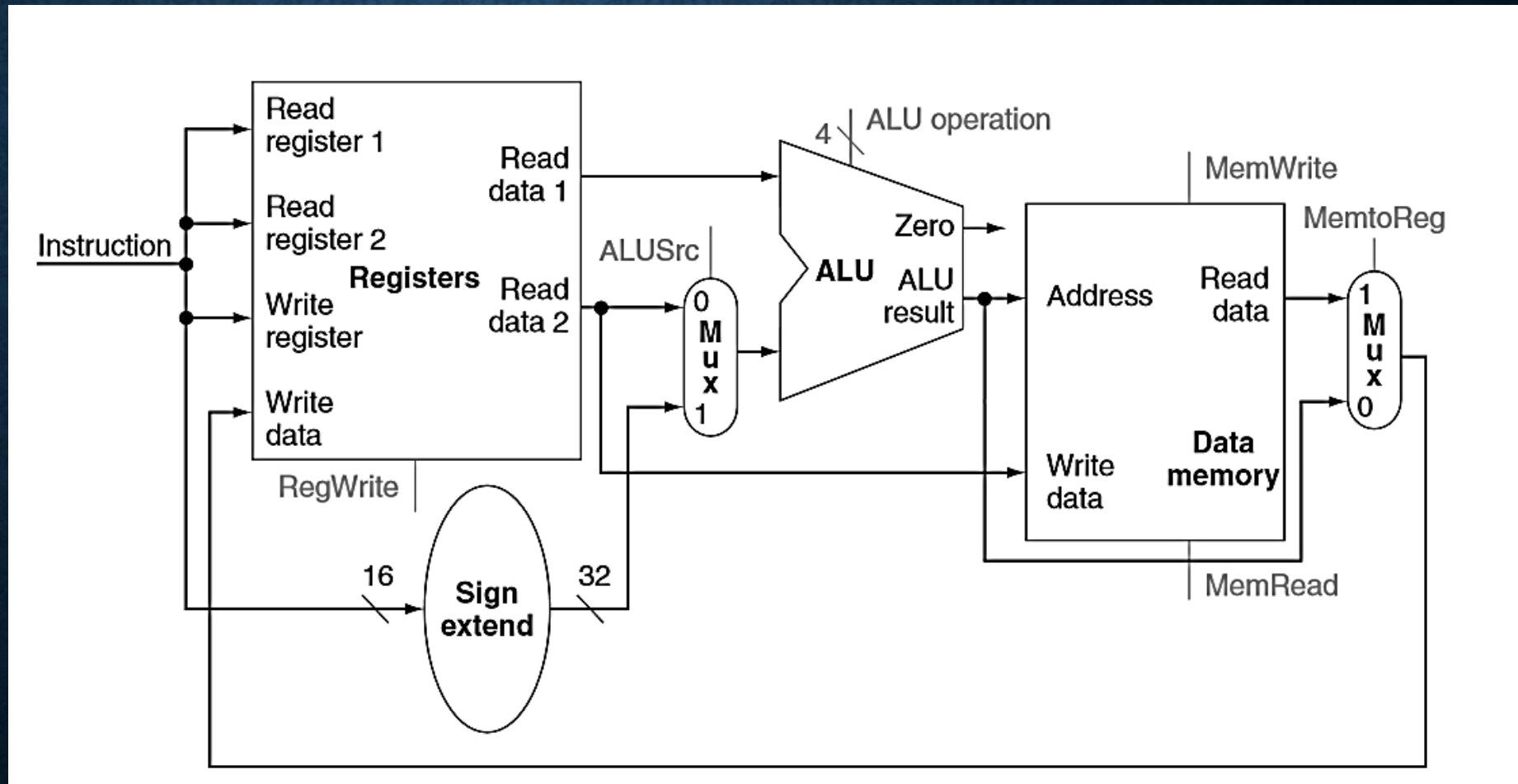
- Here, we have modified the datapath to work only for the `sw` instruction.
`sw $rt, imm($rs)`
- The registers have been added to the datapath for added clarity.



DATAPATH FOR R-FORMAT AND MEMORY ACCESS

Note: PC, adder, and instruction memory are omitted.

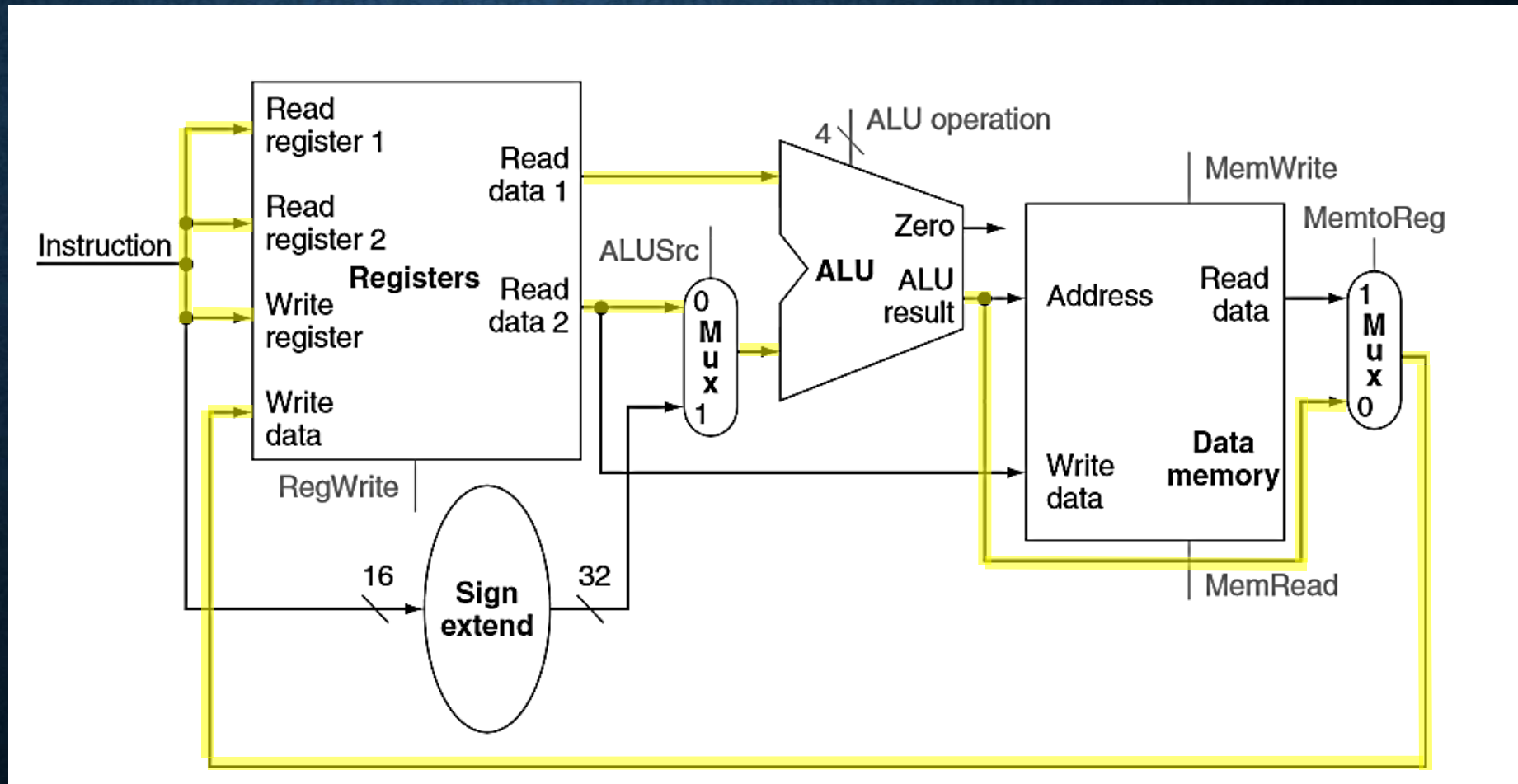
```
add $rd, $rs, $rt  
lw $rt, immmed($rs)  
sw $rt, immmed($rs)
```



DATAPATH FOR R-FORMAT AND MEMORY ACCESS

Note: PC, adder, and instruction memory are omitted.

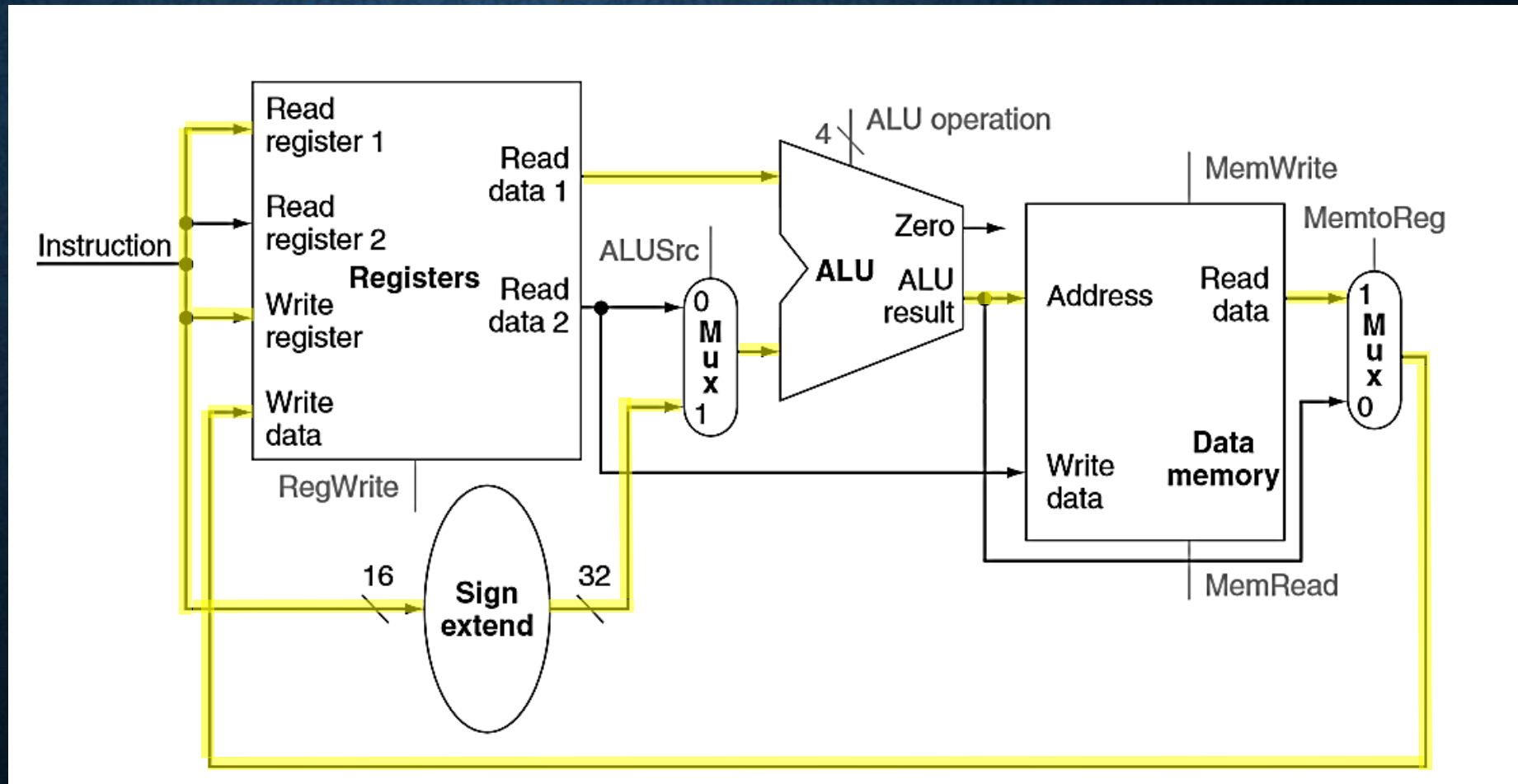
```
add $rd, $rs, $rt  
lw $rt, immmed($rs)  
sw $rt, immmed($rs)
```



DATAPATH FOR R-FORMAT AND MEMORY ACCESS

Note: PC, adder, and instruction memory are omitted.

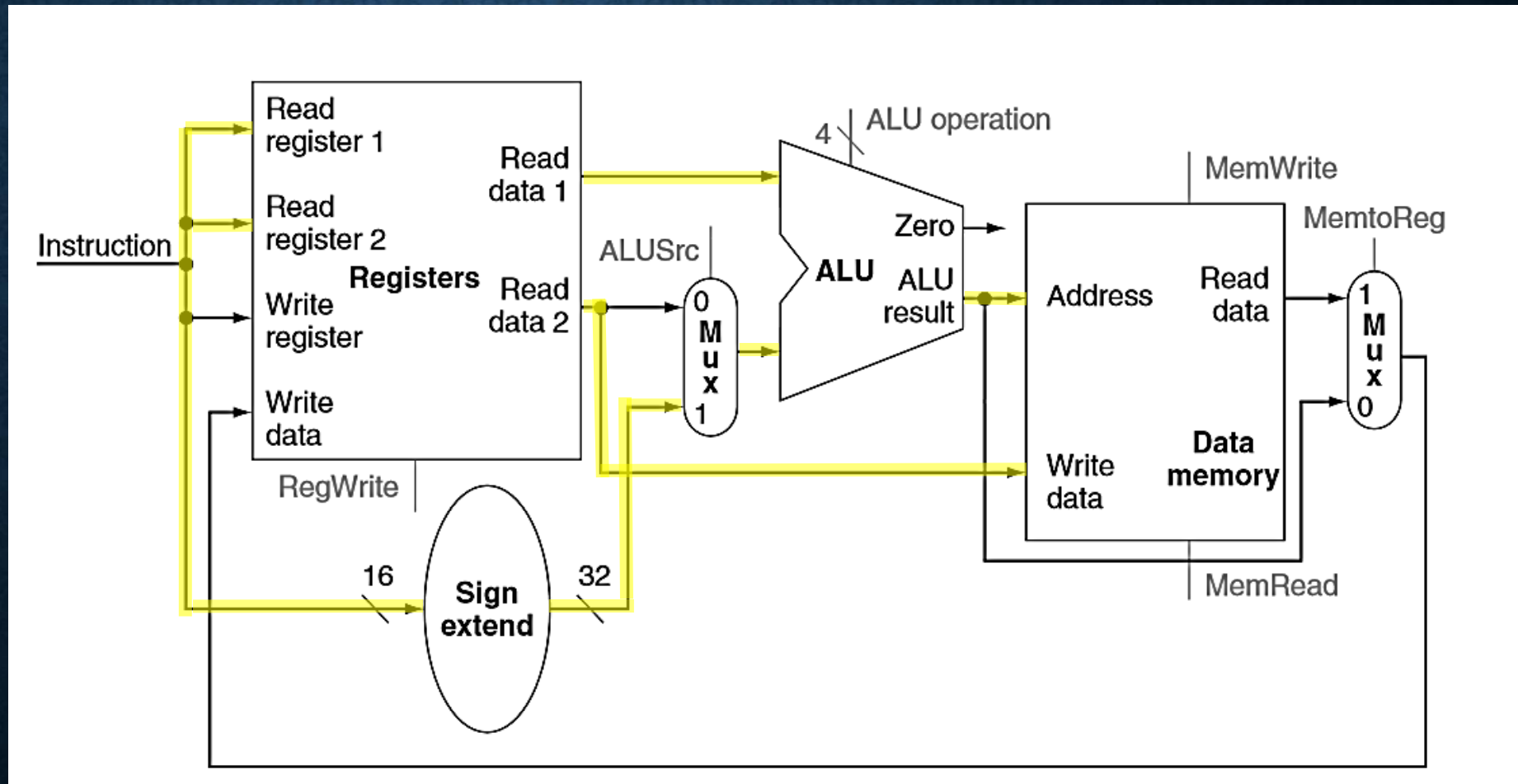
```
add $rd, $rs, $rt  
lw $rt, immmed($rs)  
sw $rt, immmed($rs)
```



DATAPATH FOR R-FORMAT AND MEMORY ACCESS

Note: PC, adder, and instruction memory are omitted.

```
add $rd, $rs, $rt  
lw $rt, immmed($rs)  
sw $rt, immmed($rs)
```



BRANCHING INSTRUCTIONS

- Now we'll turn our attention to a branching instruction. In our limited MIPS instruction set, we have the beq instruction which has the following form:

beq \$t1, \$t2, target

- This instruction compares the contents of \$t1 and \$t2 for equality and uses the 16-bit immediate field to compute the target address of the branch relative to the current address.

Name	Fields					
Field Size	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits
I format	op	rs	rt	immed		

BRANCHING INSTRUCTIONS

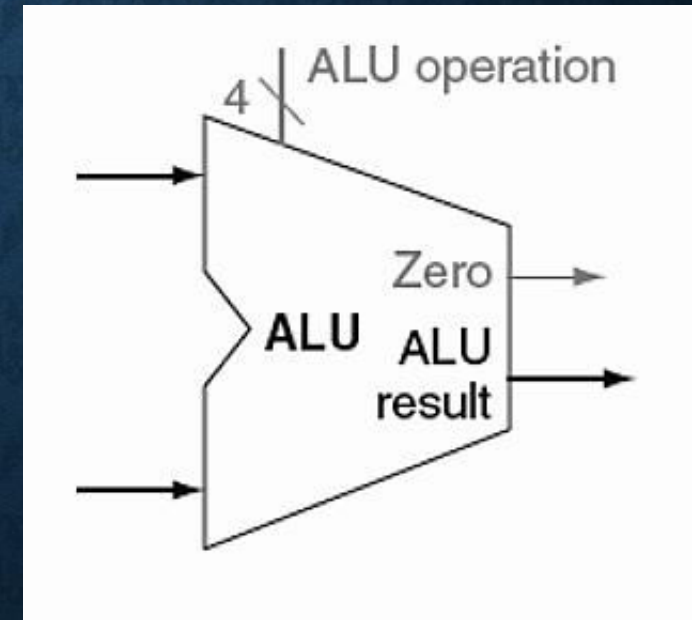
- Note that our immediate field is only 16-bits so we can't specify a full 32-bit target address. So we have to do a few things before jumping.
- The immediate field is left-shifted by two because the immediate represents the number of *words* offset from PC+4, not the number of bytes (and we want to get it in number of bytes!).
- We sign-extend the immediate field to 32-bits and add it to PC+4.

`beq $t1, $t2, target`

Name	Fields					
Field Size	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits
I format	op	rs	rt	immed		

BRANCHING INSTRUCTIONS

- Besides computing the target address, a branching instruction also has to compare the contents of the source registers.
- As stated before, the ALU has an output line denoted as Zero. This output is specifically hardwired to be set when the result of an operation is zero.
- To test whether a and b are equal, we can set the ALU to perform a subtraction operation. The Zero output line is only set if $a - b$ is 0, indicating a and b are equal.

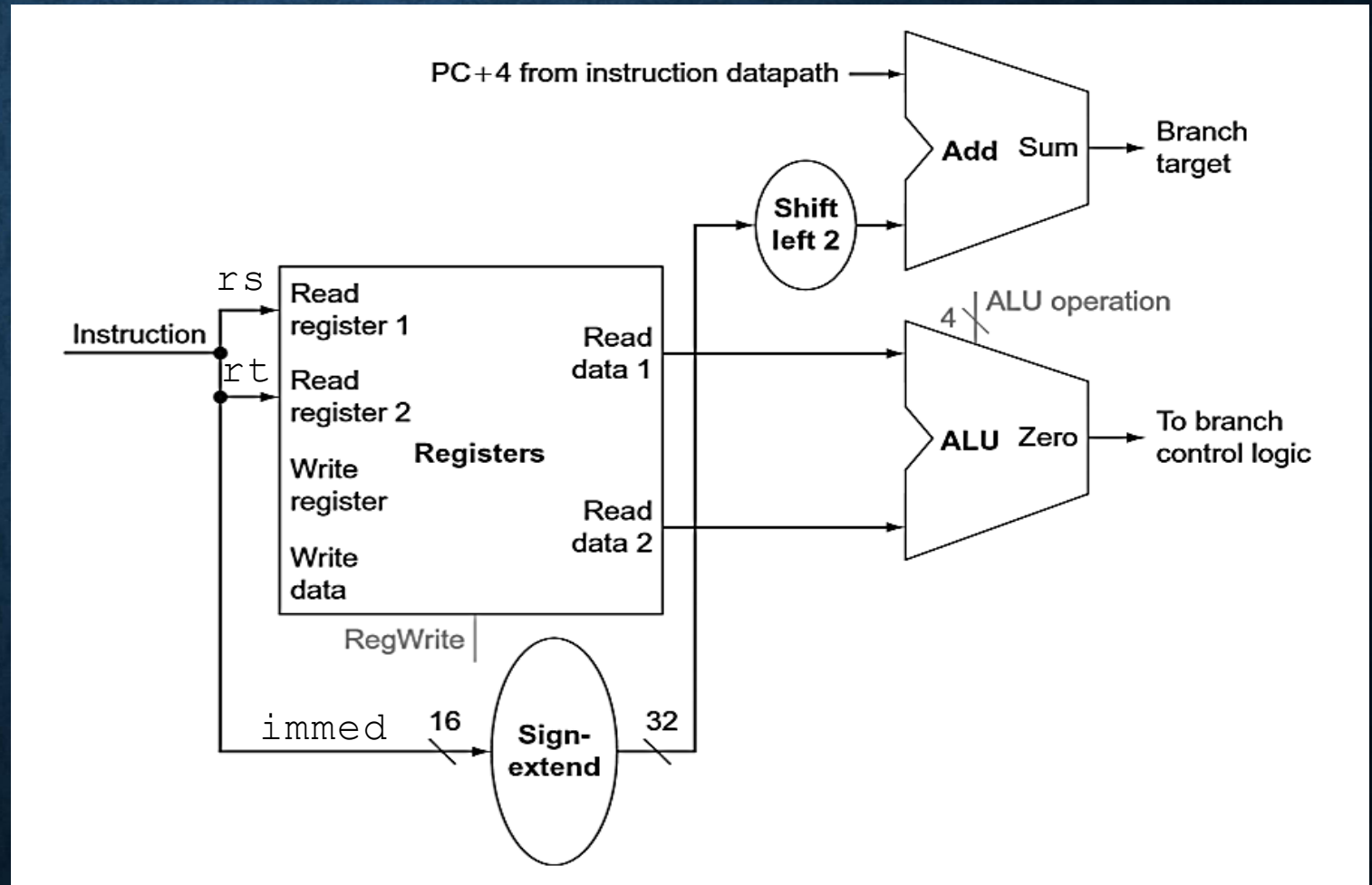


DATAPATH FOR BEQ

Here, we have modified the datapath to work only for the beq instruction.

`beq $rs, $rt, imm`

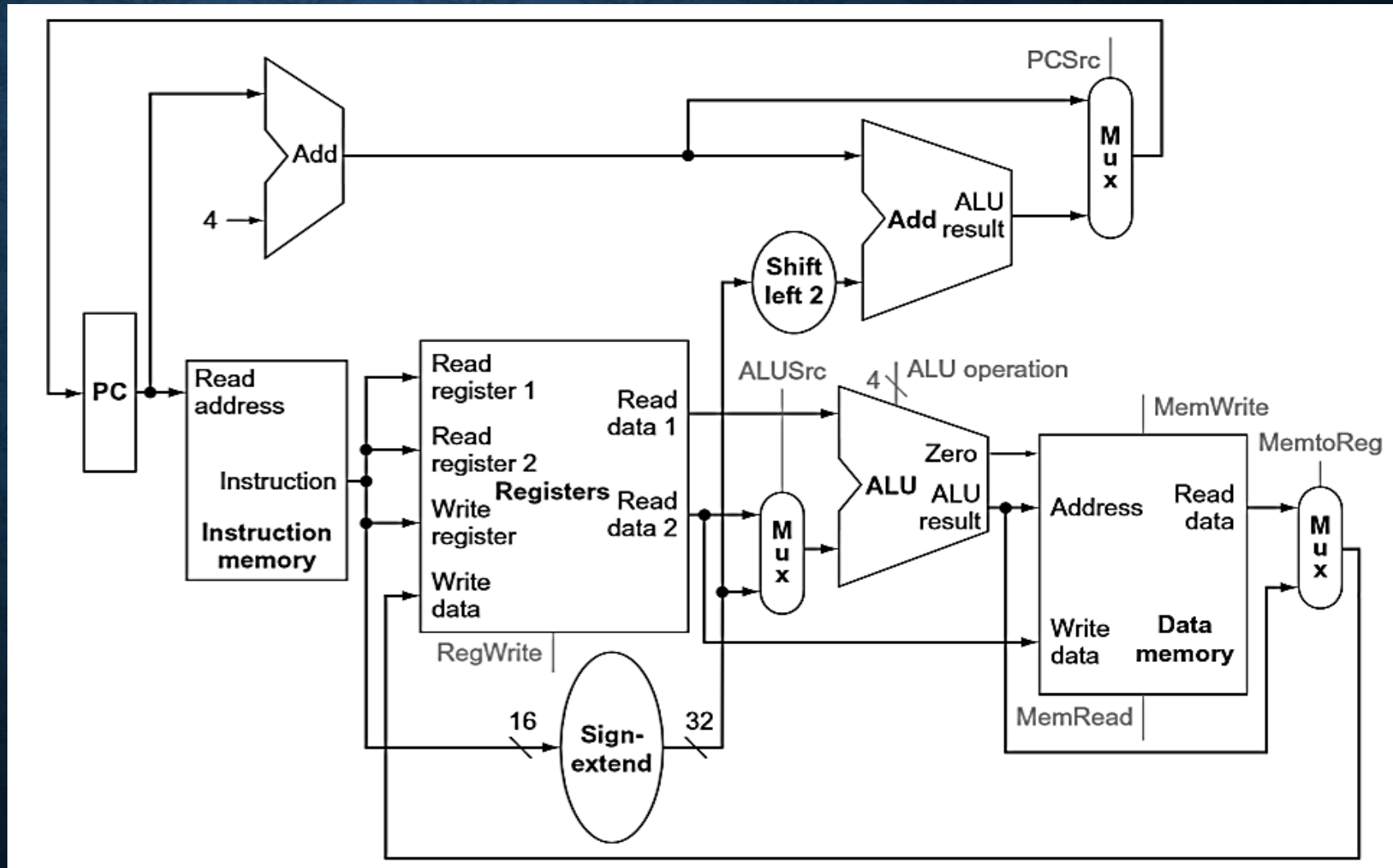
The registers have been added to the datapath for added clarity.



DATAPATH FOR R AND I FORMAT

Now we have a datapath which supports all of our R and I format instructions.

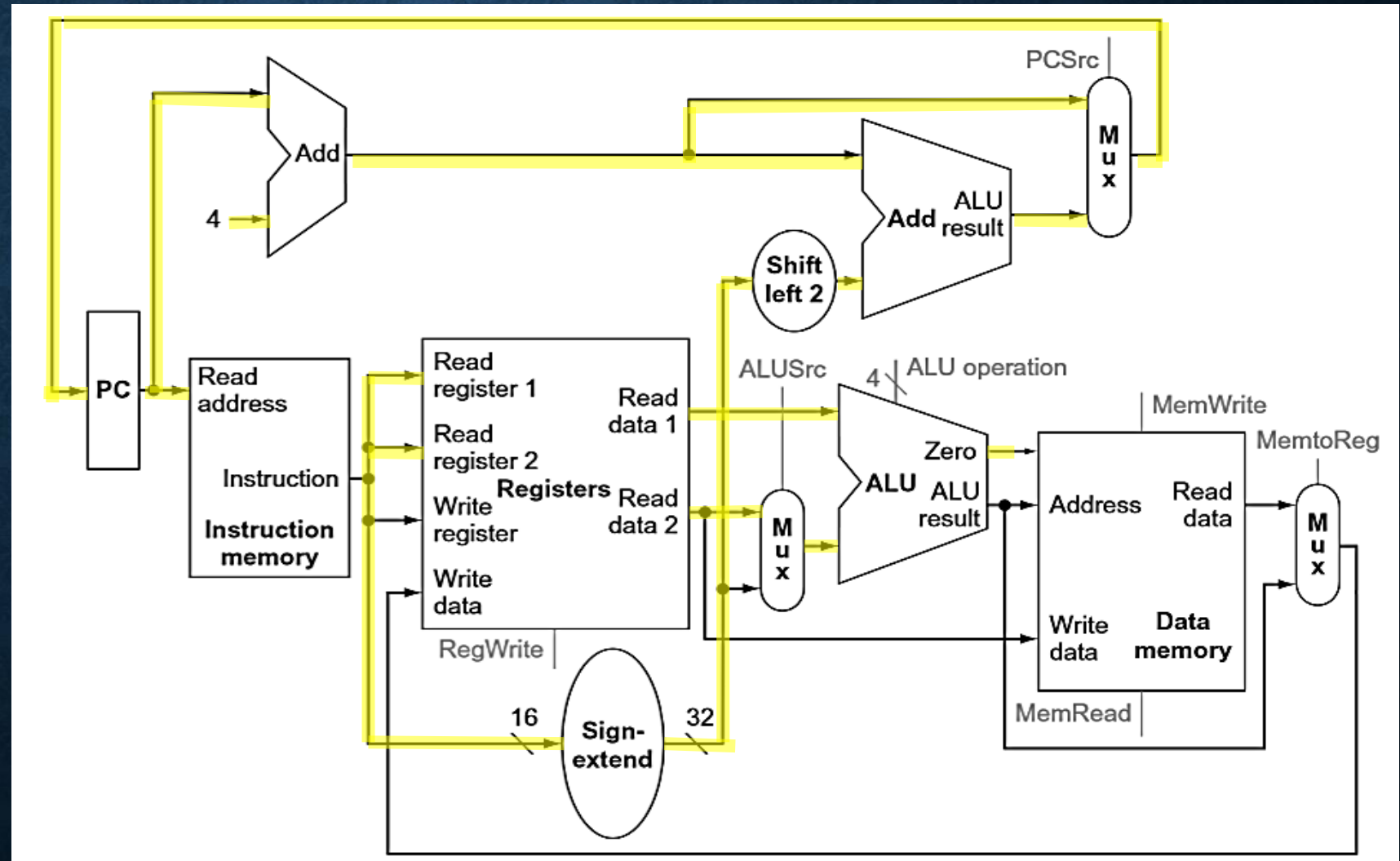
```
add $rd, $rs, $rt  
lw $rt, immed($rs)  
sw $rt, immed($rs)  
beq $rs, $rt, immed
```



DATAPATH FOR R AND I FORMAT

Now we have a datapath which supports all of our R and I format instructions.

```
add $rd, $rs, $rt  
lw $rt, immed($rs)  
sw $rt, immed($rs)  
beq $rs, $rt, immed
```



J-FORMAT INSTRUCTIONS

- The last instruction we have to implement in our simple MIPS subset is the jump instruction. An example jump instruction is `j L1`. This instruction indicates that the next instruction to be executed is at the address of label L1.
- We have 6 bits for the opcode.
- We have 26 bits for the target address.

Name	Fields					
Field Size	6 bits	5 bits	5 bits	5 bits	5 bits	6 bits
J format	op	targaddr				

J-FORMAT INSTRUCTIONS

- Note, as in the branching example, we do not have enough space in the instruction to specify a full target address. Branching solves this problem by specifying an offset in words.

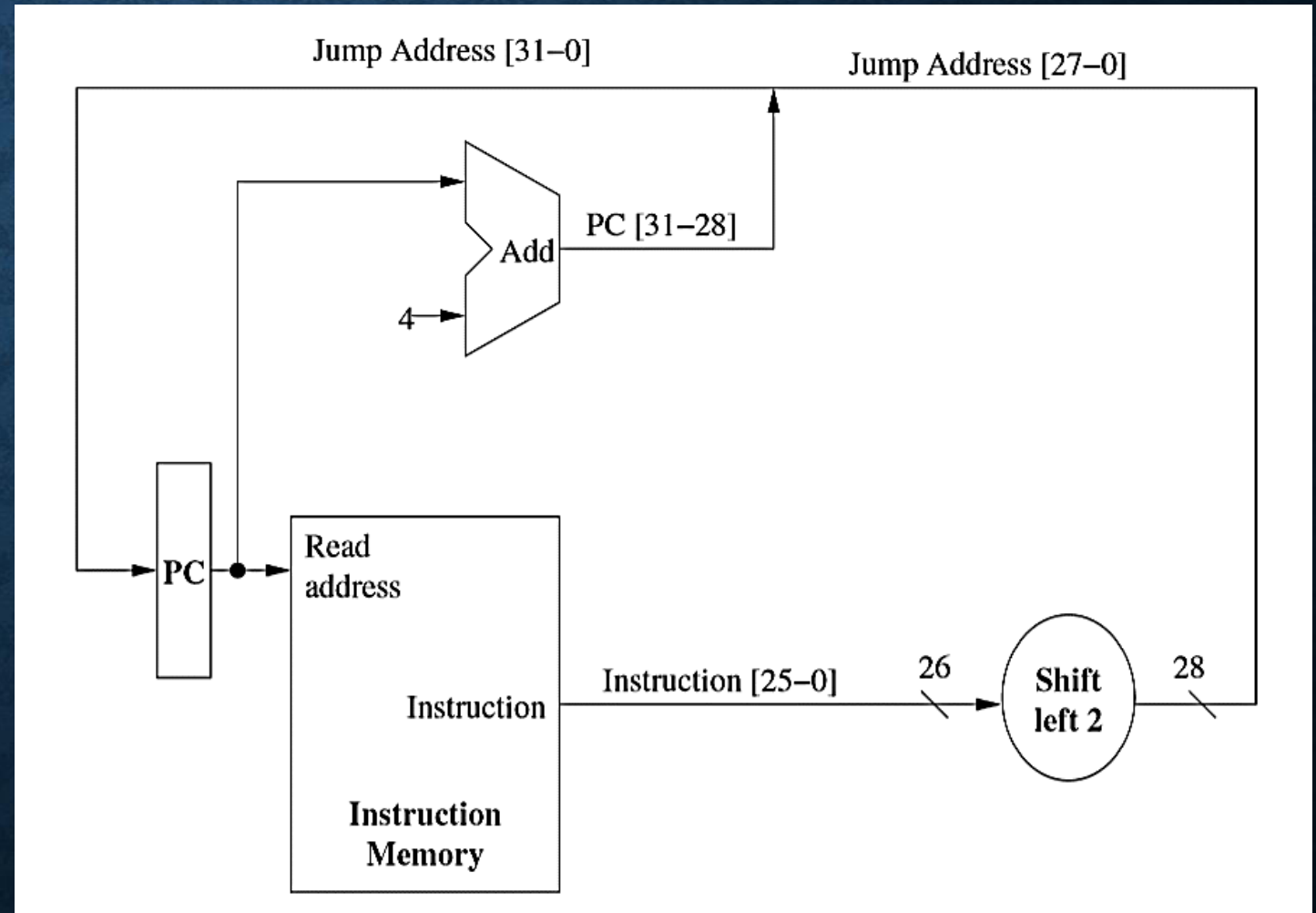
Jump instructions solve this problem by specifying *a portion of an absolute address, not an offset*.

- We take the 26-bit target address field of the instruction, left-shift by two (because we are word-aligned), and concatenate the result with the upper 4 bits of PC+4.

DATAPATH FOR J-FORMAT

Here, we have modified the datapath to work only for the `j` instruction.

`j targaddr`



SINGLE-CYCLE CONTROL

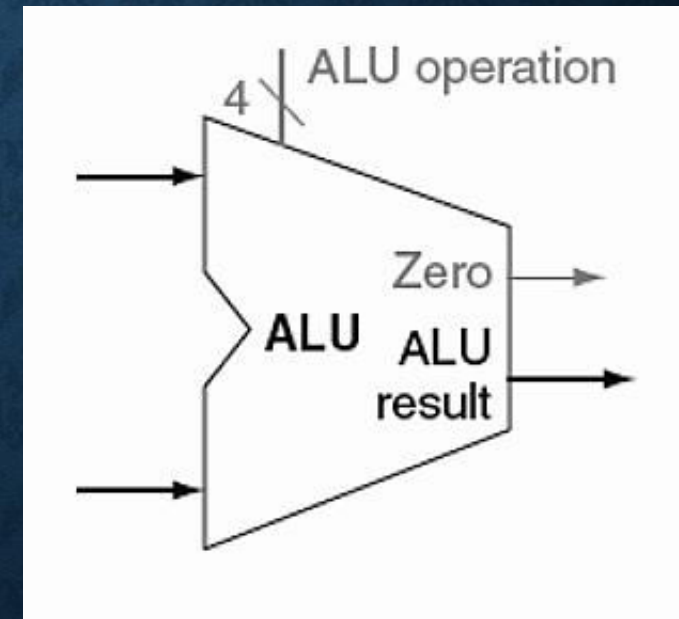
- Now we have a complete datapath for our simple MIPS subset – we will show the whole diagram in just a couple of minutes. Before that, we will add the control.
- The *control unit* is responsible for taking the instruction and generating the appropriate signals for the datapath elements.
- Signals that need to be generated include
 - Operation to be performed by ALU.
 - Whether register file needs to be written.
 - Signals for multiple intermediate multiplexors.
 - Whether data memory needs to be written.

For the most part, we can generate these signals using only the *opcode* and *funct* fields of an instruction.

ALU CONTROL LINES

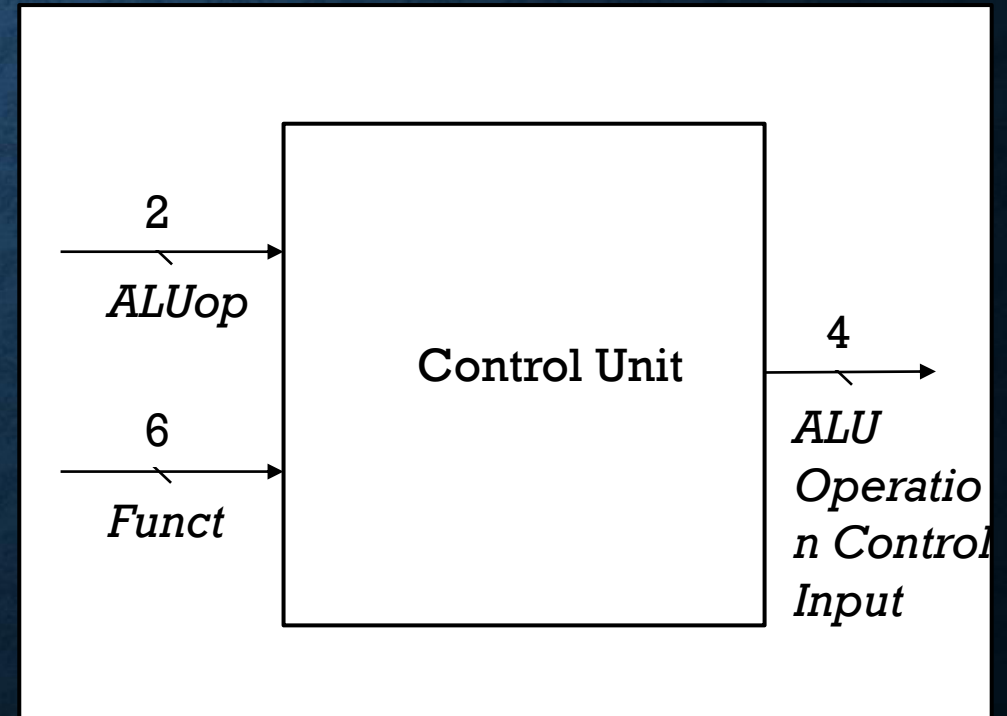
- Note here that the ALU has a 4-bit control line called ALU operation. The first two bits indicate whether a and b need to be inverted, respectively. The last two bits indicate the operation.

ALU Control Lines	Function
0000	AND
0001	OR
0010	Add
0110	Subtract
0111	Set on less than
1100	NOR



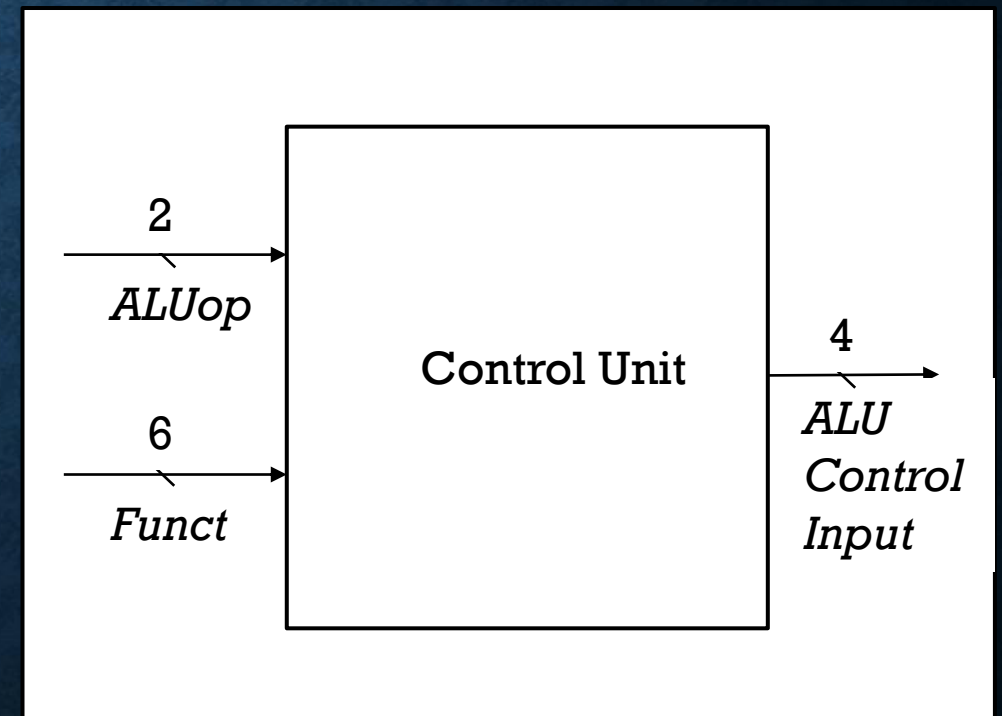
ALU CONTROL LINES

- How do we set these control lines? Consider the control unit below.
- The 2-bit *ALUop* input indicates whether an operation should be add (00) for loads and stores, subtract (01) for beq, or determined by the funct input (10).
- The 6-bit *Funct* input corresponds to the funct field of R-format instructions. Each unique funct field corresponds to a unique set of ALU control input lines.



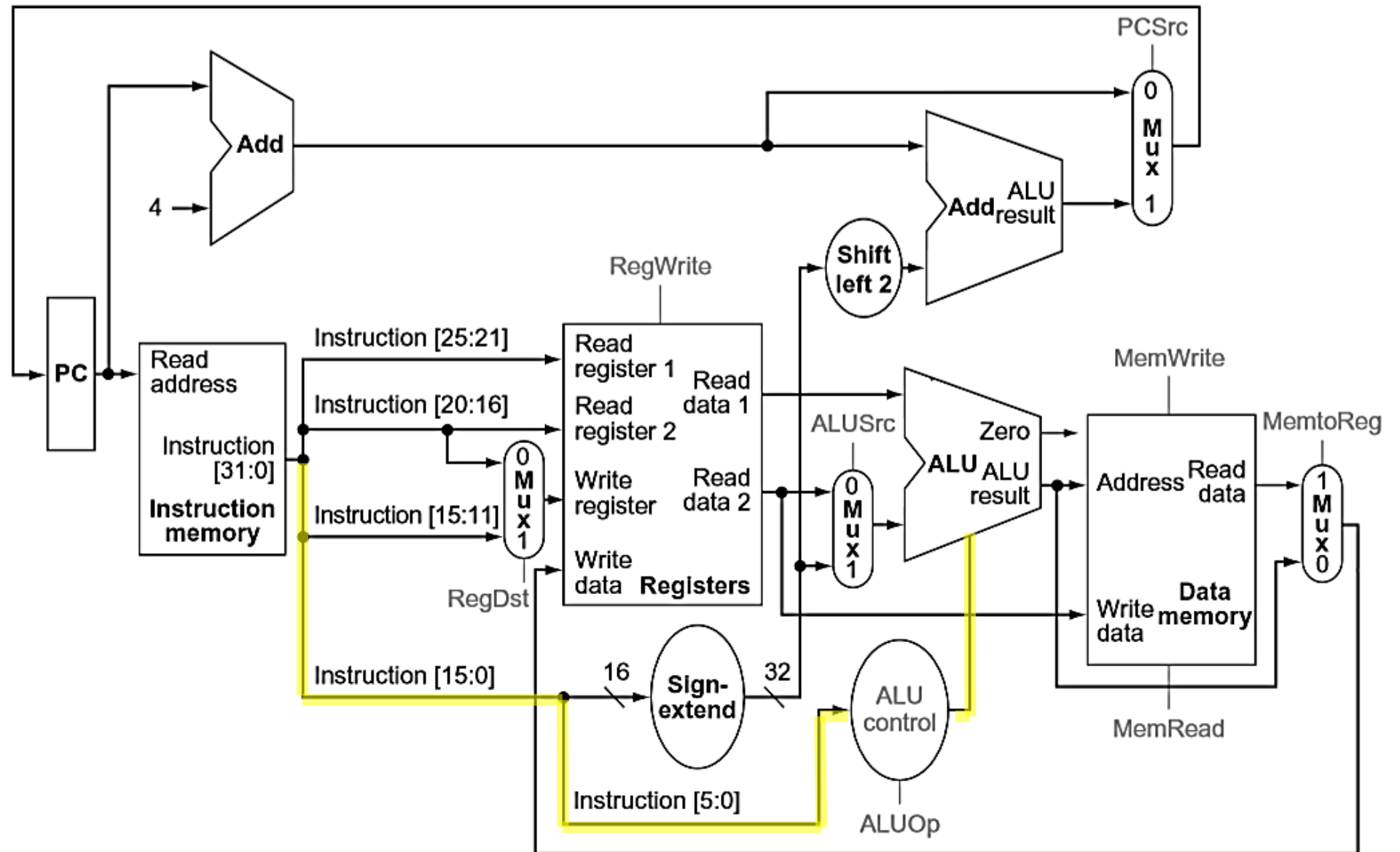
ALU CONTROL LINES

Opcod e	ALU op	Operation	Funct	ALU action	ALU Control Input
lw	00	Load word	N/A	add	0010
sw	00	Store word	N/A	add	0010
beq	01	Branch equal	N/A	subtrac t	0110
R- type	10	Add	100000	add	0010
R- type	10	Subtract	100010	subtrac t	0110
R- type	10	AND	100100	AND	0000
R- type	10	OR	100101	OR	0001
R- type	10	Set on less than	101010	slt	0111



Here, we have modified the datapath to work with every instruction except the jump instruction.

Notice the added element for determining the ALU control input from the funct field for R-types.



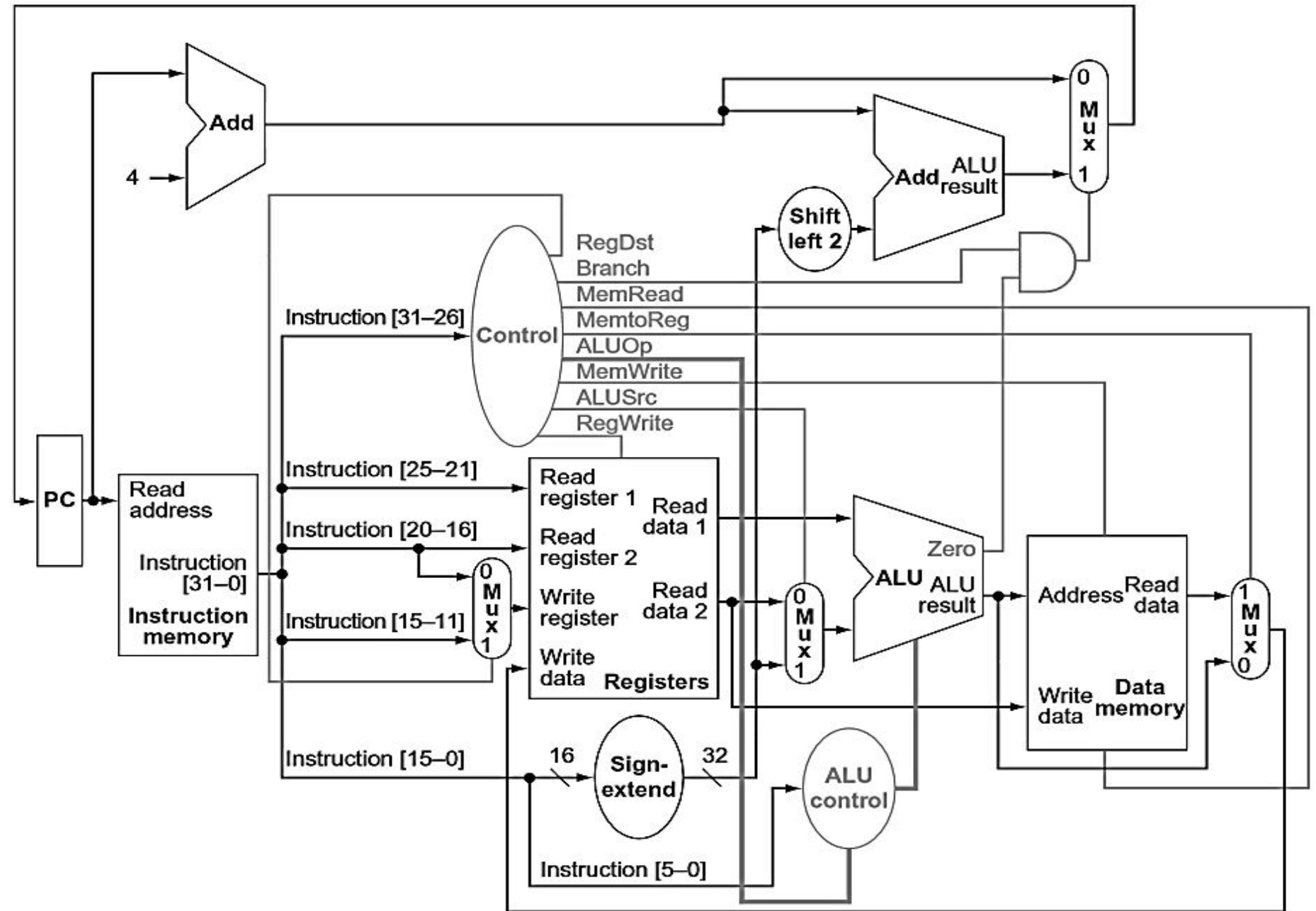
CONTROL SIGNALS

- As we can see from the previous slide, we also need to use the instruction to set control signals other than the ALU.

Signal Name	Effect when not set	Effect when set
RegDst	Destination register comes from rt field.	Destination register comes from the rd field.
RegWrite	None.	Write Register is written to with Write Data.
ALUSrc	Second ALU operand is Read Data 2.	Second ALU operand is immediate field.
PCSrc	$PC \rightarrow PC + 4$	$PC \rightarrow$ Branch target
MemRead	None.	Contents of Address input are copied to Read Data.
MemWrite	None.	Write Data is written to Address.
MemToReg	Value of register Write Data is from ALU.	Value of register Write Data is memory Read Data.

Here, we have modified the datapath to work with every instruction except the jump instruction.

Notice how most of the control decisions can be decided using only the upper 6 bits of the instruction (opcode).



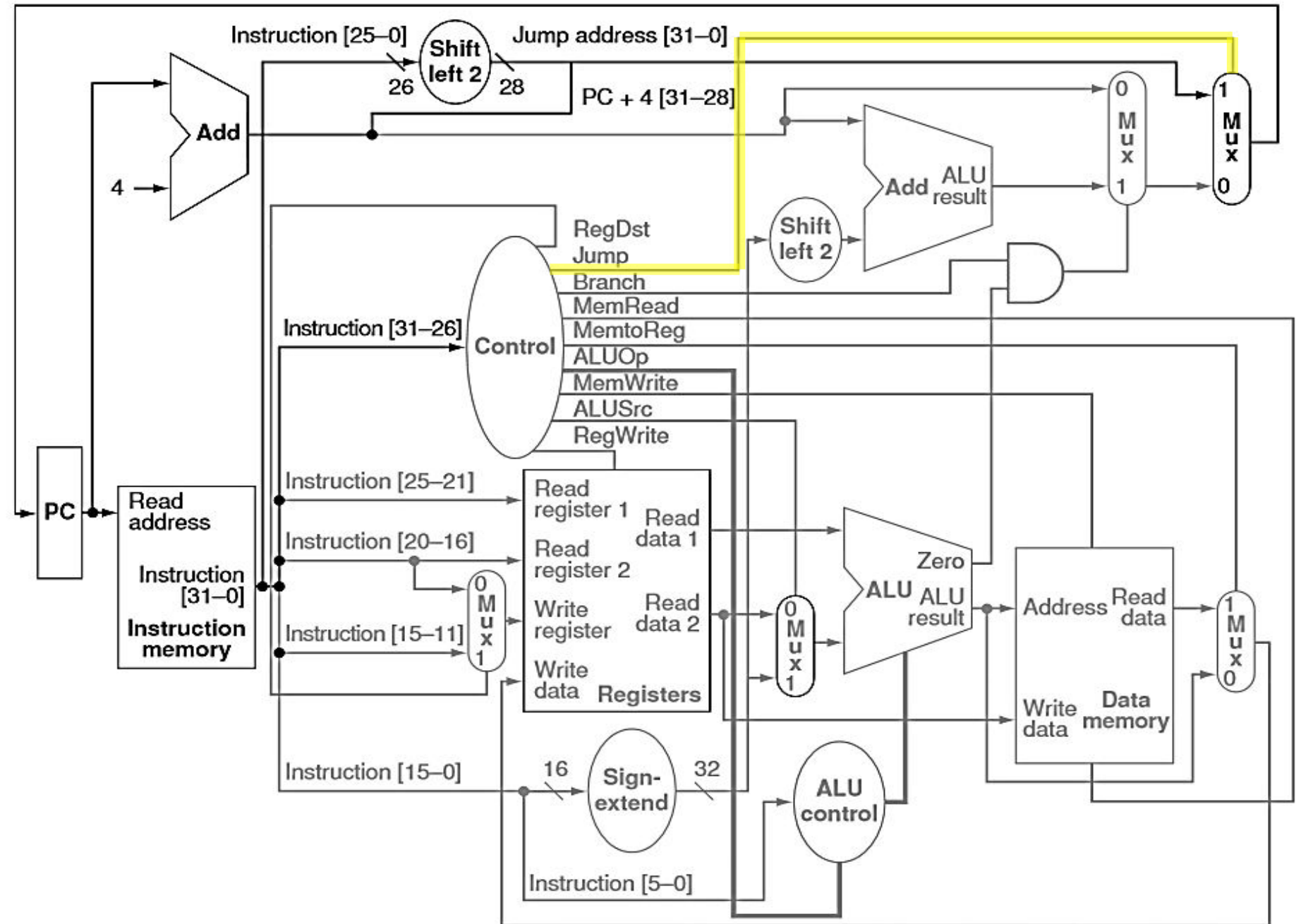
CONTROL SIGNALS

- From the previous slide, we can see that the control signals are chosen based on the upper 6 bits of the instruction. That is, the *opcode* is used to set the control lines.

Inst r.	RegDs t	ALUSr c	MemToR eg	RegWrit e	MemRea d	MemWrit e	Branc h	ALUOp1	ALUOp 2
R	1	0	0	1	0	0	0	1	0
lw	0	1	1	1	1	0	0	0	0
sw	X	1	X	0	0	1	0	0	0
beq	X	0	X	0	0	0	1	0	1

- Furthermore, as we saw before, the ALU control input lines are also dictated by the funct fields of applicable instructions.

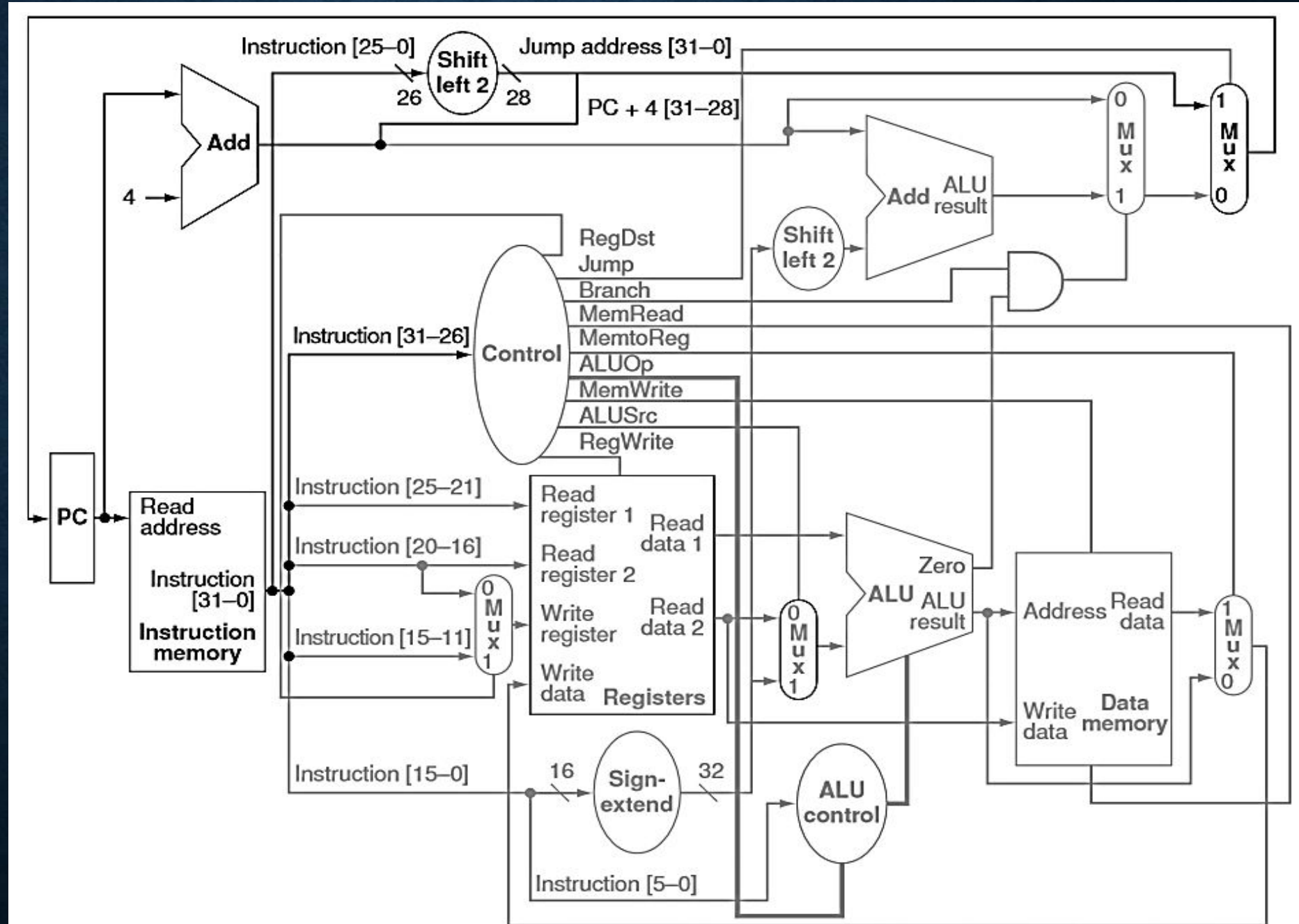
Here we add in an additional control line for jump instructions.



Quiz Time!

What are the relevant datapath lines for the add instruction and what are the values of each of the control lines?

`add $rd, $rs, $rt`

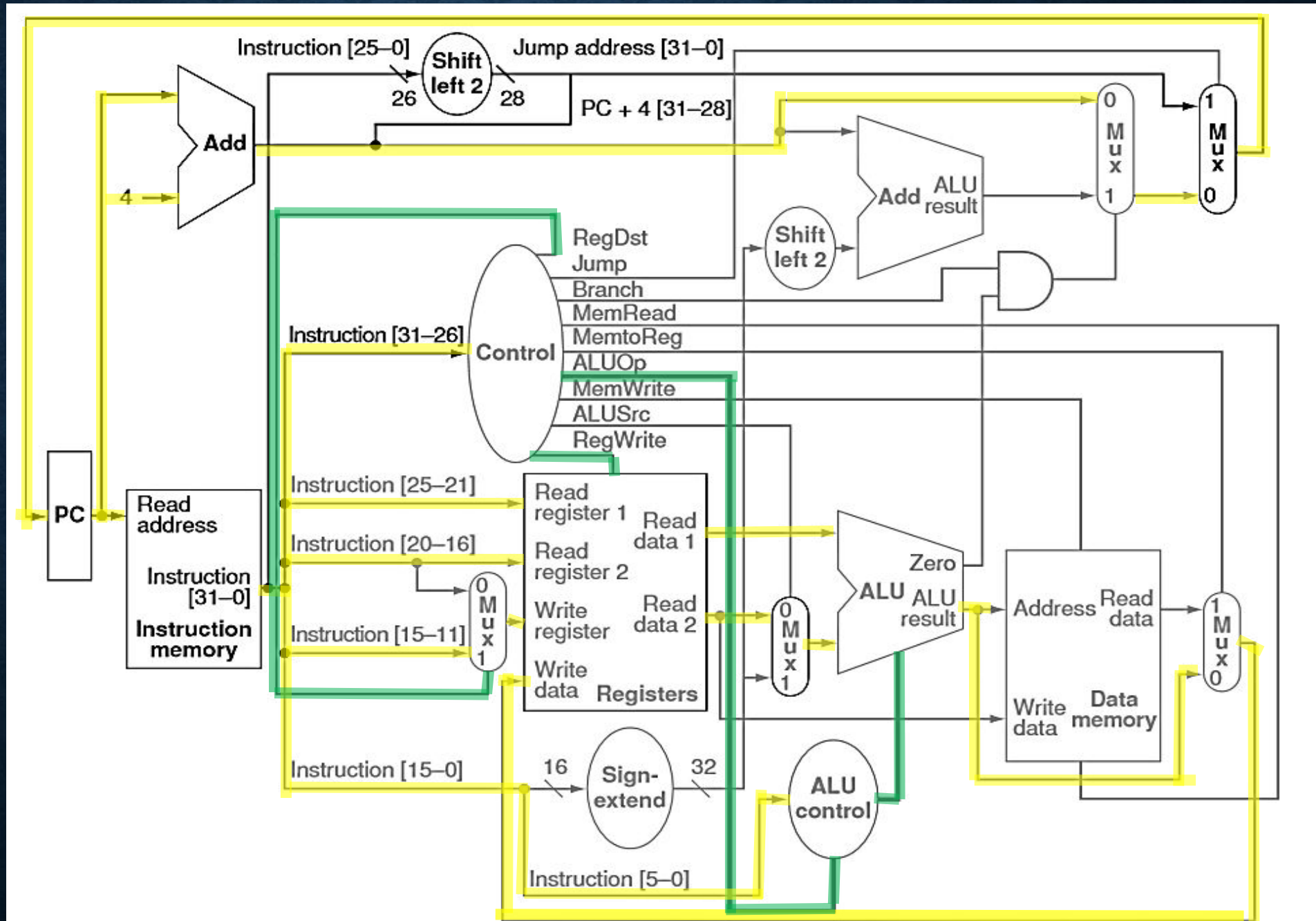


Quiz Time!

What are the relevant datapath lines for the add instruction and what are the values of each of the control lines?

```
add $rd, $rs, $rt
```

Datapath shown in yellow. Relevant control line assertions in green.

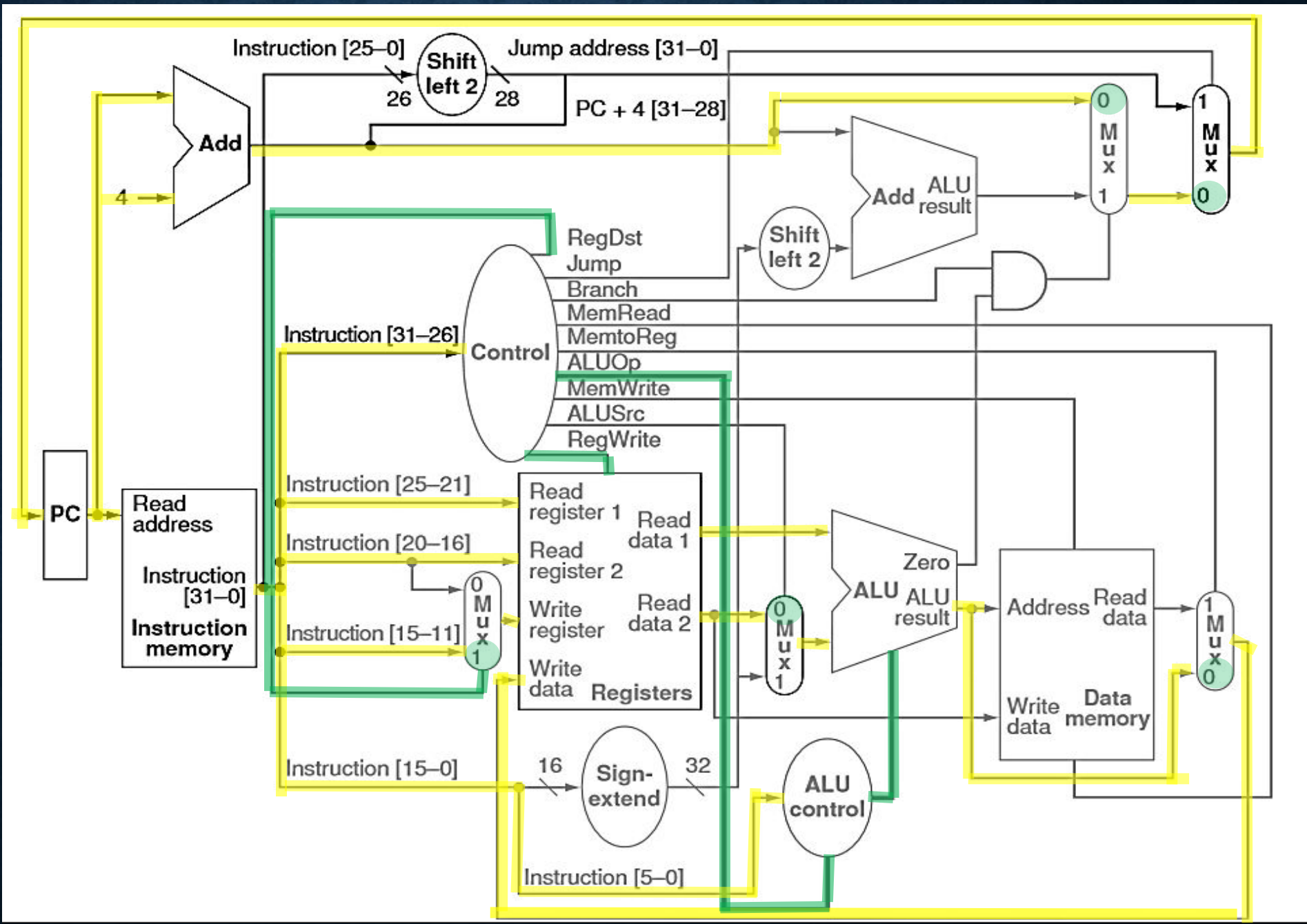


Quiz Time!

What are the relevant datapath lines for the add instruction and what are the values of each of the control lines?

```
add $rd, $rs, $rt
```

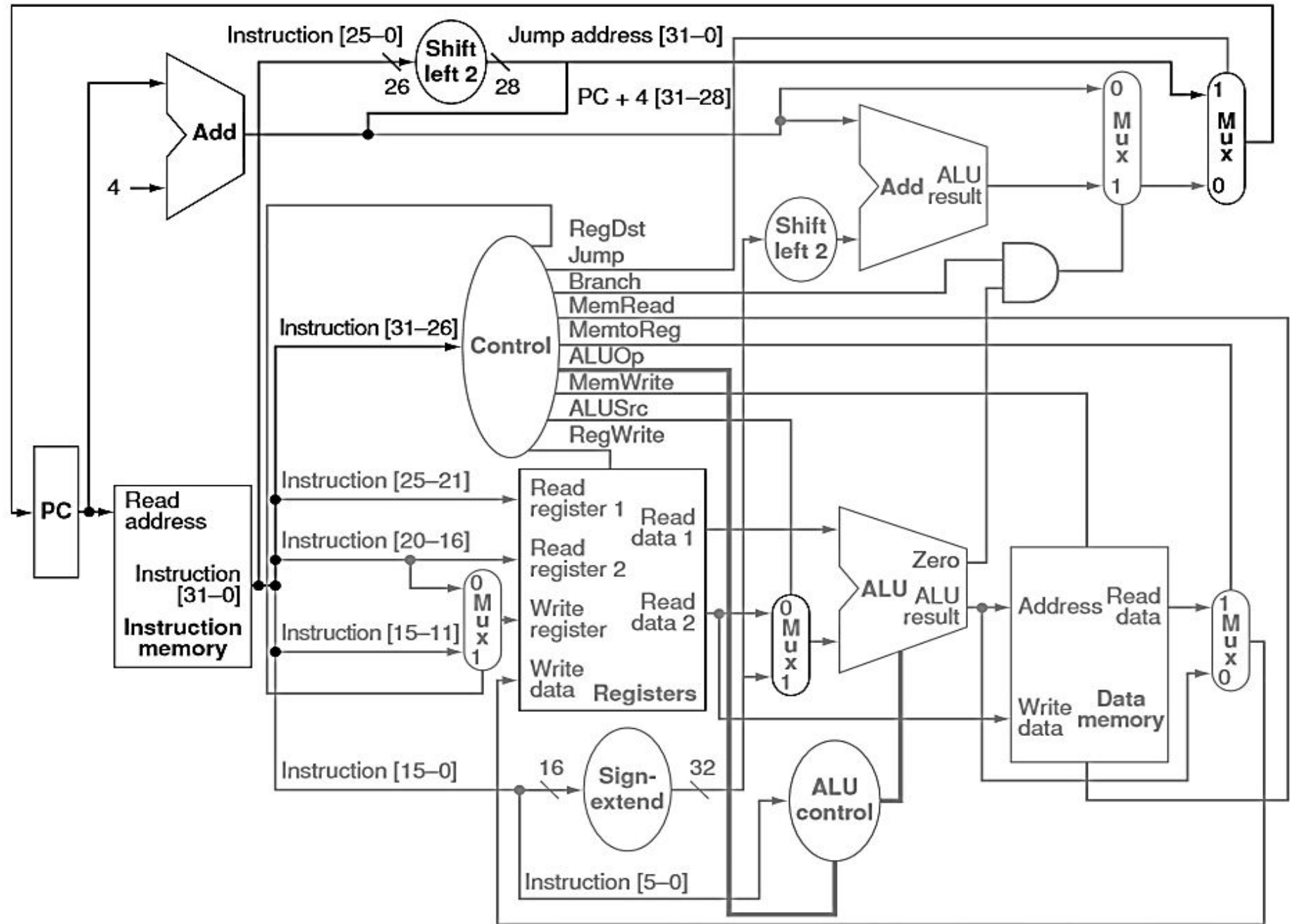
Datapath shown in yellow. Relevant control line assertions in green.



Quiz Time!

What are the relevant datapath lines for the beq instruction and what are the values of each of the control lines?

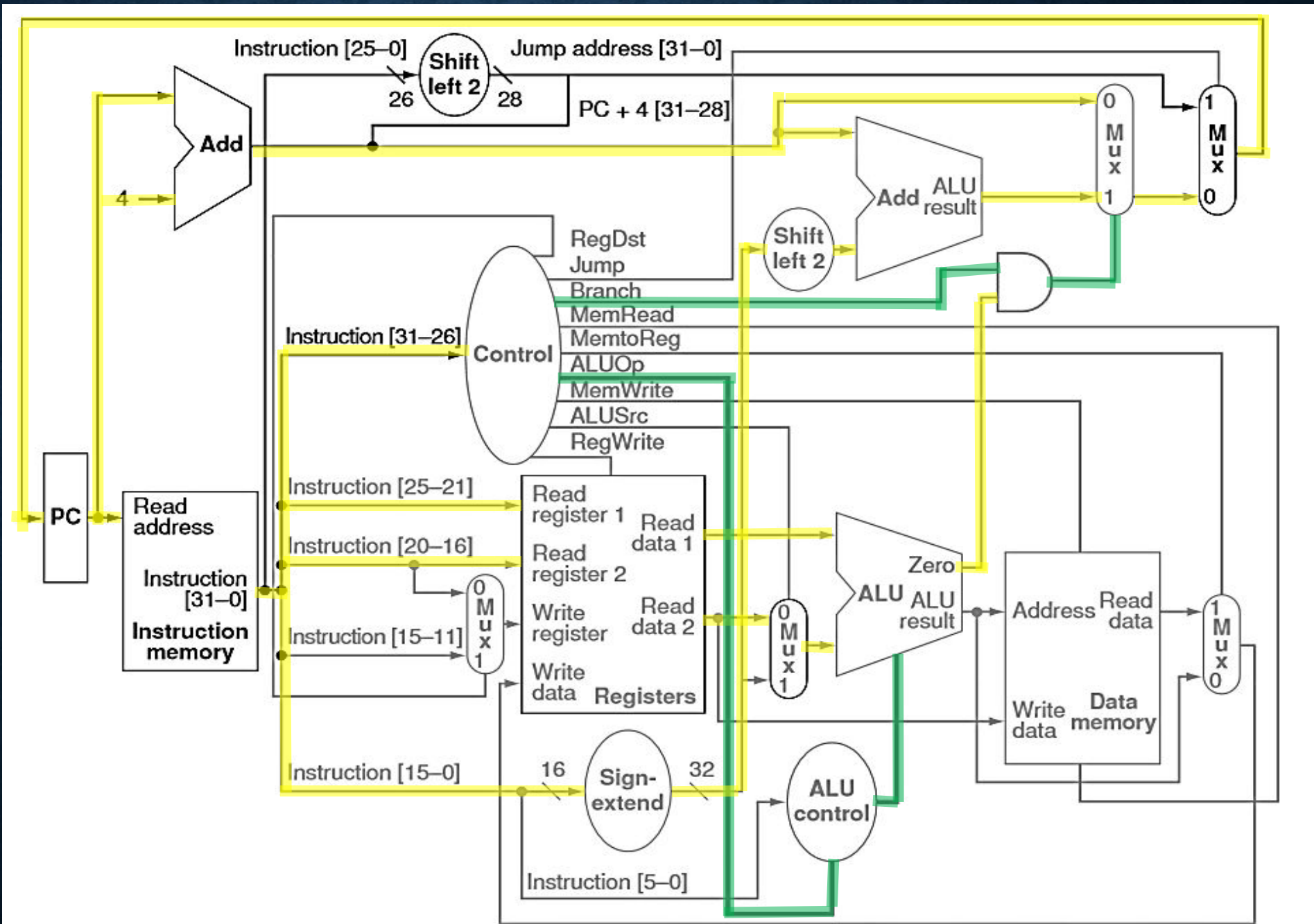
```
beq $rs, $rt, imm
```



Quiz Time!

What are the relevant datapath lines for the beq instruction and what are the values of each of the control lines?

```
beq $rs, $rt, imm
```



RELATIVE CYCLE TIME

- What is the longest path (slowest instruction) assuming 4ns for instruction and data memory, 3ns for ALU and adders, and 1ns for register reads or writes? Assume negligible delays for muxes, control unit, sign extend, PC access, shift left by 2, routing, etc

Type	Instruction Memory	Register Read	ALU Operation	Data Memory	Register Write	Total
R-format	4	1	3	0	1	9
lw	4	1	3	4	1	13
sw	4	1	3	4	0	12
beq	4	1	3	0	0	8
j	4	0	0	0	0	4

SINGLE-CYCLE IMPLEMENTATION

- The advantage of single cycle implementation is that it is simple to implement.
- Disadvantages
 - The clock cycle will be determined by the longest possible path, which is not the most common instruction. This type of implementation violates the idea of making the common case fast.
 - May be wasteful with respect to area since some functional units, such as adders, must be duplicated since they cannot be shared during a single clock cycle