On Debugging Real-Time Applications

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Overview

- debugging part of development cycle (up to 50% of time)
- few debuggers address real-time issues:
  - deadline monitoring
  - time distortion due to interference of debugging
- new debugging environment:
  - cache simulation to keep track of elapsed cycles
  - displays elapsed execution time (cycles)
  - works without changing debugger
  - slows down execution by factor of 1-4
  - much faster than hardware simulators
  - to find missed deadlines
  - to locate time-consuming code portions
Problems with Real-Time Debugging

- time distortion:
  - interference: breakpoints, debugger kernel traps, caching
  - replace real time with virtual time
  - external events simulated
- deadline monitoring and task tuning
- uni- vs. multi-processor
Overview of Debugging Environment

- Source files
- Compiler
- Object files
- Linker
- Executable program
- Source-level debugger
- Time estimation routines
- Cache configuration
- Control flow information
- Static cache simulator
- Instruction annotation
Real-Time Debugging Environment

- elapsed time tracing:
  - query during debugging (any breakpoint)
  - calculate based on cache hit and misses simulated so far
  - can translate number of cycles into seconds
- debugging optimized code:
  - allows realistic timing simulation
  - restricts debugging to basic blocks (breakpoints)
  - can also display most variables in registers
  - sometimes inconsistent values (due to optimizations)
Sample Session with dbx

(dbx) stop at 43
(dbx) stop at 123 if elapsed_cycles() > 4000000
(dbx) display elapsed_cycles()
[...]
stopped in four at line 43
    43    mmax=2;
elapsed_cycles() = 29413
(dbx) next
stopped in four at line 44
    44    while(n>mmax) {
elapsed_cycles() = 29428
[...]
    123    four(tdata,nn,isign);
elapsed_cycles() = 4015629
[...]
elapsed_cycles() = 4095351
execution completed, exit code is 1
- break after 4 million cycles
- display elapsed time
- breakpoints do not affect virtual time keeping
- deadline missed after 4+ million cycles (points to area where it’s misses)
- program terminated even later
- could set breakpoint at inner nesting level next to localize missed deadline
Performance Overhead

<table>
<thead>
<tr>
<th>unopt. code</th>
<th>opt. code with time estimates</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>1kB</td>
</tr>
<tr>
<td>1.8</td>
<td>7.8</td>
</tr>
</tbody>
</table>
• implemented on SPARC
• modified VPO
• used dbx under SunOS 4.1.3
• verified correctness of instruction cache simulation by comparing with trace-driven simulation
• 11 test programs
• unopt. about 1.8 times slower than opt. code
• instr. opt. about 2.1 to 7.8 times slower than opt. code
• instr. opt. about 1 to 4 times slower than common unopt. code
• cache size influences overhead (due to conflicts)
Future Work

- external event table
- \texttt{pragma \texttt{zerotimetoinsertnon}}
  
  intrusive\texttt{debugging\texttt{co}}\texttt{de}\texttt{extendtodat}acaching,\texttt{pipelining}
- to be used with Pthreads real-time kernel on SPARC VME board
- profiling with timing information
Related Work

- debugging capabilities typically very restricted
- Remedy: interface, suspend all processors on breakpoint
- DCT: special hardware (bus monitoring), non-intrusive
- RED, ART: software instrumentation, remote debugging
- DARTS: (1) program trace (2) debug time-stamped trace
- hardware simulators: very slow
- debugging remote, indirect (off-line), not within program
- Remedy:
  - DCT: Distributed computing testbed
  - RED: Remotely executed debugger
  - ART: instrumentation permanent part of programs
  - DARTS: Debug assistant for RTTs, no data queries
Summary

- developed new debugging enhancement for real-time
- replace real time with virtual time
- keep track of virtual time by instruction cache simulation
- feasible through static cache simulation
- debug unoptimized or optimized code
- display time repeatedly at breakpoints
- find missed deadlines through conditional breakpoints
- locate time-consuming code, tune it
- tuning may be used to make schedule feasible
- performance overhead of factor 1 to 4 over unoptimized code