On Debugging Real-Time Applications

Frank Mueller and David Whalley

Department of Computer Science Florida State University Tallahassee, FL 32304-4019

e-mail:

mueller@cs.fsu.edu whalley@cs.fsu.edu

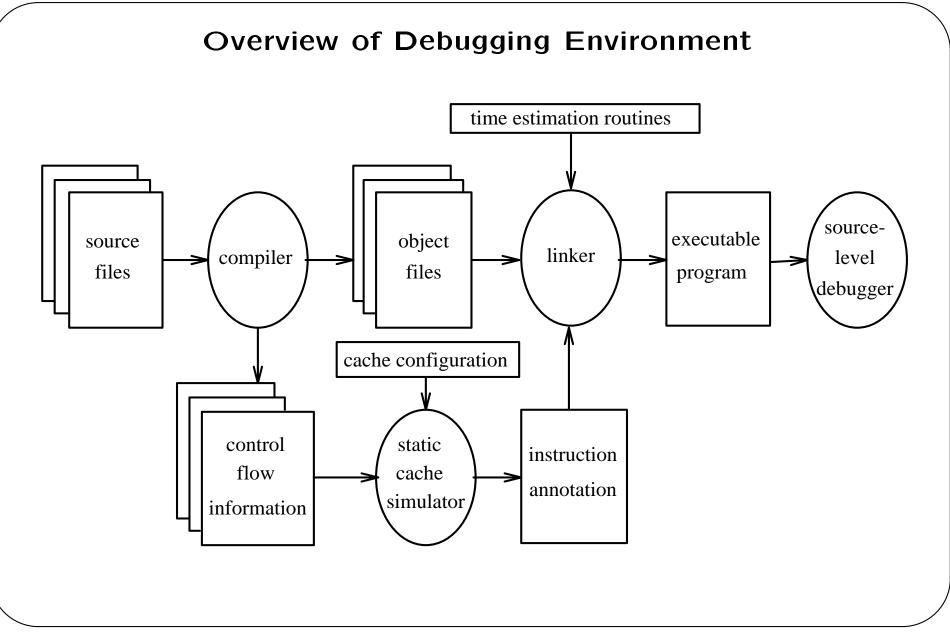
Overview

- debugging part of development cycle (up to 50% of time)
- few debuggers address real-time issues:
 - deadline monitoring
 - time distortion due to interference of debugging
- new debugging environment:
 - cache simulation to keep track of elapsed cycles
 - displays elapsed execution time (cycles)
 - works without changing debugger
 - slows down execution by factor of 1-4
 - much faster than hardware simulators
 - to find missed deadlines
 - to locate time-consuming code portions

Problems with Real-Time Debugging

• time distortion:

- interference: breakpoints, debugger kernel traps, caching
- replace real time with virtual time
- external events simulated
- deadline monitoring and task tuning
- uni- vs. multi-processor



Real-Time Debugging Environment

- elapsed time tracing:
 - query during debugging (any breakpoint)
 - calculate based on cache hit and misses simulated so far
 - can translate number of cycles into seconds
- debugging optimized code:
 - allows realistic timing simulation
 - restricts debugging to basic blocks (breakpoints)
 - can also display most variables in registers
 - sometimes inconsistent values (due to optimizations)

Sample Session with dbx

```
(dbx) stop at 43
(dbx) stop at 123 if elapsed_cycles() > 4000000
(dbx) display elapsed_cycles()
[...]
stopped in four at line 43
   43
         mmax=2;
elapsed_cycles() = 29413
(dbx) next
stopped in four at line 44
   44 while(n>mmax) {
elapsed_cycles() = 29428
[...]
           four(tdata,nn,isign);
  123
elapsed_cycles() = 4015629
[...]
elapsed cycles() = 4095351
execution completed, exit code is 1
```

- break after 4 million cycles ٠
- display elapsed time •
- ۲
- breakpoints do not affect virtual time keeping deadline missed after 4+ million cycles (points to area where it's misses) •
- program terminated even later •
- could set breakpoint at inner nesting level next to localize missed deadline

Performance Overhead

unopt.	opt. code with time estimates			
code	1kB	2kB	4kB	8kB
1.8	7.8	4.5	3.0	2.1

- implemented on SPARC
- modified VPO
- used dbx under SunOS 4.1.3
- verified correctness of instruction cache simulation by comparing with trace-driven simulation
- 11 test programs
- unopt. about 1.8 times slower than opt. code
- instr. opt. about 2.1 to 7.8 times slower than opt. code
- instr. opt. about 1 to 4 times slower than common unopt. code
- cache size influences overhead (due to conflicts)

Future Work

- external event table
- pragma zero_timetoinsertnon intrusivedebuggingcodeextendtodatacaching, pipelining
- to be used with Pthreads real-time kernel on SPARC VME board
- profiling with timing information

Related Work

- debugging capabilities typically very restricted
- Remedy: interface, suspend all processors on breakpoint
- DCT: special hardware (bus monitoring), non-intrusive
- RED, ART: software instrumentation, remote debugging
- DARTS: (1) program trace (2) debug time-stamped trace
- hardware simulators: very slow

- debugging remote, indirect (off-line), not within program
- Remedy: •
- •
- •
- •
- DCT: Distributed computing testbed RED: Remotely executed debugger ART: instrumentation permanent part of programs DARTS: Debug assistant for RTSs, no data queries •

Summary

- developed new debugging enhancement for real-time
- replace real time with virtual time
- keep track of virtual time by instruction cache simulation
- feasible through static cache simulation
- debug unoptimized or *optimized* code
- display time repeatedly at breakpoints
- find missed deadlines through conditional breakpoints
- locate time-consuming code, tune it
- tuning may be used to make schedule feasible
- performance overhead of factor 1 to 4 over unoptimized code

FSU