Divide-and-Merge Methodology for Clustering

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Outline

- Intro to data clustering
- Eigencluster algorithm
- Web search engine example
- Analysis
- Conclusion

Data Clustering

- Classification/labeling
- Input: data composed of elements
- Output: classification of elements into groups with similar objects
- Distance measure
- Machine learning, data mining, pattern recognition, statistical analysis, etc...

Cluster distance

- Distance between clusters given by distance measure
- Several measures available
 - euclidean
 - manhattan
 - mahalanobis

Data Clustering

- Hierarchical
 - Tree
 - Divisive vs Agglomerative
- Partitional
 - K-Means
- Spectral

K-Means

- Randomized centroids (K groups)
- Object membership determined by distance to centroids
- Centroid location recalculated
- Repeated until convergence
- Fuzzy c-Means, QT clustering, etc...

Eigencluster

- Clustering algorithm using "divide-andmerge" approach
- Published in Journal of the ACM, 2004
- Combination of clustering approaches
- Used for web searches, but can be applied to any clustering problem
 - http://www-math.mit.edu/cluster/

Eigencluster



- Divide and Merge methodology
- Phase 1: divide data
- Phase 2: merge divided data

- Create hierarchical clustering of data (tree)
- Input: set of objects w/ distances
- Algorithm recursively divides sets until singletons
- Output: tree with singleton leaves
 - internal nodes represent subsets
- Authors suggest spectral clustering

Spectral Clustering

- Input matrix A has objects as rows
- Uses similarity matrix (AAT)
 - similarity given by dot product:

$$a \cdot b = \sum_{i=1}^{n} a_i b_i = a_1 b_1 \times a_2 b_2 \times \dots \times a_n b_n$$

- sparse
 - knn, etc

Spectral Clustering

- Normalize sparse matrix
- Calculate second eigenvector
 - eigenvector defines "cut" on original matrix
 - cut based on: sign, mean, median, etc...

- Main idea
 - divide an initial cluster into subclusters using spectral clustering
 - compute 2nd eigenvector of similarity matrix via power method
 - find best cut in n-1 possible cuts

- Definitions:
 - Let $\rho \in \mathbb{R}^n$ be a vector of the row sums of AAT

• Let
$$\pi = \frac{1}{\Sigma_i \rho_i} \rho$$

• Let R be a diagonal matrix so that

$$R_{ii} = \rho_i$$

- Authors propose the use of the spectral algorithm in []
 - second largest eigenvalue of normalized similarity matrix B = R-1AAT
 - For efficiency, eigenvector is computed from symmetric matrix Q = DBD-1
 - Symmetric Q, power method

- Power method steps:
 - let v be an arbitrary vector orthogonal to $\pi TD-1$
 - repeat:
 - normalize v (v = v / ||v||)
 - set v = Qv
- Converges in O(log n) (proof in paper)

- Power method
 - used to estimate 2nd largest eigenvector
 - fast matrix-vector multiplication
 - $Q = DR^{-1}AA^{T}D^{-1}$
 - For v = Qv, perform four individual sparse matrix-vector multiplications (ie., v = D⁻¹v, etc...)

- Problem:
 - spectral clustering requires normalized similarity matrix (for calculating $\rho \in R^n$)
 - expensive!
 - solution: do not compute explicitly

• Rewrite row sums as:

$$\rho_i = \sum_{j=1}^n A_{(i)} \cdot A_{(j)}$$
$$= \sum_{j=1}^n \sum_{k=1}^m A_{ik} A_{jk}$$
$$= \sum_{k=1}^m A_{ik} \left(\sum_{j=1}^n A_{ik} \right)$$

• $\sum_{j=1}^{n} A_{ik}$ does not depend on i, so runtime is O(M), where M is # of nonzero entries

- Current steps:
 - Let $\rho \in \mathbb{R}^n$ be a vector of the row-sums of AA^T

• Let
$$\pi = \frac{1}{\Sigma_i \rho_i} \rho$$

- Compute 2nd largest eigenvector v' of $Q = DR^{-1}AA^{T}D^{-1}$
- Let $v = D^{-1}v'$, and sort $v so v_i < v_{i+1}$

- N-dimensional eigenvector v defines n-1 possible cuts
- Original matrix is sorted according to v, and must be cut
- Find t such that the cut (S, T) =
 ({1, ..., t}, {t+1, ..., n}) minimizes the
 conductance across the cut

- Best cut: min-conductance vs min-cut
 - min-cut = cut with minimum weight across it
 - assumes this means 2 resulting groups are least similar of possible cuts
 - problem: resulting cut may not provide best groups

 Example: cut C2 may have minimum weight across 2 edges, but cut C1 provides better grouping



- Conductance:
 - find a cut such that $(S,T) = (\{1, \dots, t\}, \{t+1, \dots, n\})$

• minimize: $\phi(S,T) = \frac{c(S,T)}{\min(c(S),c(T))}$

• where
$$\frac{c(S,T) = \sum_{i \in S, j \in T} A_{(i)} \cdot A_{(j)}}{c(S) = C(S, \{1 \dots, n\})}$$

- Conductance:
 - helps find cuts with approximately equal size
 - eg., t=2 vs t=n/2
 - t=2 yields large numerator, small denominator
 - larger overall fraction, not minimizing conductance

• Complete divide algorithm:

Input: An $n \times m$ matrix A. **Output:** A tree with the rows of A as leaves.

- (1) Let $\rho \in \mathbb{R}^n$ be a vector of the row sums of AA^T , and $\pi = \frac{1}{(\sum_i \rho_i)}\rho$.
- (2) Let R, D be diagonal matrices with $R_{ii} = \rho_i$, $D_{ii} = \sqrt{\pi_i}$.
- (3) Compute the second largest eigenvector v' of $Q = DR^{-1}AA^TD^{-1}$.
- (4) Let $v = D^{-1}v'$, and sort v so that $v_i \leq v_{i+1}$.
- (5) Find t such that the cut

$$(S,T) = (\{1,\ldots,t\},\{t+1,\ldots,n\})$$

minimizes the conductance:

$$\phi(S,T) = \frac{c(S,T)}{\min(c(S),c(T))}$$

where $c(S,T) = \sum_{i \in S, j \in T} A_{(i)} \cdot A_{(j)}$, and $c(S) = C(S, \{1...,n\})$.
6) Let \hat{A}_S , \hat{A}_T be the submatrices of A . Recurse (Steps 1-5) on \hat{A}_S and \hat{A}_T .



- Applied to tree produced by divide phase
- Idea: find best classification produced by divide phase

- Input: hierarchical tree T
- Output: partition $C_1, ..., C_k$ where C_i is a node in T
- Dynamic program to evaluate objective function g
- Bottom up traversal: OPT for interior nodes computed by merging OPT in $C_{\rm l}$, $C_{\rm r}$

- Properties of tree T:
 - each node is a subset of objects
 - L,R children form partition for parent
 - Clustering: subset S of nodes in T s.t. every leaf node is covered (leaf-root path encounters exactly 1 node in S)

- Objective function g
 - describes optimal merge
 - choice of g may vary, crucial!
 - note: $g(C_{OPT})$ may not be OPT clustering
 - choice of g
 - OPT may not respect tree

- K-Means objective function
 - k-clustering minimizing sum of squared distances of the pts in each cluster to the centroid p_i

$$g(\lbrace C_1, \dots, C_k \rbrace) = \sum_i \sum_{u \in C_i} d(u, p_i)^2$$

- pi = mean of points in a cluster Ci
- NP-Hard!

- K-Means objective functions
 - Let OPT-TREE(C,i) be optimal treerespecting clustering for C with i clusters
 - OPT-TREE(*C*,1) = {*C*}
 - OPT-TREE(C_i) = OPT-TREE(C_i ,j) \cup OPT-TREE(C_r ,i-j)
 - where $j = \operatorname{argmin}_{i \le j < i} g(OPT-TREE(C_{i}, j) \cup OPT-TREE(C_{r}, i-j))$

- Compute OPT clustering for leaf nodes first
- Interior nodes computed efficiently via dynamic programming
- OPT-TREE(root, k) gives optimal clustering of data
 - root = root node of divide phase tree

- Min-diameter objective function
 - k-clustering minimizing max diameter
 - diameter max distance between pair of objects in C_i
 - defined as:

$$g(\{C_1,\ldots,C_k\}) = \max_i \operatorname{diam}(C_i)$$

- Min-sum objective function
 - minimize sum of pairwise distances within C_i
 - computed via dynamic program

$$g(\{C_1, \dots, C_k\}) = \sum_{i=1}^k \sum_{u, v \in C_i} d(u, v)$$

 approximation algorithms exist, but not useful in practice

- Correlation clustering objective function
 - G = {V, E}; for each e_i∈E, e_i is red (similar vertices) or blue (dissimilar vertices)
 - find partition maximizing red edges within cluster, and blue edges between clusters

$$g(\{C_1 \dots C_k\}) = \sum_i |\{(u, v) \in R \cap C_i\}| + \frac{1}{2} |\{(u, v) \in B : u \in C_i, v \in U \setminus C_i\}|$$

- Time complexity
 - Divide
 - Merge
 - choice of g
 - iterations

- Sample implementation: web search
- Typical search engine: linear rank
 - fails to show inherent correlation when ambiguity is present (ie, "Mickey" -Rooney, Mantle, Mouse, ...)

- Input query: retrieve 400 results from Google
 - title, location, snippet
- Construct document-term matrix:

 D_1 = "You like Bob" D_2 = "You hate hate Bob"

	You	like	hate	Bob
D			0	
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- Divide phase spectral algorithm
- Merge phase relaxed correlation clustering
 - similar to correlation clustering but relaxed components a, β remove dependency on predefined k

• Relaxed correlation objective function:

$$\sum_i \alpha \left(\sum_{u,v \in C_i} 1 - A_{(u)} \cdot A_{(v)} \right) + \beta \left(\sum_{u \in C_i, v \notin C_i} A_{(u)} \cdot A_{(v)} \right)$$

- first component: dissimilarity within cluster
- second component: similarity failed to be captured

• eigencluster:
$$a = 0.2$$
, $\beta = 0.8$

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5 clusters and 294 additional results found in 1.290 seconds. Explore a cluster or click on a keyword to refine your search.	
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(a) Query: pods

(b) Before/after: pods

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(c) Query: mickey



(d) Before/after: mickey

Analysis

- Experiment on Boley dataset
 - 185 web pages
 - 10 classes
 - different objective functions
 - quality of results measured by entropy
 - randomness within cluster
 - lower value

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	J1	J2	J3	J4	J5	J6	J7	J8	J9	J10	J11
k-means	1.00	0.93	0.88	0.81	1.00	0.93	0.84	0.83	0.95	0.71	1.07
min-sum	0.98	0.93	0.88	0.78	0.98	0.92	0.84	0.83	0.94	0.71	1.10
min-diam	1.04	1.10	0.96	1.04	1.10	1.00	1.05	1.23	1.24	0.83	1.16
best in tree	0.98	0.93	0.88	0.78	0.96	0.91	0.84	0.83	0.92	0.71	1.05

- k-means and min-sum typically outperform min-diam
- 7 of 11 k-means or min-sum found best possible clustering

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T_mean: 69.5 6.75	

Conclusion

- clustering based on divide-merge
- idea: divide groups data hierarchically, merge finds best cluster within
- divide phase: spectral clustering
- merge: objective functions