## Homework 4: Ranking Components By Size 50 Points

A component of a graph G = (V, E) is a maximal connected subgraph  $G_1 = (V_1, E_1)$  of G. Any two vertices in  $V_1$  are connected by a path and no edge has one vertex in  $V_1$  and the other outside  $V_1$ .

A component of a Partition p is one of the sets in p.

**Part 1: Algorithms.** Invent an algorithm named **RankComponentsBySize** that operates on a Partition object p (through its API) and produces a vector v of unsigned integers such that v[i] is the size of the  $(1+i)^{th}$  largest component of p: p[0] is the size of the largest component, p[1] is the size of the second-largest component, and so on.

Also invent an algorithm that creates a Partition object p that captures the precise component structure of an undirected graph g. Combine the two algorithms to obtain an application for a graph g: The Component Rank Sequence of g.

**Part 2: Implementations.** Code up the RankComponentsBySize algorithm in C++ conformant with the stub below (and also available in the file LIB/graph/partition\_util.h).

And also install your process for capturing the component structure of a graph in the second stub below (and also available in the file LIB/graph/graph\_util.h).

Test your implementations by compiling a copy of LIB/graph/agraph.cpp and executing agraph.x on various graphs: on small graphs that can be hand verified and on some large graphs (such as the "Kevin Bacon" actor-movie abstract graph) and some very large graphs generated at random. Compare your results with those using LIB/area51/agraph\_i.x.

The following libraries *may not* be used: <string>, <set>, <unordered\_set>, <map>, <unordered\_map>, <algorithm> . Use components of cop4531p/LIB instead.

Part 3: Correctness. Provide an argument that your algorithm is correct.

**Part 4: Run Costs.** Provide an estimate of the runtime and runspace requirements of your algorithm and your component modelling process.

## Part 5: Experiments.

1: Try to provide experimental evidence of the Erdös-Reńyi "critical value" for the emergence of a giant component.

**2:** Given your analysis of the Kevin Bacon graph, in the light of the Erdös-Reńyi result, what can you see or say about these graphs?

3: Discuss large multi-component maze graphs in the light of the Erdös-Reńyi.

Here is C++ code stub in which to code your algorithm. Note that the partition p and the vector v are passed by const reference and non-const reference, respectively.

```
template < class P >
void RankComponentsBySize (const P& p, fsu::Vector<size_t>& v) // p is a Partition object
{
    // your code goes here
}
```

(See the appendix below and the file LIB/graph/partition\_util.h for complete context).

Here is C++ code stub in which to code your graph component model process. Note that the graph g is passed by const reference and the other two arguments are passed through to the call to RankComponentsBySize.

```
template < class G >
void ComponentRankSequence(const G& g , size_t maxToDisplay, std::ostream& os)
{
    fsu::Partition p (g.VrtxSize());
    // your process to model the components of g with p goes here
    RankComponentsBySize(p,maxToDisplay,os); // <-- calls your algorithm here
}</pre>
```

(See the file LIB/graph/graph\_util.h for complete context).

Include a test diary in your submission. And Cite your sources!

Appendix: Computational context for RankComponentsBySize

```
template < class P >
void RankComponentsBySize (const P& p, fsu::Vector<size_t>& v)
{
 // your code goes here
}
// below is complete code used to display the results to a stream
template < class P >
void RankComponentsBySize (const P& p, size_t maxToDisplay, std::ostream& os = std::cout)
{
  int cw = floor(log10(p.Size()));
  if (cw < 4) cw = 4;
  cw += 3;
  size_t enough, components;
  fsu::Vector<size_t> componentSize(0);
  RankComponentsBySize(p,componentSize);
  enough = components = componentSize.Size();
  if (0 < maxToDisplay && maxToDisplay < enough) enough = maxToDisplay;</pre>
  os << '' number of components: '' << components << '\n';
  if (enough == components)
    os << '' all components ranked by size:'' << '\n';
  else
    os << '' top '' << enough << '' components ranked by size:'' << '\n';
  os << std::setw(cw) << ''rank''</pre>
     << std::setw(cw) << ''size'' << '\n'
     << std::setw(cw) << ''----''
     << std::setw(cw) << ``----'' << '\n';
  for (size_t i = 0; i < enough; ++i)</pre>
  ſ
    os << std::setw(cw) << 1 + i
       << std::setw(cw) << componentSize[i] << '\n';
    if (componentSize[i] == 1 && 1 + i < componentSize.Size())</pre>
    {
      os << std::setw(cw) << '*'</pre>
         << std::setw(cw) << 1 << `` (the remaining `' << (components - i - 1)
         << '' components have size 1)\n'';
      break;
    }
 }
}
```

```
// below is complete code used to write the results to a file
template < class P >
bool RankComponentsBySize (const P& p, size_t maxToDisplay, const char* filename)
{
   std::ofstream os;
   os.open(filename);
   if (os.fail())
   {
     std::cerr << `` ** Error: unable to open file `` << filename << `\n`;
     return 0;
   }
   RankComponentsBySize (p, maxToDisplay, os);
   os.close();
   return 1;
}
```