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1 Introduction

The gSOAP tools provide an automated SOAP and XML data binding for C and C++ based on compiler technologies. The tools simplify the development of SOAP/XML Web services and XML application in C and C++ using autocode generation and advanced mapping methods. Most toolkits for Web services adopt a WSDL/SOAP-centric view and offer APIs that require the use of class libraries for XML-specific data structures. This forces a user to adapt the application logic to these libraries because users have to write code to populate XML and extract data from XML using a vendor-specific API. This often leads to fragile solutions with little or no assurances for data consistency, type safety, and XML validation. By contrast, gSOAP provides a type-safe and transparent solution through the use of compiler technology that hides irrelevant WSDL-, SOAP-, and XML-specific details from the user, while automatically ensuring XML validity checking, memory management, and type-safe serialization. The gSOAP tools automatically map native and user-defined C and C++ data types to semantically equivalent XML data types and vice-versa. As a result, full SOAP interoperability is achieved with a simple API relieving the user from the burden of WSDL/SOAP/XML details, thus enabling him or her to concentrate on the application-essential logic.

The gSOAP tools support the integration of (legacy) C/C++ codes (and other programming languages when a C interface is available), embedded systems, and real-time software in SOAP/XML applications that share computational resources and information with other SOAP applications, possibly across different platforms, language environments, and disparate organizations located behind firewalls.

The gSOAP tools are also popular to implement XML data binding in C and C++. This means that application-native data structures can be encoded in XML automatically, without the need to write conversion code. The tools also produce XML schemas for the XML data binding, so external applications can consume the XML data based on the schemas.

1.1 Getting Started

To start building Web services applications or automate XML data bindings with gSOAP, you need:

- The gSOAP package from http://www.genivia.com/Products/downloads.html (select gSOAP toolkit standard edition from the list of software packages)
- A C or C++ compiler.
- You may want to install OpenSSL and the Zlib libraries to enable SSL (HTTPS) and compression. These libraries are available for most platforms and are often already installed.

The gSOAP software is self-contained, so there is no need to download any third-party software (unless you want to use OpenSSL and the library is not already installed, or if you need to rebuild the soapcpp2 tool, see below).

The gSOAP packages available from SourceForge include pre-build tools in the gsoap/bin directory:
• The \texttt{wsdl2h} WSDL/schema importer and data binding mapper tool.
• The \texttt{soapcpp2} stub/skeleton compiler and code generator.

Binaries of these two tools are included in the gSOAP package in \texttt{gsoap/bin} for Windows, Linux, and Mac OS platforms, see also the README files in the package for more details.

Although gSOAP tools are available in binary format for several platforms, the code generated by these tools are all equivalent. This means that the generated source codes can be transferred to other platforms and locally compiled.

If you don’t have the binaries or if you want to rebuild them, you need

• A C compiler and Bison (or Yacc) to build \texttt{soapcpp2}.
• A C compiler and Flex (or Lex) to build \texttt{soapcpp2}.
• A C++ compiler to build \texttt{wsdl2h}.

Bison and Flex are preferred. Both are released under open source licenses that are compatible with gSOAP’s licenses.

• Bison is available from \url{http://www.gnu.org/software/bison}
• Flex is available from \url{http://flex.sourceforge.net}

The gSOAP engine is built as a library \texttt{libgsoap.a} and \texttt{libgsoap++.a} with separate versions that support SSL. See the \texttt{README.txt} instructions on how to build these libraries with the platform-independent gSOAP package’s autoconf and automake. Alternatively, you can compile and link the engine’s source code \texttt{stdsoap2.c} (or \texttt{stdsoap2.cpp} for C++) directly with your code.

The gSOAP packages contain numerous examples in the \texttt{samples} directory. Run \texttt{make} to build the example applications. The examples are also meant to demonstrate different features of gSOAP. A streaming MTOM attachment server and client application demonstrate efficient file exchanges in \texttt{samples/mtom-stream}. An SSL-secure Web server application demonstrates the generation of dynamic content for Web browsing and Web services functionality at the same time, see \texttt{samples/webservice}. And much more.

\section*{1.2 Quick Start: Developing a Web Service Client Application}

The gSOAP tools minimize application adaptation efforts for building Web Services by using a XML data binding for C and C++ implemented by advanced XML schema analyzers and source-to-source code generation tools. The gSOAP \texttt{wsdl2h} tool imports one or more WSDLs and XML schemas and generates a gSOAP header file with familiar C/C++ syntax to define the Web service operations and the C/C++ data types. The gSOAP \texttt{soapcpp2} compiler then takes this header file and generates XML serializers for the data types (\texttt{soapH.h} and \texttt{soapC.cpp}), the client-side stubs (\texttt{soapClient.cpp}), and server-side skeletons (\texttt{soapServer.cpp}).

The gSOAP \texttt{soapcpp2} compiler can also generate WSDL definitions for implementing a service from scratch, i.e. without defining a WSDL first. This ”closes the loop” in that it enables Web services
development from WSDL or directly from a set of C/C++ operations in a header file without the need for users to analyze Web service details.

You only need to follow a few steps to execute the tools from the command line or Makefile (see also MSVC++ project examples in the samples directory with tool integration in the MSVC++ IDE). For example, to generate code for the calculator Web service, we run the wsdl2h tool from the command line on the URL of the WSDL and use option -o to specify the output file:

```bash
> wsdl2h -o calc.h http://www.genivia.com/calc.wsdl
```

This generates the calc.h service definition header file with service operation definitions and types for the operation’s data. This header file is then to be processed with soapcpp2 to generate the stub and/or skeleton code and XML serialization routines. The calc.h file includes all documentation, so you can use Doxygen (http://www.doxygen.org) to automatically generate the documentation pages for your development.

The wsdl2h-generated service definitions header file also contains information on the use of the service, such as WS-Policy assertions when applicable.

In this example we are developing a C++ API for the calculator service. By default, gSOAP assumes you will use C++ with STL. To build without STL, use option -s:

```bash
> wsdl2h -s -o calc.h http://www.genivia.com/calc.wsdl
```

To build a pure C application, use option -c:

```bash
> wsdl2h -c -o calc.h http://www.genivia.com/calc.wsdl
```

**Important**: Visual Studio users should make sure to compile all gSOAP source files in C++ compilation mode. If you migrate to a project file .vcproj, please set CompileAs="2" in your .vcproj file. We have not yet generated the stubs for the C/C++ API. To do so, run the soapcpp2 compiler:

```bash
> soapcpp2 -i -C -limport calc.h
```

Option -i (and alternatively option -j) indicates that we want C++ proxy and server objects that include the client (and server) code, -C indicates client-side only files (soapcpp2 generates both client and server stubs and skeletons by default). Option -I is needed to import the stlvector.h file from the import directory in the gSOAP package to support serialization of STL vectors.

Suppose we develop a C++ client for the calculator service using wsdl2h -o calc.h http://www.genivia.com/calc.wsdl and soapcpp2 -i -C calc.h.

We use the generated soapcalcProxy class and calc.nsmap XML namespace mapping table to access the Web service. The soapcalcProxy class is a proxy to invoke the service:

```c
#include "soapcalcProxy.h"
#include "calc.nsmap"
int main()
{
    calcProxy service;
```
double result;
if (service.add(1.0, 2.0, result) == SOAP_OK)
    std::cout << "The sum of 1.0 and 2.0 is " << result << std::endl;
else
    service.soap_stream_fault(std::cerr);
    service.destroy(); // delete data and release memory
}

To complete the build, compile the code above and compile and link this with the generated
soapC.cpp, soapcalcProxy.cpp, and the run-time gSOAP engine -lgsoap++ (or use source stdsoap2.cpp
in case libgsoap++.a is not installed) with your code.

Suppose we develop a client in C using wsdl2h -c -o calc.h http://www.genivia.com/calc.wsdl and soapcpp2
-C calc.h. In this case our code uses a simple C function call to invoke the service and we also need
to explicitly delete data and the context with soap_end and soap_free:

#include "soapH.h"
#include "calc.nsmap"
int main()
{
    struct soap *soap = soap_new();
    double result;
    if (soap_call_ns_add(soap, 1.0, 2.0, &result) == SOAP_OK)
        printf("The sum of 1.0 and 2.0 is %lg\n", result);
    else
        soap_print_fault(soap, stderr);
    soap_end(soap);
    soap_free(soap);
}

The calculator example is fairly simple and used here to illustrate the development process. The
development process for large-scale XML applications is similar. More extensive examples can be
found in the samples directory in the gSOAP package.

1.3 Quick Start: Developing a Web Service

Developing a service application is easy too. We will use CGI here because it is a simple mechanism.
This is not the preferred deployment mechanism. Because CGI is slow and stateless. Faster services
can be developed as a stand-alone gSOAP HTTP/HTTPS server (but see comments at the end of
this section) or, as preferred, the use of Apache module or IIS (included in the gSOAP package
under gsoap/mod_gsoap with instructions).

Suppose we implement a CGI-based service that returns the time in GMT. The Common Gateway
Interface (CGI) is a simple mechanism to publish services on your Web site.

For this example we start with a gSOAP header file, currentTime.h which contains the service defini-
tions. Such a file can be obtained from a WSDL using wsdl2h when a WSDL is available. When a
WSDL is not available, you can define the service in C/C++ definitions in a newly created header
file and let the gSOAP tools generate the source code and WSDL for you.

Our `currentTime` service only has an output parameter, which is the current time defined in our `currentTime.h` gSOAP service specification:

```c
// File: currentTime.h
//@gsoap ns service name: currentTime
//@gsoap ns service namespace: urn:currentTime
//@gsoap ns service location: http://www.yourdomain.com/currentTime.cgi
int ns__currentTime(time_t & response);
```

Note that we associate an XML namespace prefix `ns` and namespace name `urn:currentTime` with the service WSDL and SOAP/XML messages. The gSOAP tools use a special convention for identifier names that are part of a namespace: a namespace prefix (`ns` in this case) followed by a double underscore `__`. This convention is used to resolve namespaces and to avoid name clashes. The `ns` namespace prefix is bound to the `urn:currentTime` namespace name with the `//gsoap` directive. The `//@gsoap` directives are used to set the properties of the service, in this case the name, namespace, and location endpoint.

The service implementation for CGI requires a `soap_serve` call on a soap context created with `soap_new`.

```c
// File: currentTime.cpp
#include "soapH.h" // include the generated declarations
#include "currentTime.nsmap" // include the XML namespace mappings
int main()
{
    // create soap context and serve one CGI-based request:
    return soap_serve(soap_new());
}
int ns__currentTime(struct soap *soap, time_t & response)
{
    response = time(0);
    return SOAP_OK;
}
```

Note that we pass the soap struct with the gSOAP context information to the service routine. This can come in handy to determine properties of the connection and to dynamically allocate data with `soap_malloc(soap, num_bytes)` that will be automatically deleted when the service is finished.

We run the `soapcpp2` compiler on the header file to generate the server-side code:

```
> soapcpp2 -S currentTime.h
```

and then compile the CGI binary:

```
> c++ -o currentTime.cgi currentTime.cpp soapC.cpp soapServer.cpp stdsoap2.cpp
```

You will find `stdsoap2.cpp` in the `gsoap` dir. Or after installation you can link with `libgsoap++` instead of using the `stdsoap2.cpp` source:
To activate the service, copy the currentTime.cgi binary to your bin-cgi directory using the proper file permissions.

The soapcpp2 tool generated the WSDL definitions currentTime.wsdl. You can use the WSDL to advertise your service. You don’t need to use this WSDL to develop a gSOAP client. You can use the currentTime.h file with soapcpp2 option -C to generate client-side code.

A convenient aspect of CGI is that it exchanges messages over standard input/output. Therefore, you can run the CGI binary on the auto-generated example request XML file to test your server:

```
> ./currentTime.cgi < currentTime.currentTime.req.xml
```

and this displays the server response in SOAP XML.

The above approach works also for C. Just use soapcpp2 option -c in addition to the -S option to generate ANSI C code. Of course, in C we use pointers instead of references and the currentTime.h file should be adjusted to use C-only types.

A more elegant server implementation in C++ can be obtained by using the soapcpp2 option -i (or -j) to generate C++ client-side proxy and server-side service objects as classes that you can use to build clients and services in C++. The option removes the generation of soapClient.cpp and soapServer.cpp, since these are no longer needed when we have classes that implement the client and server logic:

```
> soapcpp2 -i -S currentTime.h
```

This generates soapcurrentTimeService.h and soapcurrentTimeService.cpp files, as well as auxiliary files soapStub.h (included by default by all codes) and currentTime.nsmap.

Using the currentTimeService object we rewrite the CGI server as:

```c++
// File: currentTime.cpp
#include "soapcurrentTimeService.h" // include the proxy declarations
#include "currentTime.nsmap" // include the XML namespace mappings
int main()
{
    // create server and serve one CGI-based request:
    currentTimeService server;
    server.serve();
    server.destroy();
}
int currentTimeService::currentTime(time_t& response)
{
    response = time(0);
    return SOAP_OK;
}
```

Compile with

```
> c++ -o currentTime.cgi currentTime.cpp soapC.cpp soapcurrentTimeService.cpp -lgsoap++
```
and install the binary as CGI. To install the CGI binary please consult your Web server documentation on how to deploy CGI applications.

To run the server as a stand-alone iterative (non-multithreaded) server on port 8080:

```c
while (server.run(8080) != SOAP_TCP_ERROR)
    server.soap_stream_fault(std::cerr);
```

To implement threaded services, please see Section 7.2.4. These stand-alone Web Services that handle multiple SOAP requests by spawning a thread for each request. Thread pooling is also an option. The use of Apache and IIS modules to deploy gSOAP services is preferred to ensure load balancing, access control, tracing, and so on.

For more information on server-side service classes, see Section 7.2.7. For more information on client-side proxy classes, see Section 7.1.4.

### 1.4 Quick Start: XML Data Bindings

Or in other words, how to map schemas (XSD files) to C/C++ bindings for automatically reading and writing XML data.

The XML C/C++ data binding in gSOAP provides and automated mechanism to encode any C and C++ data type in XML (and decode XML back to C/C++ data). An XML schema (XSD file) can be transformed into a set of C or C++ definitions that can be readily incorporated into your application to manipulate XML with much more ease than DOM or SAX. Essentially, each XML component definition in an XML schema has a C/C++ data type representation that has equivalent type properties. The advantage of this approach is immediately apparent when we look at an XSD complexType that maps to a class:

```xml
<complexType name="Address">
  <sequence>
    <element name="name" type="string"/>
    <element name="home" type="tns:Location" minOccurs="0"/>
    <element name="phone" type="unsignedLong"/>
    <element name="dob" type="dateTime"/>
    <attribute name="ID" type="int" use="required"/>
  </sequence>
</complexType>
```

In this way, an automatic mapping between XML elements of the XML schema and members of a class is created to No DOM traversals and SAX events are needed. In addition, the XML C/C++ data binding makes XML manipulation type safe. That is, the type safety of C/C++ ensures that only valid XML documents can be parsed and generated.

The `wsdl2h` tool performs the mapping of WSDL and XML schemas to C and/or C++ automatically. The output of `wsdl2h` is an annotated header file that includes comments and documentation on the use of the C/C++ declarations in a SOAP/XML client/server or in a generic application for reading and writing XML using the auto-generated serializers.
We will illustrate this further with an example. Suppose we have an XML document with a book record:

```xml
<book isbn="1234567890">
  <title>Farewell John Doe</title>
  <publisher>ABC's is our Name</publisher>
</book>
```

An example XML schema that defines the book element and type could be

```xml
<schema ...>
  <element name="book">
    <complexType>
      <sequence>
        <element name="title" type="string" minOccurs="1"/>
        <element name="publisher" type="string" minOccurs="1"/>
      </sequence>
      <attribute name="isbn" type="unsignedLong" use="required"/>
    </complexType>
  </element>
</schema>
```

Using `wsdl2h` we translate the XML schema that defines the book type and root element to a class definition:

```cpp
class book {
  @ULONG64 isbn;
  std::string title;
  std::string publisher;
}
```

Note that annotations such as `@` are used to distinguish attributes from elements. These annotations are gSOAP-specific and are handled by the `soapcpp2` tool to generate serializers for the data type(s) for reading and writing XML.

The `soapcpp2` tool generates all the necessary code to parse and generate XML for `book` objects. Validation constraints such as `minOccurs="1"` and `use="required"` are included in the generated code as checks.

To write the XML representation of a book, we first create a `soap` engine context and use it with `soap_write_book` (generated by `soapcpp2`) to write the object in XML to standard output:

```cpp
soap *ctx = soap_new1(SOAP_XMLINDENT); // new context with option
book bk;
bk.isbn = 1234567890;
bk.title = "Farewell John Doe";
bk.publisher = "ABC's is our Name";
if (soap_write_book(ctx, &bk) != SOAP_OK)
  ... error ...
soap_destroy(ctx); // clean up allocated class instances
```
The \texttt{ctx} gSOAP engine context (type \texttt{struct soap}) controls settings and holds state, such as XML formatting, (e.g. \texttt{SOAP/XML_INDENT}), serialization options, current state, and I/O settings. Simply set the output stream (\texttt{std::ostream}) \texttt{ctx->os} of the context to redirect the content, e.g. to a file or string. Also, when serializing a graph rather than an XML tree (\texttt{SOAP/XML_TREE} option forces trees) the XML output conforms to SOAP encoding for object graphs based on id-ref, see Section 7.5 for details.

To read the XML representation from standard input into a book object, use:

```cpp
soap *ctx = soap_new1(SOAP_XML_STRICT); // new context with option
book bk;
if (soap_read_book(ctx, &bk) != SOAP_OK) ... error ...
else
    cout << bk.isbn <<", " << bk.title <<", " << bk.publisher << endl;
    ... further use of \texttt{bk} ...
soap_destroy(ctx); // delete deserialized objects
soap_end(ctx); // delete temporaries
soap_free(ctx); // delete context
```

Automatic built-in XML validation (enabled with \texttt{SOAP/XML_STRICT}) ensures that data members are present so we can safely print them in this example, thus ensuring consistency of data with the XML schema. Set the \texttt{ctx->os} input stream to read from a file/string stream instead of stdin.

The \texttt{soap_destroy} and \texttt{soap_end} calls deallocate the deserialized content, so use with care. In general, memory management is automatic in gSOAP to avoid leaks.

The above uses a very simple example schema. The gSOAP toolkit handles all XML schema constructs defined by the XML schema standard. The toolkit is also able to (de)serialize pointer-based C/C++ data structures (including cyclic graphs), structs/classes, unions, enums, STL containers, and even special data types such as \texttt{struct tm}. Therefore, the toolkit works in two directions: from WSDL/schema to C/C++ and from C/C++ to WSDL/schema.

The gSOAP toolkit also handles multiple schemas defined in multiple namespaces. Normally the namespace prefixes of XML namespaces are added to the C/C++ type definitions to ensure type uniqueness. For example, if we would combine two schemas in the same application where both schemas define a \texttt{book} object, we need to resolve this conflict. In gSOAP this is done using namespace prefixes, rather than C++ namespaces (research has pointed out that XML namespaces are not equivalent to C++ namespaces). Thus, the \texttt{book} class might actually be bound to an XML namespace and the class would be named \texttt{ns\_book}, where \texttt{ns} is bound to the corresponding namespace.

The following options are available to control serialization:

```cpp
soap->encodingStyle = NULL; // to remove SOAP 1.1/1.2 encodingStyle
soap_mode(soap, SOAP_XML_TREE); // XML without id-ref (no cycles!)
soap_mode(soap, SOAP_XML_GRAPH); // XML with id-ref (including cycles)
soap_set_namespaces(soap, \texttt{struct Namespace *nsmapi}); // to set xmlns bindings
```
Other flags can be used to format XML, see Section 9.12.
More information on XML databinding support for C and C++, see Section 7.5.

1.5 Feature Overview

The highlights of gSOAP are:

- Unique interoperability features: the tools generate type-safe SOAP marshalling routines to (de)serialize native and user-defined C and C++ data structures.

- Support WSDL 1.1, WSDL 2.0, SOAP 1.1, SOAP 1.2, SOAP RPC encoding style, and document/literal style. gSOAP is one of the few SOAP toolkits that support the full range of SOAP 1.1 RPC encoding features including sparse multi-dimensional arrays and polymorphic types. For example, a service operation with a base class parameter may accept derived class instances from a client. Derived class instances keep their identity through dynamic binding. The toolkit also supports all XSD schema type constructs and has been tested against the W3C XML Schema Patterns for Databinding Interoperability working group and of gSOAP release 2.8.x passes all tests.

- Supports WS-Security, WS-Addressing, WS-ReliableMessaging, C14N exclusive canonicalization. The protocols are implemented using code generation with wsdl2h and soapcpp2. The gSOAP tools can be used to generate messaging protocols for other WS-* protocols.

- gSOAP supports XML-RPC and RSS protocols. Examples are provided.

- JSON support is included in the XML-RPC library to switch between XML-RPC and JSON protocols. For more details, see the samples/xml-rpc-json folder in the package.

- The wsdl2h tool supports WS-Policy. Policy assertions are included in the generated service description header file with recommendations and usage hints.

- gSOAP supports MIME (SwA), DIME, and MTOM attachments and has streaming capabilities to direct the data stream to/from resources. gSOAP is the only toolkit that supports streaming MIME, DIME, and MTOM attachment transfers, which allows you to exchange binary data of practically unlimited size in the fastest possible way (streaming) while ensuring the usefulness of XML interoperability.

- gSOAP supports SOAP-over-UDP.

- gSOAP supports IPv4 and IPv6.

- gSOAP supports Zlib deflate and gzip compression (for HTTP, TCP/IP, and XML file storage).

- gSOAP supports SSL (HTTPS) using OpenSSL and optionally using GNUTLS.

- gSOAP supports HTTP/1.0, HTTP/1.1 keep-alive, chunking, basic authentication, and digest authentication using a plugin.
• gSOAP supports SOAP one-way messaging.

• The schema-specific XML pull parser is fast and efficient and does not require intermediate data storage for demarshalling to save space and time.

• The soapcpp2 compiler includes a WSDL and schema generator for convenient Web Service publishing.

• The soapcpp2 compiler generates sample input and output messages for verification and testing (before writing any code). An option (-T) can be used to automatically implement echo message services for testing.

• The WSDL importer wsd2h (converts to gSOAP header files) for automated client and server development.

• Generates source code for stand-alone Web Services and client applications.

• Ideal for small devices such as Palm OS, Symbian, Pocket PC, because the memory footprint is small.

• Ideal for building web services that are compute-intensive and are therefore best written in C and C++.

• Platform independent: Windows, Unix, Linux, Mac OS X, Pocket PC, Palm OS, Symbian, VXWorks, etc.

• Supports serializing of application’s native C and C++ data structures, which allows you to save and load XML serialized data structures to and from files.

• Selective input and output buffering is used to increase efficiency, but full message buffering to determine HTTP message length is not used. Instead, a three-phase serialization method is used to determine message length. As a result, large data sets such as base64-encoded images can be transmitted with or without DIME attachments by small-memory devices such as PDAs.

• Supports C++ single class inheritance, dynamic binding, overloading, arbitrary pointer structures such as lists, trees, graphs, cyclic graphs, fixed-size arrays, (multi-dimensional) dynamic arrays, enumerations, built-in XSD Schema types including base64Binary encoding, and hexBinary encoding.

• No need to rewrite existing C/C++ applications for Web service deployment. However, parts of an application that use unions, pointers to sequences of elements in memory, and void* need to be modified, but only if the data structures that adopt them are required to be serialized or deserialized as part of a service operation invocation.

• Three-phase marshalling: 1) analysis of pointers, single-reference, multi-reference, and cyclic data structures, 2) HTTP message-length determination, and 3) serialization as per SOAP 1.1 encoding style or user-defined encoding styles.
• Two-phase demarshalling: 1) SOAP parsing and decoding, which involves the reconstruction of multi-reference and cyclic data structures from the payload, and 2) resolution of "forward" pointers (i.e. resolution of the forward $\texttt{href}$ attributes in SOAP).

• Full and customizable SOAP Fault processing (client receive and service send).

• Customizable SOAP Header processing (send and receive), which for example enables easy transaction processing for the service to keep state information.

2 Notational Conventions

The typographical conventions used by this document are:

Sans serif or italics font denotes C and C++ source code, file names, and shell/batch commands.

Bold font denotes C and C++ keywords.

Courier font denotes HTTP header content, HTML, XML, XML Schema content and WSDL content.

[Optional] denotes an optional construct.

The keywords "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in RFC-2119.

3 Differences Between gSOAP Versions 2.4 (and Earlier) and 2.5

To comply with WS-I Basic Profile 1.0a, gSOAP 2.5 and higher adopts SOAP document/literal by default. There is no need for concern, because the WSDL parser $\texttt{wsdl2h}$ automatically takes care of the differences when you provide a WSDL document, because SOAP RPC encoding, literal, and document style are supported. A new soapcpp2 compiler option was added -$e$ for backward compatibility with gSOAP 2.4 and earlier to adopt SOAP RPC encoding by default in case you want to develop a service that uses SOAP encoding. You can also use the gSOAP soapcpp2 compiler directives to specify SOAP encoding for individual operations, when desired.

4 Differences Between gSOAP Versions 2.1 (and Earlier) and 2.2

You should read this section only if you are upgrading from gSOAP 2.1 to 2.2 and later.

Run-time options and flags have been changed to enable separate recv/send settings for transport, content encodings, and mappings. The flags are divided into four classes: transport (IO), content encoding (ENC), XML marshalling (XML), and C/C++ data mapping (C). The old-style flags $\texttt{soap\_disable\_X}$ and $\texttt{soap\_enable\_X}$, where $\texttt{X}$ is a particular feature, are deprecated. See Section 9.12 for more details.
5 Differences Between gSOAP Versions 1.X and 2.X

You should read this section only if you are upgrading from gSOAP 1.X to 2.X.

gSOAP versions 2.0 and later have been rewritten based on versions 1.X. gSOAP 2.0 and later is thread-safe, while 1.X is not. All files in the gSOAP 2.X distribution are renamed to avoid confusion with gSOAP version 1.X files:

<table>
<thead>
<tr>
<th>gSOAP 1.X</th>
<th>gSOAP 2.X</th>
</tr>
</thead>
<tbody>
<tr>
<td>soapcpp</td>
<td>soapcpp2</td>
</tr>
<tr>
<td>soapcpp.exe</td>
<td>soapcpp2.exe</td>
</tr>
<tr>
<td>stdsoap.h</td>
<td>stdsoap2.h</td>
</tr>
<tr>
<td>stdsoap.c</td>
<td>stdsoap2.c</td>
</tr>
<tr>
<td>stdsoap.cpp</td>
<td>stdsoap2.cpp</td>
</tr>
</tbody>
</table>

Changing the version 1.X application codes to accommodate gSOAP 2.X does not require a significant amount of recoding. The change to gSOAP 2.X affects all functions defined in stdsoap2.c[pp] (the gSOAP runtime context API) and the functions in the sources generated by the gSOAP soapcpp2 compiler (the gSOAP RPC+marshalling API). Therefore, clients and services developed with gSOAP 1.X need to be modified to accommodate a change in the calling convention used in 2.X: In 2.X, all gSOAP functions (including the service operation proxy routines) take an additional parameter which is an instance of the gSOAP runtime context that includes file descriptors, tables, buffers, and flags. This additional parameter is always the first parameter of any gSOAP function.

The gSOAP runtime context is stored in a struct soap type. A struct was chosen to support application development in C without the need for a separate gSOAP implementation. An object-oriented approach with a class for the gSOAP runtime context would have prohibited the implementation of pure C applications. Before a client can invoke service operations or before a service can accept requests, a runtime context needs to be allocated and initialized. Three new functions are added to gSOAP 2.X:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>soap_init(struct soap *soap)</td>
<td>Initializes a context (required only once)</td>
</tr>
<tr>
<td>struct soap *soap_new()</td>
<td>Allocates, initializes, and returns a pointer to a runtime context</td>
</tr>
<tr>
<td>struct soap *soap_copy(struct soap *soap)</td>
<td>Allocates a new runtime context and copies contents of the context such that the new environment does not share any data with the original context</td>
</tr>
</tbody>
</table>

A context can be reused as many times as necessary and does not need to be reinitialized in doing so. A dynamically allocated context is deallocated with soap_free.

A new context is only required for each new thread to guarantee exclusive access to a new runtime context by each thread. For example, the following code stack-allocates the runtime context which is used for multiple service operation calls:

```c
int main()
{
```
struct soap soap;
...
soap_init(&soap); // initialize runtime context
...
soap_call_ns__method1(&soap, ...); // make a remote call
...
soap_call_ns__method2(&soap, ...); // make another remote call
...
soap_destroy(&soap); // remove deserialized class instances (C++ only)
soap_end(&soap); // clean up and remove deserialized data
soap_done(&soap); // detach context (last use and no longer in scope)
...
}

The runtime context can also be heap allocated:

int main()
{
    struct soap *soap;
    ...
    soap = soap_new(); // allocate and initialize runtime context
    if (!soap) // couldn't allocate: stop
        ...
    soap_call_ns__method1(soap, ...); // make a remote call
    ...
    soap_call_ns__method2(soap, ...); // make another remote call
    ...
    soap_destroy(soap); // remove deserialized class instances (C++ only)
    soap_end(soap); // clean up and remove deserialized data
    soap_free(soap); // detach and free runtime context
}

A service needs to allocate and initialize an context before calling soap.serve:

int main()
{
    struct soap soap;
    soap_init(&soap);
    soap.serve(&soap);
}

Or alternatively:

int main()
{
    soap.serve(soap_new());
}

The soap.serve dispatcher handles one request or multiple requests when HTTP keep-alive is enabled (with the SOAP_IO_KEEPALIVE flag see Section 19.11).
A service can use multi-threading to handle requests while running some other code that invokes service operations:

```c
int main()
{
    struct soap soap1, soap2;
    pthread_t tid;
    ...
    soap_init(&soap1);
    if (soap_bind(&soap1, host, port, backlog) < 0) exit(1);
    if (soap_accept(&soap1) < 0) exit(1);
    pthread_create(&tid, NULL, (void(*)(*)(void*))soap_serve, (void*)&soap1);
    ...
    soap_init(&soap2);
    soap_call_ns_method(&soap2, ...); // make a remote call
    ...
    soap_end(&soap2);
    ...
    pthread_join(tid, NULL); // wait for thread to terminate
    soap_end(&soap1); // release its data
}
```

In the example above, two runtime contexts are required. In comparison, gSOAP 1.X statically allocates the runtime context, which prohibits multi-threading (only one thread can invoke service operations and/or accept requests due to the single runtime context).

Section 7.2.4 presents a multi-threaded stand-alone Web Service that handles multiple SOAP requests by spawning a thread for each request.

### 6 Interoperability

gSOAP interoperability has been verified with the following SOAP implementations and toolkits:

- Apache 2.2
- Apache Axis
- ASP.NET
- Cape Connect
- Delphi
- easySOAP++
- eSOAP
- Frontier
- GLUE
- Iona XMLBus
- kSOAP
- MS SOAP
- Phalanx
- SIM
7 Quick User Guide

This user guide offers a quick way to get started with gSOAP. This section requires a basic understanding of the SOAP protocol and some familiarity with C and/or C++. In principle, SOAP clients and SOAP Web services can be developed in C and C++ with the gSOAP soapcpp2 compiler without a detailed understanding of the SOAP protocol when gSOAP client-server applications are built as an ensemble and only communicate within this group (i.e., meaning that you don’t have to worry about interoperability with other SOAP implementations). This section is intended to illustrate the implementation of gSOAP Web services and clients that connect to and interoperate with other SOAP implementations such as Apache Axis, SOAP::Lite, and .NET. This requires some details of the SOAP and WSDL protocols to be understood.

7.1 How to Build SOAP/XML Clients

In general, the implementation of a SOAP client application requires a stub (also called service proxy) for each service operation that the client invokes. The primary stub’s responsibility is to marshal the parameter data, send the request with the parameters to the designated SOAP service over the wire, to wait for the response, and to demarshal the parameter data of the response when it arrives. The client application invokes the stub routine for a service operation as if it would invoke a local function. To write a stub routine in C or C++ by hand is a tedious task, especially if the input and/or output parameters of a service operation contain elaborate data structures such as objects, structs, containers, arrays, and pointer-linked graph structures. Fortunately, the gSOAP wsdl2h WSDL parser tool and soapcpp2 stub/skeleton and serialization code generator tool automate the development of SOAP/XML Web service client and server applications.

The soapcpp2 tool generates the necessary gluing code (also called stubs and skeletons) to build web service clients and services. The input to the soapcpp2 tool consists of an service definition-annotated C/C++ header file. The header file can be generated from a WSDL (Web Service Description Language) documentation of a service with the gSOAP wsdl2h WSDL parser tool.

Consider the following command (entered at the Linux/Unix/Windows command line prompt):

```
> wsdl2h -o calc.h http://www.genivia.com/calc.wsdl
```

This generates the file Web service description calc.h in an annotated C++ header file. The WSDL
specification (possibly consisting of multiple imported WSDL files and XSD schema files) is mapped to C++ using C++ databindings for SOAP/XML. The generated header file contains data types and messages to operate the service, and meta information related to WSDL and XML schemas.

To generate a service definition header file to develop a pure C client application, use the `-c` option:

```
> wsdl2h -c -o calc.h http://www.genivia.com/calc.wsdl
```

For more details on the WSDL parser and its options, see 8.

The service definition `calc.h` header file is further processed by the gSOAP `soapcpp2` compiler to generate the gluing code’s logic to invoke the Web service from a client.

Looking into the file `calc.h` we see that the SOAP service methods are specified as function prototypes. For example, the `add` function to add two double floats:

```c
int ns2__add(double a, double b, double& result);
```

The `ns2__add` function uses an XML namespace prefix to distinguish it from operations defined in other namespaces, thus preventing name clashes. The convention to add an XML namespace prefix to the names of operations, types, and `struct` and `class` members is universally used by the gSOAP tools and automatically created by `wsdl2h`, but it is not mandatory when translating existing C/C++ types and operations to web services. Thus, the prefix notation can be omitted from type names defined in an header file with to run `soapcpp2` to create clients and services that exchange existing (i.e. application-native) data types.

These function prototypes are translated by the gSOAP `soapcpp2` tool to stubs and proxies for remote calls:

```
soapStub.h      annotated copy of the input definitions
soapH.h         serializers
soapC.cpp       serializers
soapClient.cpp  client calling stubs
```

Thus, the logic of the generated stub routines allow C and C++ client applications to seamlessly interact with existing SOAP Web services as illustrated by the client code example in the next section.

The input and output parameters of a SOAP service operation may be primitive data types or complex compound data types such as containers and pointer-based linked data structures. These are defined in the header file that is either generated by the WSDL parser or specified by hand. The gSOAP `soapcpp2` tool automatically generates XML serializers and XML deserializers for the data types to enable the generated stub routines to encode and decode the contents of the parameters of the service operations in SOAP/XML.

Note that the gSOAP `soapcpp2` tool also generates skeleton routines `soapServer.cpp` for each of the service operations specified in the header file. The skeleton routines can be readily used to implement one or more of the service operations in a new SOAP Web service. These skeleton routines are not used for building SOAP clients in C++, although they can be used to build mixed SOAP client/server applications (peer applications).
7.1.1 Example

The add service operation (declared in the calc.h file obtained with the wsdl2h tool in the previous section) adds two float values. The WSDL description of the service provides the endpoint to invoke the service operations and the XML namespace used by the operations:

Endpoint URL:  http://websrv.cs.fsu.edu/engelen/calcserver.cgi
XML namespace:  urn:calc

Each service operation has a SOAP action, which is an optional string to identify the operation (mainly used with WS-Addressing), an operation request message and a response message. The request and response messages for SOAP RPC-encoded services are simply represented by C functions with input and output parameters. For the add operation, the SOAP binding details are:

SOAP style:  RPC
SOAP encoding:  encoded
SOAP action:  "" (empty string)

This information is translated to the wsdl2h-generated header file with the service definitions. The calc.h header file for C++ generated by wsdl2h contains the following directives and declarations: (the actual contents may vary depending on the release version and the options used to control the output):

```c
//gsoap ns2 service name: calc  //gsoap ns2 service type: calcPortType  //gsoap ns2 service port: http://websrv.cs.fsu.edu/engelen/calcserver.cgi
//gsoap ns2 service namespace: urn:calc

//gsoap ns2 service method-protocol: add SOAP  //gsoap ns2 service method-style: add rpc
//gsoap ns2 service method-encoding: add http://schemas.xmlsoap.org/soap/encoding/
//gsoap ns2 service method-action: add ""
int ns2_add(double a, double b, double& result);
```

The other calculator operations are similar and elided here for clarity.

The //gsoap directives are required for the soapcpp2 tool to generate code that is compliant to the SOAP protocol. For this service the SOAP protocol with the common "RPC encoding style" is used. For //gsoap directive details, see Section 19.2.

The service operations are declared as function prototypes, with all non-primitive parameter types needed by the operation declared in the header file (all parameter types are primitive in this case).

The calculator add operation takes two double floats a and b, and returns the sum in result. By convention, all parameters are input parameters except the last. The last parameter is always the output parameter. A struct or class is used to wrap multiple output parameters, see also Section 7.1.9. This last parameter must be a pointer or reference. By contrast, the input parameters support pass by value or by pointer, but not pass by C++ reference.

The function prototype associated with a service operation always returns an int. The value indicates success (0 or equivalently SOAP_OK) or failure (any nonzero value). See Section 10.2 for the nonzero error codes.
The role of the namespace prefix (ns2__) in the service operation name in the function prototype declaration is discussed in detail in 7.1.2. Basically, a namespace prefix is added to a function name or type name with a pair of underscores, as in ns2__add, where ns2 is the namespace prefix and add is the service operation name. This mechanism ensures uniqueness of operations and types associated with a service.

It is strongly recommended to set the namespace prefix to a name of your choice. This avoids problems when running wsdl2h on multiple WSDLs where the sequence of prefixes ns1, ns2, and so on are arbitrarily assigned to the services. To choose a prefix name for all the operations and types of a service, say prefix c__ for the calculator service, add the following line to typemap.dat:

    c = "urn:calc"

and rerun wsdl2h. The typemap.dat configures wsdl2h to use specific bindings and data types for services. The result is that c__add is used to uniquely identify the operation rather than the more arbitrary name ns2__add.

Note on the use of underscores in names: a single underscore in an identifier name will be translated into a dash in XML, because dashes are more frequently used in XML compared to underscores, see Section 10.3.

Next, the gSOAP soapcpp2 tool is invoked from the command line to process the calc.h service definitions:

    > soapcpp2 calc.h

The tool generates the stub routines for the service operations. Stub routines can be invoked by a client program to invoke the remote service operations. The interface of the generated stub routine is identical to the function prototype in the calc.h service definition file, but with additional parameters to pass the gSOAP engine’s runtime context soap, an endpoint URL (or NULL for the default), and a SOAP action (or NULL for the default):

    int soap_call_c__add(struct soap *soap, char *URL, char *action, double a, double b, double& result);

This stub routine is saved in soapClient.cpp. The file soapC.cpp contains the serializer and deserializer routines for the data types used by the stub. You can use option -c for the soapcpp2 tool to generate pure C code, when needed.

Note: the soap parameter must be a valid pointer to a gSOAP runtime context. The URL can be set to override the default endpoint address (the endpoint defined by the WSDL). The URL can be set to override the default SOAP action.

The following example C/C++ client program uses the stub:

    #include "soapH.h"  // include all interfaces (library and generated)
    #include "calc.nsmap"  // import the generated namespace mapping table
    int main()
    {
        double sum;

    26
struct soap soap; // the gSOAP runtime context
soap_init(&soap); // initialize the context (only once!)
if (soap_call_c_add(&soap, NULL, NULL, 1.0, 2.0, &sum) == SOAP_OK)
    std::cout << "Sum = " << sum << std::endl;
else // an error occurred
    soap_print_fault(&soap, stderr); // display the SOAP fault message on the stderr stream
soap_destroy(&soap); // delete deserialized class instances (for C++)
soap_end(&soap); // remove deserialized data and clean up
soap_done(&soap); // detach the gSOAP context
return 0;
}

The call returns SOAP_OK (zero) on success and a nonzero error on failure. When an error occurred the fault is displayed with the soap_print_fault function. Use soap_sprint_fault(struct soap*, char *buf, size_t len) to print the error to a string, and use soap_stream_fault(struct soap*, std::ostream&) to send it to a stream (C++ only).

The following functions can be used to explicitly setup a gSOAP runtime context (struct soap):

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>soap_init(struct soap *soap)</td>
<td>Initializes a runtime context</td>
</tr>
<tr>
<td>soap_init1(struct soap *soap, soap_mode iomode)</td>
<td>Initializes a runtime context and set in/out mode flags</td>
</tr>
<tr>
<td>soap_init2(struct soap *soap, soap_mode imode, soap_mode omode)</td>
<td>Initializes a runtime context and set in/out mode flags</td>
</tr>
<tr>
<td>struct soap *soap_new()</td>
<td>Allocates, initializes, and returns a pointer to a runtime context</td>
</tr>
<tr>
<td>struct soap *soap_new1(soap_mode iomode)</td>
<td>Allocates, initializes, and returns a pointer to a runtime context and set in/out mode flags</td>
</tr>
<tr>
<td>struct soap *soap_new2(soap_mode imode, soap_mode omode)</td>
<td>Allocates, initializes, and returns a pointer to a runtime context and set in/out mode flags</td>
</tr>
<tr>
<td>struct soap *soap_copy(struct soap *soap)</td>
<td>Allocates a new runtime context and copies a context (deep copy, i.e. the new context does not share any data with the other context)</td>
</tr>
<tr>
<td>soap_done(struct soap *soap)</td>
<td>Reset, close communications, and remove callbacks</td>
</tr>
<tr>
<td>soap_free(struct soap *soap)</td>
<td>Reset and deallocate the context created with soap_new or soap_copy</td>
</tr>
</tbody>
</table>

A runtime context can be reused as many times as necessary for client-side remote calls and does not need to be reinitialized in doing so. A new context is required for each new thread to guarantee exclusive access to runtime context by threads. Also the use of any client calls within an active service method requires a new context.

The soapcpp2 code generator tool also generates a service proxy class for C++ client applications (and service objects for server applications) with the -i (or -j) option:
The proxy is defined in:

```
soapcalcProxy.h     client proxy class
soapcalcProxy.cpp   client proxy class
```

Note: without the -i option only old-style service proxies and objects are generated, which are less flexible and no longer recommended. Use -j as an alternative to -i to generate classes with the same functionality, but that are not inherited from `struct` soap and use a pointer to a `struct` soap engine context that can be shared with other proxy and service class instances. This choice is also important when services are chained, see Section 7.2.8.

The generated C++ proxy class initializes the gSOAP runtime context and offers the service interface as a collection of methods:

```cpp
#include "soapcalcProxy.h" // get proxy
#include "calc.nsmap" // import the generated namespace mapping table

int main()
{
    calcProxy calc(SOAP_XML_INDENT);
    double sum;
    if (calc.add(1.0, 2.0, sum) == SOAP_OK)
        std::cout << "Sum = " << sum << std::endl;
    else
        calc.soap_stream_fault(std::cerr);
    return calc.error; // nonzero when error
}
```

The proxy class is derived from the gSOAP runtime context structure `struct` soap and thus inherits (option -i) all state information of the runtime. The proxy constructor takes context mode parameters to initialize the context, e.g. `SOAP_XML_INDENT` in this example.

The code is compiled and linked with `soapcalcProxy.cpp`, `soapC.cpp`, and `stdsoap2.cpp` (or use `libgsoap++-a`).

The proxy class name is extracted from the WSDL content and may not always be in a short format. Feel free to change the entry

```
//gsoap ns2 service name: calc
```

and rerun `soapcpp2` to generate code that uses the new name.

When the example client application is invoked, a SOAP request is performed:

```
POST / engelen/calcserver.cgi HTTP/1.1
Host: websrv.cs.fsu.edu
User-Agent: gSOAP/2.7
Content-Type: text/xml; charset=utf-8
Content-Length: 464
Connection: close
```
SOAPAction: ""

<?xml version="1.0" encoding="UTF-8"?>
xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xmlns:xsd="http://www.w3.org/2001/XMLSchema"
xmns:="urn:calc">
</SOAP-ENV:Envelope>

The SOAP response message:

HTTP/1.1 200 OK
Date: Wed, 05 May 2010 16:02:21 GMT
Server: Apache/2.0.52 (Scientific Linux)
Content-Length: 463
Connection: close
Content-Type: text/xml; charset=utf-8

<?xml version="1.0" encoding="UTF-8"?>
xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xmlns:xsd="http://www.w3.org/2001/XMLSchema"
xmns:="urn:calc">
</SOAP-ENV:Envelope>

A client can invoke a sequence of service operations:

```c
#include "soapcalcProxy.h" // get proxy
#include "calc.nsmap" // import the generated namespace mapping table
int main()
{
    calcProxy calc(SOAP_IO_KEEPALIVE); // keep-alive improves connection performance
    double sum = 0.0;
    double val[] = 5.0, 3.5, 7.1, 1.2 ;
    for (int i = 0; i < 4; i++)
        if (calc.add(sum, val[i], sum))
```
In the above, no data is deallocated until the proxy is deleted. To deallocate deserialized data between the calls, use:

```c
for (int i = 0; i < 4; i++)
{
    if (calc.add(sum, val[i], sum))
        return calc.error;
    calc.destroy();
}
```

Deallocation is safe here, since the float values were copied and saved in `sum`. In other scenarios one must make sure data is copied or removed from the deallocation chain with:

```c
soap.unlink(struct soap *soap, const void *data)
```

which is to be invoked on each data item to be preserved, before destroying deallocated data. When the proxy is deleted, also all deserialized data is deleted. To delegate deletion to another runtime context for later removal, use:

```c
soap.delegate_deletion(struct soap *soap_from, struct soap *soap_to)
```

For example

```c
struct soap soap;
soap_init(&soap);
{ // create proxy
calcProxy calc;
    ... data generated ...
soap.delegate_deletion(&calc, &soap);
} // proxy deleted
    ... data used ...
soap_destroy(&soap);
soap_end(&soap);
soap_done(&soap);
```

In C (use `wsdl2h -c`) the example program would be written as:

```c
#include "soapH.h"
#include "calc.nsmap"
int main()
{
    struct soap soap;
    double sum = 0.0;
    double val[] = 5.0, 3.5, 7.1, 1.2 ;
```
```c
int i;
for (i = 0; i < 4; i++)
    soap_init1(&soap, SOAP_IO_KEEPALIVE);
    if (soap_call_c_add(&soap, NULL, NULL, sum, val[i], &sum))
        return soap.error;
    printf("Sum = %lg \n", sum);
    soap_end(&soap);
    soap_done(&soap);
return 0;
}
```

The code above is compiled and linked with soapClient.c, soapC.c, and stdsoap2.c (or use libgsoap.a).

### 7.1.2 XML Namespace Considerations

The declaration of the `ns2_add` function prototype (discussed in the previous section) uses the namespace prefix `ns2_` of the service operation namespace, which is distinguished by a pair of underscores in the function name to separate the namespace prefix from the service operation name. The purpose of a namespace prefix is to associate a service operation name with a service in order to prevent naming conflicts, e.g. to distinguish identical service operation names used by different services.

Note that the XML response of the service example uses a namespace prefix that may be different (e.g. `ns`) as long as it bound to the same namespace name `urn:calc` through the `xmlns:ns="urn:calc binding`. The use of namespace prefixes and namespace names is also required to enable SOAP applications to validate the content of SOAP messages. The namespace name in the service response is verified by the stub routine by using the information supplied in a namespace mapping table that is required to be part of gSOAP client and service application codes. The table is accessed at run time to resolve namespace bindings, both by the generated stub’s data structure serializer for encoding the client request and by the generated stub’s data structure deserializer to decode and validate the service response. The namespace mapping table should not be part of the header file input to the gSOAP soapcpp2 tool. Service details including namespace bindings may be provided with gSOAP directives in a header file, see Section 19.2.

The namespace mapping table is:

```c
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name"}
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"}, // MUST be first
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"}, // MUST be second
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"}, // MUST be third
    {"ns2", "urn:calc"}, // given by the service description
    {NULL, NULL} // end of table
};
```

The first four namespace entries in the table consist of the standard namespaces used by the SOAP 1.1 protocol. In fact, the namespace mapping table is explicitly declared to enable a programmer
to specify the SOAP encoding style and to allow the inclusion of namespace-prefix with namespace-name bindings to comply to the namespace requirements of a specific SOAP service. For example, the namespace prefix ns2, which is bound to urn:calc by the namespace mapping table shown above, is used by the generated stub routine to encode the add request. This is performed automatically by the gSOAP soapcpp2 tool by using the ns2 prefix of the ns2_add method name specified in the calc.h header file. In general, if a function name of a service operation, struct name, class name, enum name, or field name of a struct or class has a pair of underscores, the name has a namespace prefix that must be defined in the namespace mapping table.

The namespace mapping table will be output as part of the SOAP Envelope by the stub routine. For example:

```xml
xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/
xmns:xsi="http://www.w3.org/2001/XMLSchema-instance"
xmns:xsd="http://www.w3.org/2001/XMLSchema"
xmns:ns2="urn:calc"
SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">...
```

The namespace bindings will be used by a SOAP service to validate the SOAP request.

### 7.1.3 Example

The incorporation of namespace prefixes into C++ identifier names is necessary to distinguish service operations that share the same name but are provided by separate Web services and/or organizations. It avoids potential name clashes, while sticking to the C syntax. The C++ proxy classes generated with soapcpp2 -i (or -j) drop the namespace prefix from the method names.

The namespace prefix convention is also be applied to non-primitive types. For example, class names are prefixed to avoid name clashes when the same name is used by multiple XML schemas. This ensures that the XML databinding never suffers from conflicting schema content. For example:

```cpp
class e_Address // an electronic address from schema 'e'
{
    char *email;
    char *url;
};
class s_Address // a street address from schema 's'
{
    char *street;
    int number;
    char *city;
};
```

The namespace prefix is separated from the name of a data type by a pair of underscores (\_\_). An instance of e_Address is encoded by the generated serializer for this type as an Address element with namespace prefix e:
While an instance of s_Address is encoded by the generated serializer for this type as an Address element with namespace prefix s:

<s:Address xsi:type="s:Address">
  <street xsi:type="string">Technology Drive</street>
  <number xsi:type="int">5</number>
  <city xsi:type="string">Softcity</city>
</s:Address>

The namespace mapping table of the client program must have entries for e and s that refer to the XML Schemas of the data types:

```c
struct Namespace namespaces[] =
{
  ...
  {"e", "http://www.me.com/schemas/electronic-address"},
  {"s", "http://www.me.com/schemas/street-address"},
  ...
};
```

This table is required to be part of the client application to allow access by the serializers and deserializers of the data types at run time.

### 7.1.4 How to Generate C++ Client Proxy Classes

Proxy classes for C++ client applications are automatically generated by the gSOAP soapcpp2 tool, as was shown in Section 7.1.1.

There is a new and improved code generation capability for proxy classes, which is activated with the `soapcpp2 -i` (or `j`) option. These new proxy classes are derived from the soap structure, have a cleaner interface and offer more capabilities.

With C++, you can also use `wsdl2h` option `-qname` to generate the proxy in a C++ namespace `name`. This is very useful if you want to create multiple proxies for services by repeated use of `wsdl2h` and combine them in one code. Alternatively, you can run `wsdl2h` just once on all service WSDLs and have `soapcpp2` generate multiple proxies for you. The latter approach does not use C++ namespaces and may reduce the overall amount of code.

To illustrate the generation of a “standard” (old-style) proxy class, the calc.h header file example of the previous section is augmented with the appropriate directives to enable the gSOAP soapcpp2 tool to generate the proxy class. Directives are included in the generated header file by the `wsdl2h` WSDL importer:

```c
// Content of file "calc.h":
//gsoap ns2 service name: calc
//gsoap ns2 service port: http://websrv.cs.fsu.edu/ engelen/calcserver.cgi
```
The first three directives provide the service details, which is used to name the proxy class, the service location port (endpoint), and the XML namespace. The subsequent groups of three directives per method define the operation’s SOAP style (RPC) and encoding (SOAP encoded), and SOAP action string. These directives can be provided for each service operation when the SOAPAction is required, such as with SOAP1.1 RPC encoded and when WS-Addressing is used. In this example, the service protocol is set by default for all operations to use SOAP 1.1 RPC encoding. For //gsoap directive details, see Section 19.2.

The soapcpp2 tool takes this header file and generates a proxy soapcalcProxy.h with the following contents (not using option -i):

```cpp
#include "soapH.h"

class calc
{
    public:
        struct soap *soap;
        const char *endpoint;
        calc() { ... ;}
        ~calc() { ... ;}
        virtual int ns2__add(double a, double b, double& result) { return soap ? soap_call_ns2__add(soap, endpoint, NULL, a, b, result) : SOAP_EOM; };
        virtual int ns2__sub(double a, double b, double& result) { return soap ? soap_call_ns2__sub(soap, endpoint, NULL, a, b, result) : SOAP_EOM; };
        virtual int ns2__mul(double a, double b, double& result) { return soap ? soap_call_ns2__mul(soap, endpoint, NULL, a, b, result) : SOAP_EOM; };
    ... 
};
```
The gSOAP context and endpoint are declared public to enable access.

This generated proxy class can be included into a client application together with the generated namespace table as shown in this example:

```cpp
#include "soapcalcProxy.h" // get proxy
#include "calc.nsmap" // get namespace bindings
int main()
{
    calc s;
    double r;
    if (s.ns2_add(1.0, 2.0, r) == SOAP_OK)
        std::cout << r << std::endl;
    else
        soap_print_fault(s.soap, stderr);
    return 0;
}
```

The constructor allocates and initializes a gSOAP context for the instance.

You can use `soapcpp2` option `-n` together with `-p` to create a local namespaces table to avoid link conflicts when you need multiple namespace tables or need to combine multiple clients, see also Sections 9.1 and 19.36, and you can use a C++ code `namespace` to create a namespace qualified proxy class, see Section 19.35.

The `soapcpp2 -i` option to generate proxy classes derived from the base soap structure. In addition, these classes offer more functionality as illustrated in Section 7.1.1.

### 7.1.5 XSD Type Encoding Considerations

Many SOAP services require the explicit use of XML Schema types in the SOAP payload. The default encoding, which is also adopted by the gSOAP `soapcpp2` tool, assumes SOAP RPC encoding which only requires the use of types to handle polymorphic cases. Nevertheless, the use of XSD typed messages is advised to improve interoperability. XSD types are introduced with `typedef` definitions in the header file input to the gSOAP `soapcpp2` tool. The type name defined by a `typedef` definition corresponds to an XML Schema type (XSD type). For example, the following `typedef` declarations define various built-in XSD types implemented as primitive C/C++ types:

```cpp
// Contents of header file:
...
typedef char *xsd_string; // encode xsd:string value as the xsd:string schema type
typedef char *xsd_anyURI; // encode xsd:anyURI value as the xsd:anyURI schema type
typedef float xsd_float; // encode xsd:float value as the xsd:float schema type
typedef long xsd_int; // encode xsd:int value as the xsd:int schema type
typedef bool xsd_boolean; // encode xsd:boolean value as the xsd:boolean schema type
typedef unsigned long xsd_positiveInteger; // encode xsd:positiveInteger value as the xsd:positiveInteger schema type
...
```

This easy-to-use mechanism informs the gSOAP `soapcpp2` tool to generate serializers and deserializers that explicitly encode and decode the primitive C++ types as built-in primitive XSD types.
when the typedefed type is used in the parameter signature of a service operation (or when used nested within structs, classes, and arrays). At the same time, the use of typedef does not force any recoding of a C++ client or Web service application as the internal C++ types used by the application are not required to be changed (but still have to be primitive C++ types, see Section 11.3.2 for alternative class implementations of primitive XSD types which allows for the marshalling of polymorphic primitive types).

7.1.6 Example

Reconsider the calculator example, now rewritten with explicit XSD types to illustrate the effect:

```c++
// Contents of file "calc.h":
typedef double xsd_double;
int ns2_add(xsd_string a, xsd_double b, xsd_double &Result);
```

When processed by the gSOAP soapcpp2 tool it generates source code for the function `soap_call_ns2_add`, which is identical to the C-style SOAP call:

```c
int soap_call_ns2_add(struct soap *soap, char *URL, char *action, double a, double b, double & result);
```

The client application does not need to be rewritten and can still call the proxy using the “old” C-style function signatures. In contrast to the previous implementation of the stub however, the encoding and decoding of the data types by the stub has been changed to explicitly use the XSD types in the message payload.

For example, when the client application calls the proxy, the proxy produces a SOAP request with an `xsd:double` (the `xsi:type` is shown when the `soapcpp2 -t` option is used):

```xml
...<soap:Body>
s2:add
  <a xsi:type="xsd:string">1.0</a>
  <b xsi:type="xsd:string">2.0</b>
</ns2:add>
</soap:Body>...
```

The service response is:

```xml
...<soap:Body>
  <n:addResponse xmlns:n="urn:calc">
    <result xsi:type="xsd:double">3.0</result>
  </n:addResponse>
</soap:Body>...
```
The validation of this service response by the stub routine takes place by matching the namespace names (URIs) that are bound to the xsd namespace prefix. The stub also expects the `addResponse` element to be associated with URI urn:calc through the binding of the namespace prefix ns2 in the namespace mapping table. The service response uses namespace prefix n for the `addResponse` element. This namespace prefix is bound to the same URI urn:calc and therefore the service response is valid. When the XML is not well formed or does not pass validation, the response is rejected and a SOAP fault is generated. The validation level can be increased with the SOAP_XML_STRICT flag, but this is not advised for SOAP RPC encoded messaging.

7.1.7 How to Change the Response Element Name

There is no standardized convention for the response element name in a SOAP RPC encoded response message, although it is recommended that the response element name is the method name ending with "Response". For example, the response element of `add` is `addResponse`.

The response element name can be specified explicitly using a `struct` or `class` declaration in the header file. This name must be qualified by a namespace prefix, just as the operation name should use a namespace prefix. The `struct` or `class` name represents the SOAP response element name used by the service. Consequently, the output parameter of the service operation must be declared as a field of the `struct` or `class`. The use of a `struct` or a `class` for the service response is fully SOAP 1.1 compliant. In fact, the absence of a `struct` or `class` indicates to the soapcpp2 tool to automatically generate a `struct` for the response which is internally used by a stub.

7.1.8 Example

Reconsider the calculator service operation specification which can be rewritten with an explicit declaration of a SOAP response element as follows:

```c
// Contents of "calc.h":
typedef double xsd_double;
struct ns2_addResponse {xsd_double result;};
int ns2_add(xsd_string a, xsd_double b, struct ns2_addResponse &r);
```

The SOAP request and response messages are the same as before:

```xml
...<SOAP-ENV:Body>
 <ns2:add>
   <a xsi:type="xsd:string">1.0</a>
   <b xsi:type="xsd:string">2.0</b>
 </ns2:add>
</SOAP-ENV:Body>
...
```

The difference is that the service response is required to match the specified `addResponse` name and its namespace URI:
This use of a **struct** or **class** enables the adaptation of the default SOAP response element name and/or namespace URI when required.

### 7.1.9 How to Specify Multiple Output Parameters

The gSOAP `soapcpp2` tool compiler uses the convention that the **last parameter** of the function prototype declaration of a service operation in a header file is also the **only single output parameter** of the method. All other parameters are considered input parameters of the service operation. To specify a service operation with **multiple output parameters**, a **struct** or **class** must be declared for the service operation response, see also 7.1.7. The name of the **struct** or **class** must have a namespace prefix, just as the service method name. The fields of the **struct** or **class** are the output parameters of the service operation. Both the order of the input parameters in the function prototype and the order of the output parameters (the fields in the **struct** or **class**) is not significant. However, the SOAP 1.1 specification states that input and output parameters may be treated as having anonymous parameter names which requires a particular ordering, see Section 7.1.13.

### 7.1.10 Example

As an example, consider a hypothetical service operation `getNames` with a single input parameter `SSN` and two output parameters `first` and `last`. This can be specified as:

```cpp
// Contents of file "getNames.h"
int ns3_getNames(char *SSN, struct ns3_getNamesResponse {char *first; char *last;} &r);
```

The gSOAP `soapcpp2` tool takes this header file as input and generates source code for the function `soap_call ns3_getNames`. When invoked by a client application, the proxy produces the SOAP request:

```xml
...<SOAP-ENV:Envelope ... xmlns:ns3="urn:names" ...>
...<ns3:getNames>
<SSN>999 99 9999</SSN>
</ns3:getNames>
...
```

The response by a SOAP service could be:

```xml
...<m:getNamesResponse xmlns:m="urn:names">
```
where first and last are the output parameters of the getNames service operation of the service.

As another example, consider a service operation copy with an input parameter and an output parameter with identical parameter names (this is not prohibited by the SOAP 1.1 protocol). This can be specified as well using a response struct:

```c
// Content of file "copy.h":
int X_rox_.copy_name(char *name, struct X_rox_.copy_nameResponse {char *name;} &r);
```

The use of a struct or class for the service operation response enables the declaration of service operations that have parameters that are passed both as input and output parameters.

The gSOAP soapcpp2 compiler takes the copy.h header file as input and generates the soap_call_X_rox_.copy_name proxy. When invoked by a client application, the proxy produces the SOAP request:

```xml
...<SOAP-ENV:Envelope ... xmlns:X-rox="urn:copy" ...>
  ...
  <X-rox:copy-name>
    <name>SOAP</name>
  </X-rox:copy-name>
  ...
</X-rox:copy-name>
```

The response by a SOAP copy service could be something like:

```xml
...<m:copy-nameResponse xmlns:m="urn:copy">
  <name>SOAP</name>
</m:copy-nameResponse>
```

The name will be parsed and decoded by the proxy and returned in the name field of the struct X_rox_.copy_nameResponse &r parameter.

### 7.1.11 How to Specify Output Parameters With struct/class Compound Data Types

If the single output parameter of a service operation is a complex data type such as a struct or class it is necessary to specify the response element of the service operation as a struct or class at all times. Otherwise, the output parameter will be considered the response element (!), because of the response element specification convention used by gSOAP, as discussed in 7.1.7.

### 7.1.12 Example

This is best illustrated with an example. The Flighttracker service by ObjectSpace provides real time flight information for flights in the air. It requires an airline code and flight number as
parameters. The service operation name is `getFlightInfo` and the method has two string parameters: the airline code and flight number, both of which must be encoded as `xsd:string` types. The method returns a `getFlightResponse` response element with a `return` output parameter that is of complex type `FlightInfo`. The type `FlightInfo` is represented by a `class` in the header file, whose field names correspond to the `FlightInfo` accessors:

```c++
// Contents of file "flight.h":
typedef char *xsd_string;
class ns2_FlightInfo
{
    public:
        xsd_string airline;
        xsd_string flightNumber;
        xsd_string altitude;
        xsd_string currentLocation;
        xsd_string equipment;
        xsd_string speed;
    };
struct ns1_getFlightInfoResponse {ns2_FlightInfo return_};
int ns1_getFlightInfo(xsd_string param1, xsd_string param2, struct ns1_getFlightInfoResponse &r);
```

The response element `ns1_getFlightInfoResponse` is explicitly declared and it has one field: `return_` of type `ns2_FlightInfo`. Note that `return_` has a trailing underscore to avoid a name clash with the `return` keyword, see Section 10.3 for details on the translation of C++ identifiers to XML element names.

The gSOAP soapcpp2 compiler generates the `soap_call_ns1_getFlightInfo` proxy. Here is an example fragment of a client application that uses this proxy to request flight information:

```c++
struct soap soap;
...
soap_init(&soap);
...
soap_call_ns1_getFlightInfo(&soap, "testvger.objectspace.com/soap/servlet/rpcrouter",
    "urn:galdemo:flighttracker", "UAL", "184", r);
...
struct Namespace namespaces[] = {
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC","http://schemas.xmlsoap.org/soap/encoding/"},
    "{xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    "{xsd", "http://www.w3.org/2001/XMLSchema"},
    "{ns1", "urn:galdemo:flighttracker"},
    "{ns2", "http://galdemo.flighttracker.com"},
    {NULL, NULL}
};
```

When invoked by a client application, the proxy produces the SOAP request:

```
POST /soap/servlet/rpcrouter HTTP/1.1
Host: testvger.objectspace.com
```

40
The Flighttracker service responds with:

HTTP/1.1 200 ok
Date: Thu, 30 Aug 2001 00:34:17 GMT
Server: IBM_HTTP_Server/1.3.12.3 Apache/1.3.12 (Win32)
Set-Cookie: sesessionid=2GFVTDGC30D0LGRGU2L4HFA;Path=/
Cache-Control: no-cache="set-cookie,set-cookie2"
Expires: Thu, 01 Dec 1994 16:00:00 GMT
Content-Length: 861
Content-Type: text/xml; charset=utf-8
Content-Language: en

<?xml version="1.0" encoding="UTF-8"?>
    xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
    xmlns:xsd="http://www.w3.org/2001/XMLSchema"
    xmlns:ns1="urn:galdemo:flighttracker"
    xmlns:ns2="http://galdemo.flighttracker.com"
    SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
<SOAP-ENV:Body>
<ns1:getFlightInfoResponse xmlns:ns1="urn:galdemo:flighttracker"
    SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
<ns1:getFlightInfoResponse>
<return xmlns:ns2="http://galdemo.flighttracker.com" xsi:type="ns2:FlightInfo">
<equipment xsi:type="xsd:string">A320</equipment>
<airline xsi:type="xsd:string">UAL</airline>
<currentLocation xsi:type="xsd:string">188 mi W of Lincoln, NE</currentLocation>
<altitude xsi:type="xsd:string">37000</altitude>
<speed xsi:type="xsd:string">497</speed>
<flightNumber xsi:type="xsd:string">184</flightNumber>
</return>
</ns1:getFlightInfoResponse>
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>
The proxy returns the service response in variable \( r \) of type **struct** `ns1._getFlightInfoResponse` and this information can be displayed by the client application with the following code fragment:

```cpp
cout << r.return.equipment << " flight " << r.return.airline << r.return.flightNumber
<< " traveling " << r.return.speed << " mph " << " at " << r.return.altitude
<< " ft, is located " << r.return.currentLocation << endl;
```

This code displays the service response as:

A320 flight UAL184 traveling 497 mph at 37000 ft, is located 188 mi W of Lincoln, NE

Note: the flight tracker service is no longer available since 9/11/2001. It is kept in the documentation as an example to illustrate the use of structs/classes and response types.

### 7.1.13 How to Specify Anonymous Parameter Names

The SOAP RPC encoding protocol allows parameter names to be anonymous. That is, the name(s) of the output parameters of a service operation are not strictly required to match a client’s view of the parameters names. Also, the input parameter names of a service operation are not strictly required to match a service’s view of the parameter names. The gSOAP `soapcpp2` compiler can generate stub and skeleton routines that support anonymous parameters. Parameter names are implicitly anonymous by omitting the parameter names in the function prototype of the service operation. For example:

```cpp
// Contents of "calc.h":
typedef double xsd_double;
int ns2_add(xsd_string, xsd_double, xsd_double &);
```

To make parameter names explicitly anonymous on the receiving side (client or service), the parameter names should start with an underscore (`_`) in the function prototype in the header file. For example:

```cpp
// Contents of "calc.h":
typedef double xsd_double;
int ns2_add(xsd_string _a, xsd_double _b, xsd_double & _return);
```

In this example, the `_a`, `_b`, and `_return` are anonymous parameters. As a consequence, the service response to a request made by a client created with gSOAP using this header file specification may include any name for the output parameter in the SOAP payload. The input parameters may also be anonymous. This affects the implementation of Web services in gSOAP and the matching of parameter names by the service.

**Caution**: when anonymous parameter names are used, the order of the parameters in the function prototype of a service operation is significant.
7.1.14 How to Specify a Method with No Input Parameters

To specify a service operation that has no input parameters, just provide a function prototype with one parameter which is the output parameter (some C/C++ compilers will not compile and complain about an empty struct: use compile flag -DWITH_NOEMPTYSTRUCT to compile the generated code for these cases). This struct is generated by gSOAP to contain the SOAP request message. To fix this, provide one input parameter of type void* (gSOAP can not serialize void* data). For example:

```c
struct ns3_SoapService
{
    public:
    int ID;
    char *name;
    char *owner;
    char *description;
    char *homepageURL;
    char *endpoint;
    char *SOAPAction;
    char *methodName;
    char *SOAPAction;
    char *soapNamespace;
    char *serviceStatus;
    char *methodName;
    char *dateCreated;
    char *downloadURL;
    char *wsdlURL;
    char *instructions;
    char *contactEmail;
    char *serverImplementation;
};
struct ArrayOfSoapService {struct ns3_SoapService *ptr; int size;};
int ns_getAllSoapServices(void *return);
```

The ns_getAllSoapServices method has one void* input parameter which is ignored by the serializer to produce the request message.

Most C/C++ compilers allow empty structs and therefore the void* parameter is not required.

7.1.15 How to Specify a Method with No Output Parameters

To specify a service operation that has no output parameters, just define a function prototype with a response struct that is empty. For example:

```c
enum ns_event { off, on, stand_by };
int ns_signal(enum ns_event in, struct ns_signalResponse { } *out);
```

Since the response struct is empty, no output parameters are specified.

Some SOAP resources refer to SOAP RPC with empty responses as one way SOAP messaging. However, we refer to one-way massaging by asynchronous explicit send and receive operations as described in Section 7.3. The latter view of one-way SOAP messaging is also in line with Basic Profile 1.0.
7.2 How to Build SOAP/XML Web Services

The gSOAP soapcpp2 compiler generates skeleton routines in C++ source form for each of the service operations specified as function prototypes in the header file processed by the gSOAP soapcpp2 compiler. The skeleton routines can be readily used to implement the service operations in a new SOAP Web service. The compound data types used by the input and output parameters of service operations must be declared in the header file, such as structs, classes, arrays, and pointer-based data structures (graphs) that are used as the data types of the parameters of a service operation. The gSOAP soapcpp2 compiler automatically generates serializers and deserializers for the data types to enable the generated skeleton routines to encode and decode the contents of the parameters of the service operations. The gSOAP soapcpp2 compiler also generates a service operation request dispatcher routine that will serve requests by calling the appropriate skeleton when the SOAP service application is installed as a CGI application on a Web server.

7.2.1 Example

The following example specifies three service operations to be implemented by a new SOAP Web service:

```c
// Contents of file "calc.h"
typedef double xsd__double;
int ns__add(xsd__double a, xsd__double b, xsd__double &result);
int ns__sub(xsd__double a, xsd__double b, xsd__double &result);
int ns__sqrt(xsd__double a, xsd__double &result);
```

The add and sub methods are intended to add and subtract two double floating point numbers stored in input parameters `a` and `b` and should return the result of the operation in the `result` output parameter. The sqrt method is intended to take the square root of input parameter `a` and to return the result in the output parameter `result`. The `xsd__double` type is recognized by the gSOAP soapcpp2 compiler as the `xsd:double` XSD Schema data type. The use of `typedef` is a convenient way to associate primitive C types with primitive XML Schema data types.

To generate the skeleton routines, the gSOAP soapcpp2 compiler is invoked from the command line with:

```
> soapcpp2 calc.h
```

The compiler generates the skeleton routines for the `add`, `sub`, and `sqrt` service operations specified in the `calc.h` header file. The skeleton routines are respectively, `soap_serve_ns__add`, `soap_serve_ns__sub`, and `soap_serve_ns__sqrt` and saved in the file `soapServer.cpp`. The generated file `soapC.cpp` contains serializers and deserializers for the skeleton. The compiler also generates a service dispatcher: the `soap_serve` function handles client requests on the standard input stream and dispatches the service operation requests to the appropriate skeletons to serve the requests. The skeleton in turn calls the service operation implementation function. The function prototype of the service operation implementation function is specified in the header file that is input to the gSOAP soapcpp2 compiler.

Here is an example Calculator service application that uses the generated `soap_serve` routine to handle client requests:
// Contents of file "calc.cpp":
#include "soapH.h"
#include <math.h> // for sqrt()
int main()
{
    return soap_serve(soap_new()); // use the service operation request dispatcher
}
// Implementation of the "add" service operation:
int ns_add(struct soap *soap, double a, double b, double &result)
{
    result = a + b;
    return SOAP_OK;
}
// Implementation of the "sub" service operation:
int ns_sub(struct soap *soap, double a, double b, double &result)
{
    result = a - b;
    return SOAP_OK;
}
// Implementation of the "sqrt" service operation:
int ns_sqrt(struct soap *soap, double a, double &result)
{
    if (a >= 0)
    {
        result = sqrt(a);
        return SOAP_OK;
    }
    else
    {
        return soap_receiver_fault(soap, "Square root of negative number", "I can only take the square root of a non-negative number");
    }
}
// As always, a namespace mapping table is needed:
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name"}
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "urn:simple-calc"}, // bind "ns" namespace prefix
    {NULL, NULL}
};

Note that the service operations have an extra input parameter which is a pointer to the gSOAP runtime context. The implementation of the service operations MUST return a SOAP error code. The code SOAP_OK denotes success, while SOAP_FAULT denotes an exception with details that can be defined by the user. The exception description can be assigned to the soap->fault->faultstring string and details can be assigned to the soap->fault->detail string. This is SOAP 1.1 specific. SOAP 1.2 requires the soap->fault->SOAP_ENV_Reason and the soap->fault->SOAP_ENV_Detail strings to be assigned. Better is to use the soap_receiver_fault function that allocates a fault struct and sets the SOAP Fault string and details regardless of the SOAP 1.1 or SOAP 1.2 version used. The
The soap_receiver_fault function returns SOAP_FAULT, i.e. an application-specific fault. The fault exception will be passed on to the client of this service.

This service application can be readily installed as a CGI application. The service description would be:

- **Endpoint URL:** the URL of the CGI application
- **SOAP action:** "" (2 quotes)
- **Remote method namespace:** urn:simple-calc
- **Remote method name:** add
  - **Input parameters:** a of type xsd:double and b of type xsd:double
  - **Output parameter:** result of type xsd:double
- **Remote method name:** sub
  - **Input parameters:** a of type xsd:double and b of type xsd:double
  - **Output parameter:** result of type xsd:double
- **Remote method name:** sqrt
  - **Input parameter:** a of type xsd:double
  - **Output parameter:** result of type xsd:double or a SOAP Fault

The soapcpp2 compile generates a WSDL file for this service, see Section 7.2.9.

Unless the CGI application inspects and checks the environment variable SOAPAction which contains the SOAP action request by a client, the SOAP action is ignored by the CGI application. SOAP actions are specific to the SOAP protocol and provide a means for routing requests and for security reasons (e.g. firewall software can inspect SOAP action headers to grant or deny the SOAP request. Note that this requires the SOAP service to check the SOAP action header as well to match it with the service operation.)

The header file input to the gSOAP soapcpp2 compiler does not need to be modified to generate client stubs for accessing this service. Client applications can be developed by using the same header file as for which the service application was developed. For example, the soap_call_ns_add stub routine is available from the soapClient.cpp file after invoking the gSOAP soapcpp2 compiler on the calc.h header file. As a result, client and service applications can be developed without the need to know the details of the SOAP encoding used.

### 7.2.2 MSVC++ Builds

- Win32 builds need winsock2 (MS Visual C++ "ws2_32.lib") To do this in Visual C++ 6.0, go to “Project”, “settings”, select the “Link” tab (the project file needs to be selected in the file view) and add "ws2_32.lib" to the "Object/library modules" entry.
- Use files with extension .cpp only (don’t mix .c with .cpp).
- Turn pre-compiled headers off.
- When creating a new project, you can specify a custom build step to automatically invoke the gSOAP soapcpp2 compiler on a gSOAP header file. In this way you can incrementally build a new service by adding new operations and data types to the header file. To specify a custom build step, select the "Project" menu item "Settings" and select the header file in the File view pane. Select the "Custom Build" tab and enter 'soapcpp2.exe "$\{inputPath\}$' in
the "Command" pane. Enter 'soapStub.h soapH.h soapC.cpp soapClient.cpp soapServer.cpp'. Don’t forget to add the soapXYZProxy.h soapXYZObject.h files that are generated for C++ class proxies and server objects named XYZ. Click "OK". Run soapcpp2 once to generate these files (you can simply do this by selecting your header file and select "Compile"). Add the files to your project. Each time you make a change to the header file, the project sources are updated automatically.

- You may want to use the WinInet interface available in the mod_gsoap directory of the gSOAP package to simplify Internet access and deal with encryption, proxies, and authentication. API instructions are included in the source.

- For the PocketPC, run the wsdl2h WSDL parser with option -s to prevent the generation of STL code. In addition, time_t serialization is not supported, which means that you should add the following line to typemap.dat indicating a mapping of xsd_dateTime to char*: xsd_dateTime = | char* | char*.

### 7.2.3 How to Create a Stand-Alone Server

The deployment of a Web service as a CGI application is an easy means to provide your service on the Internet. However, the performance of CGI is not great. Also, gSOAP services can be run as stand-alone services on any port by utilizing the built-in HTTP and TCP/IP stacks. However, the preferred mechanism to deploy a service is through an Apache module or IIS module. These servers and modules are designed for server load balancing and access control.

To create a stand-alone service, only the main routine of the service needs to be modified as follows. Instead of just calling the soapServe routine, the main routine is changed into:

```c
int main()
{
    struct soap soap;
    int m, s; // master and slave sockets
    soap_init(&soap);
    m = soap_bind(&soap, "machine.genivia.com", 18083, 100);
    if (m < 0)
        soap_print_fault(&soap, stderr);
    else
    {
        fprintf(stderr, "Socket connection successful: master socket = %d\n", m);
        for (int i = 1; ; i++)
        {
            s = soap_accept(&soap);
            if (s < 0)
                { soap_print_fault(&soap, stderr);
                  break;
                }
            fprintf(stderr, "%d: accepted connection from IP=%d.%d.%d.%d socket=%d",
                      i, (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF, s);
            if (soap_serve(&soap) != SOAP_OK) // process RPC request
```
The `soap_serve` dispatcher handles one request or multiple requests when HTTP keep-alive is enabled (with the `SOAP_IO_KEEPALIVE` flag see Section 19.11).

The gSOAP functions that are frequently used for server-side coding are:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>soap_new()</code></td>
<td>Allocates and Initializes gSOAP context</td>
</tr>
<tr>
<td><code>soap_init(struct soap *soap)</code></td>
<td>Initializes a stack-allocated gSOAP context (required once)</td>
</tr>
<tr>
<td><code>soap_bind(struct soap *soap, char *host, int port, int backlog)</code></td>
<td>Returns master socket (backlog = max. queue size for requests). When host==NULL: host is the machine on which the service runs</td>
</tr>
<tr>
<td><code>soap_accept(struct soap *soap)</code></td>
<td>Returns slave socket</td>
</tr>
<tr>
<td><code>soap_end(struct soap *soap)</code></td>
<td>Clean up deserialized data (except class instances) and temporary data</td>
</tr>
<tr>
<td><code>soap_free_temp(struct soap *soap)</code></td>
<td>Clean up temporary data only</td>
</tr>
<tr>
<td><code>soap_destroy(struct soap *soap)</code></td>
<td>Clean up deserialized class instances (note: this function will be renamed with option -n</td>
</tr>
<tr>
<td><code>soap_done(struct soap *soap)</code></td>
<td>Reset and detach context: close master/slave sockets and remove callbacks</td>
</tr>
<tr>
<td><code>soap_free(struct soap *soap)</code></td>
<td>Detach and deallocate context (soap_new())</td>
</tr>
</tbody>
</table>

The `host` name in `soap_bind` may be NULL to indicate that the current host should be used.

The `soap.accept_timeout` attribute of the gSOAP runtime context specifies the timeout value for a non-blocking `soap_accept(&soap)` call. See Section 19.19 for more details on timeout management.

See Section 9.13 for more details on memory management.

A client application connects to this stand-alone service with the endpoint `machine.genivia.com:18083`. A client may use the `http://` prefix. When absent, no HTTP header is sent and no HTTP-based information will be communicated to the service.

### 7.2.4 How to Create a Multi-Threaded Stand-Alone Service

Stand-alone multi-threading a Web Service is essential when the response times for handling requests by the service are (potentially) long or when keep-alive is enabled, see Section 19.11. In case of long response times, the latencies introduced by the unrelated requests may become prohibitive for a successful deployment of a stand-alone service. When HTTP keep-alive is enabled, a client may not close the socket on time, thereby preventing other clients from connecting.

However, the preferred mechanism to deploy a service is through an Apache module or IIS module. These servers and modules are designed for server load balancing and access control.
The following example illustrates the use of threads to improve the quality of service by handling new requests in separate threads:

```c
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
int main(int argc, char **argv)
{
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soapserve(&soap); // serve request, one thread, CGI style
        soap_destroy(&soap); // dealloc C++ data
        soap_end(&soap); // dealloc data and clean up
    }
    else
    {
        soap.send_timeout = 60; // 60 seconds
        soap.recv_timeout = 60; // 60 seconds
        soap.accept_timeout = 3600; // server stops after 1 hour of inactivity
        soap.max_keep_alive = 100; // max keep-alive sequence
        void *process_request(void*);
        struct soap *tsoap;
        pthread_t tid;
        int port = atoi(argv[1]); // first command-line arg is port
        SOAP_SOCKET m, s;
        m = soap_bind(&soap, NULL, port, BACKLOG);
        if (!soap_valid_socket(m))
            exit(1);
        fprintf(stderr, "Socket connection successful %d\n", m);
        for (;;)
        {
            s = soap_accept(&soap);
            if (!soap_valid_socket(s))
            {
                if (soap.errnum)
                {
                    soap_print_fault(&soap, stderr);
                    exit(1);
                }
                fprintf(stderr, "server timed out\n");
                break;
            }
            tsoap = soap_copy(&soap); // make a safe copy
            pthread_create(&tid, NULL, (void*)(void*)process_request, (void*)tsoap);
        }
    }
}
```
void *process_request(void *soap) {
    pthread_detach(pthread_self());
    soap_serve((struct soap*)soap); // dealloc C++ data
    soap_destroy((struct soap*)soap); // dealloc data and clean up
    soap_end((struct soap*)soap); // dealloc data and clean up
    soap_done((struct soap*)soap); // detach soap struct
    free(soap);
    return NULL;
}

Note: the code does not wait for threads to join the main thread upon program termination.

The soap_serve dispatcher handles one request or multiple requests when HTTP keep-alive is set with SOAP_IO_KEEPALIVE. The soap.max_keep_alive value can be set to the maximum keep-alive calls allowed, which is important to avoid a client from holding a thread indefinitely. The send and receive timeouts are set to avoid (intentionally) slow clients from holding a socket connection too long. The accept timeout is used to let the server terminate automatically after a period of inactivity.

The following example uses a pool of servers to limit the machine’s resource utilization:

```c
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
#define MAXTHR (10) // Max. threads to serve requests
int main(int argc, char **argv) {
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soap_serve(&soap); // serve request, one thread, CGI style
        soap_destroy(&soap); // dealloc C++ data
        soap_end(&soap); // dealloc data and clean up
    }
    else {
        struct soap *soap_thr[MAXTHR]; // each thread needs a runtime context
        pthread_t tid[MAXTHR];
        int port = atoi(argv[1]); // first command-line arg is port
        SOAP_SOCKET m, s;
        int i;
        m = soap_bind(&soap, NULL, port, BACKLOG);
        if (!soap_valid_socket(m))
            exit(1);
        fprintf(stderr, "Socket connection successful %d\n", m);
        for (i = 0; i < MAXTHR; i++)
            soap_thr[i] = NULL;

```
for (;;)
{
    for (i = 0; i < MAX_THR; i++)
    {
        s = soap_accept(&soap);
        if (!soap_valid_socket(s))
        {
            if (soap.ermnum)
            {
                soap_print_fault(&soap, stderr);
                continue; // retry
            }
            else
            {
                fprintf(stderr, "Server timed out\n");
                break;
            }
        }
        fprintf(stderr, "Thread %d accepts socket %d connection from IP %d.%d.%d.%d\n", i, s, (soap.ip >> 24)&0xFF, (soap.ip >> 16)&0xFF, (soap.ip >> 8)&0xFF, soap.ip & 0xFF);
        if (!soap.thr[i]) // first time around
        {
            soap.thr[i] = soap_copy(&soap);
            if (!soap.thr[i])
                exit(1); // could not allocate
        }
        else // recycle soap context
        {
            pthread_join(tid[i], NULL);
            fprintf(stderr, "Thread %d completed\n", i);
            soap_destroy(soap.thr[i]); // deallocate C++ data of old thread
            soap_end(soap.thr[i]); // deallocate data of old thread
        }
        soap.thr[i]->socket = s; // new socket fd
        pthread_create(&tid[i], NULL, (void(*)(void*))soap_serve, (void*)soap.thr[i]);
    }
}
for (i = 0; i < MAX_THR; i++)
    if (soap.thr[i])
    {
        soap_done(soap.thr[i]); // detach context
        free(soap.thr[i]); // free up
    }
return 0;
}

The following functions can be used to setup a gSOAP runtime context (struct soap):
Function

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>soap_init(struct soap *soap)</td>
<td>Initializes a runtime context required only once</td>
</tr>
<tr>
<td>struct soap *soap_new()</td>
<td>Allocates, initializes and returns a pointer to a runtime context</td>
</tr>
<tr>
<td>struct soap *soap_copy(struct soap *soap)</td>
<td>Allocates a new runtime context (deep copy)</td>
</tr>
</tbody>
</table>

the argument context such that the new context does not share data with the argument context

soap_done(struct soap *soap) | Reset, close connections |

A new context is initiated for each thread to guarantee exclusive access to runtime contexts.

For clean termination of the server, the master socket can be closed and callbacks removed with soap_done(struct soap *soap).

The advantage of the code shown above is that the machine cannot be overloaded with requests, since the number of active services is limited. However, threads are still started and terminated. This overhead can be eliminated using a queue of requests (open sockets) as is shown in the code below.

```c
#include "soapH.h"
#include <pthread.h>
#define BACKLOG (100) // Max. request backlog
#define MAX_THR (10) // Size of thread pool
#define MAX_QUEUE (1000) // Max. size of request queue
SOAP_SOCKET queue[MAX_QUEUE]; // The global request queue of sockets
int head = 0, tail = 0; // Queue head and tail
void *process_queue(void*);
int enqueue(SOAP_SOCKET);
SOAP_SOCKET dequeue();
pthread_mutex_t queue_cs;
pthread_cond_t queue_cv;
int main(int argc, char **argv)
{
    struct soap soap;
    soap_init(&soap);
    if (argc < 2) // no args: assume this is a CGI application
    {
        soap_serve(&soap); // serve request, one thread, CGI style
        soap_destroy(&soap); // dealloc C++ data
        soap_end(&soap); // dealloc data and clean up
    }
    else
    {
        struct soap *soap_thr[MAX_THR]; // each thread needs a runtime context
        pthread_t tid[MAX_THR];
        int port = atoi(argv[1]); // first command-line arg is port
        SOAP_SOCKET m, s;
        int i;
        m = soap_bind(&soap, NULL, port, BACKLOG);
        if (!soap_valid_socket(m))
```
exit(1);
fprintf(stderr, "Socket connection successful %d\n", m);
pthread_mutex_init(&queue_cs, NULL);
pthread_cond_init(&queue_cv, NULL);
for (i = 0; i < MAX_THR; i++)
{
    soap_thr[i] = soap_copy(&soap);
    fprintf(stderr, "Starting thread %d\n", i);
    pthread_create(&tid[i], NULL, (void*)(*)process_queue, (void*)soap_thr[i]);
}
for (;;)
{
    s = soap_accept(&soap);
    if (!soap_valid_socket(s))
    {
        if (soap.ernum)
        {
            soap_print_fault(&soap, stderr);
            continue; // retry
        }
        else
        {
            fprintf(stderr, "Server timed out\n");
            break;
        }
    }
    fprintf(stderr, "Thread %d accepts socket %d connection from IP %d.%d.%d.%d\n", i, s, (soap.ip>>24)&0xFF, (soap.ip>>16)&0xFF, (soap.ip>>8)&0xFF, soap.ip&0xFF);
    while (enqueue(s) == SOAP_EOM)
    sleep(1);
}
for (i = 0; i < MAX_THR; i++)
{
    while (enqueue(SOAP_INVALID_SOCKET) == SOAP_EOM)
    sleep(1);
}
for (i = 0; i < MAX_THR; i++)
{
    fprintf(stderr, "Waiting for thread %d to terminate... ", i);
    pthread_join(tid[i], NULL);
    fprintf(stderr, "terminated\n");
    soap_done(soap_thr[i]);
    free(soap_thr[i]);
}
pthread_mutex_destroy(&queue_cs);
pthread_cond_destroy(&queue_cv);
soap_done(&soap);
return 0;
}

void *process_queue(void *soap)


```c
struct soap *tsoap = (struct soap*)soap;
for (;;) {
    tsoap->socket = dequeue();
    if (!soap_valid_socket(tsoap->socket))
        break;
    soap_server(tsoap);
    soap_destroy(tsoap);
    soap_end(tsoap);
    fprintf(stderr, "served\n");
}
return NULL;
}

int enqueue(SOAP_SOCKET sock)
{
    int status = SOAP_OK;
    int next;
    pthread_mutex_lock(&queue_cs);
    next = tail + 1;
    if (next >= MAX_QUEUE)
        next = 0;
    if (next == head)
        status = SOAP_EOM;
    else
    {
        queue[tail] = sock;
        tail = next;
        pthread_cond_signal(&queue_cv);
    }
    pthread_mutex_unlock(&queue_cs);
    return status;
}

SOAP_SOCKET dequeue()
{
    SOAP_SOCKET sock;
    pthread_mutex_lock(&queue_cs);
    while (head == tail)
    {
        pthread_cond_wait(&queue_cv, &queue_cs);
        sock = queue[head++];
        if (head >= MAX_QUEUE)
            head = 0;
        pthread_mutex_unlock(&queue_cs);
    }
    return sock;
}
```

Note: the plugin/threads.h and plugin/threads.c code can be used for a portable implementation. Instead of POSIX calls, use MUTEX_LOCK, MUTEX_UNLOCK, and COND_WAIT. These are wrappers for Win API calls or POSIX calls.
7.2.5 How to Pass Application Data to Service Methods

The `void *soap.user` field can be used to pass application data to service methods. This field should be set before the `soap.serve()` call. The service method can access this field to use the application-dependent data. The following example shows how a non-static database handle is initialized and passed to the service methods:

```c
{ ...  
    struct soap soap;  
    database_handle_type database_handle;  
    soap_init(&soap);    soap.user = (void*)database_handle;  
    ...  
    soap.serve(&soap);  // call the service operation dispatcher to handle request  
    ...  
}
int ns_myMethod(struct soap *soap, ...)  
{ ...  
    fetch((database_handle_type*)soap->user);  
    // get data ...  
    return SOAP_OK;  
}
```

Another way to pass application data around in a more organized way is accomplished with plugins, see Section 19.38.

7.2.6 Web Service Implementation Aspects

The same client header file specification issues apply to the specification and implementation of a SOAP Web service. Refer to

- 7.1.2 for namespace considerations.
- 7.1.5 for an explanation on how to change the encoding of the primitive types.
- 7.1.7 for a discussion on how the response element format can be controlled.
- 7.1.9 for details on how to pass multiple output parameters from a service operation.
- 7.1.11 for passing complex data types as output parameters.
- 7.1.13 for anonymizing the input and output parameter names.

7.2.7 How to Generate C++ Server Object Classes

Server object classes for C++ server applications are automatically generated by the gSOAP `soapcpp2` compiler.

There are two modes for generating classes. Use `soapcpp2` option `-i` (or `-j`) to generate improved class definitions where the class’ member functions are the service methods.
The older examples (without the use of soapcpp2 option -i and -j) use a C-like approach with globally defined service methods, which is illustrated here with a calculator example:

```c
// Content of file "calc.h":
//gsoap ns service name: Calculator
//gsoap ns service protocol: SOAP
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://www.cs.fsu.edu/~engelen/calc.cgi
//gsoap ns schema namespace: urn:calc
//gsoap ns service method-action: add ""
int ns_add(double a, double b, double &result);
int ns_sub(double a, double b, double &result);
int ns_mul(double a, double b, double &result);
int ns_div(double a, double b, double &result);
```

The first three directives provide the service name which is used to name the service class, the service location (endpoint), and the schema. The fourth directive defines the optional SOAPAction for the method, which is a string associated with SOAP 1.1 operations. Compilation of this header file with soapcpp2 -i creates a new file soapCalculatorObject.h with the following contents:

```c
#include "soapH.h"
class CalculatorObject : public soap
{
public:
    Calculator() { ... };
    ~Calculator() { ... };
    int serve() { return soapServe(this); };
};
```

This generated server object class can be included into a server application together with the generated namespace table as shown in this example:

```c
#include "soapCalculatorObject.h"    // get server object
#include "Calculator.nsmap"    // get namespace bindings
int main()
{
    CalculatorObject c;
    return c.serve(); // calls soapServe to serve as CGI application (using stdin/out)
}
```

You can use soapcpp2 option -n together with -p to create a local namespace table to avoid link conflict when you need to combine multiple tables and/or multiple servers, see also Sections 9.1
and 19.36, and you can use a C++ code namespace to create a namespace qualified server object class, see Section 19.35.

The example above serves requests over stdin/out. Use the bind and accept calls to create a stand-alone server to service inbound requests over sockets, see also 7.2.3.

A better alternative is to use the soapcpp2 option -i. The C++ proxy and server objects are derived from the soap context struct, which simplifies the proxy invocation and service operation implementations.

Compilation of the above header file with the gSOAP compiler soapcpp2 option -i creates new files soapCalculatorService.h and soapCalculatorService.cpp (rather than the C-style soapServer.cpp).

This generated server object class can be included into a server application together with the generated namespace table as shown in this example:

```cpp
#include "soapCalculatorService.h" // get server object
#include "Calculator.nsmap" // get namespace bindings
int main()
{
    soapCalculatorService c;
    return c.serve(); // calls soap.serve to serve as CGI application (using stdin/out)
}

// The 'add' service method (soapcpp2 w/ option -i)
int soapCalculatorService::add(double a, double b, double &result)
{
    result = a + b;
    return SOAP_OK;
}
... sub(), mul(), and div() implementations ...
```

Note that the service operation does not need a prefix (ns_) and there is no soap context struct passed to the service operation since the service object itself is the context (it is derived from the soap struct).

### 7.2.8 How to Chain C++ Server Classes to Accept Messages on the Same Port

When combining multiple services into one application, you can run wsdl2h on multiple WSDLs to generate the single all-inclusive service definitions header file. This header file is then processed with soapcpp2, for example to generate server class objects with option -i and -q to separate the service codes with C++ namespaces, see Section 19.35.

This works well, but the problem is that we end up with multiple classes, each for a collection of service operations the class is supposed to implement. But what if we need to provide one endpoint port for all services and operations? In this case invoking the server object's serve method is not sufficient, since only one service can accept requests while we want multiple services to listen to the same port.

The approach is to chain the service dispatchers, as shown below:

```cpp
    Abc::soapABCService abc; // generated with soapcpp2 -i -S -qAbc
    Uvw::soapUVWService uvw; // generated with soapcpp2 -i -S -qUvw
```
Xyz::soapXYZService xyz; // generated with soapcpp2 -i -S -qXyz
...
abc.bind(NULL, 8080, 100);
...
abc.accept();
// when using SSL: ssl_accept(&abc);
...
if(soap_begin_serve(&abc)) // available in 2.8.2 and later
    abc.soap_stream_fault(std::cerr);
elseif (abc.dispatch() == SOAP_NO_METHOD)
{
    soap_copy_stream(&uvw, &abc);
    if (uvw.dispatch() == SOAP_NO_METHOD)
    {
        soap_copy_stream(&xyz, &uvw);
        if (xyz.dispatch())
        {
            soap_send_fault(&xyz); // send fault to client
            xyz.soap_stream_fault(std::cerr);
        }
        soap_free_stream(&xyz); // free the copy
        xyz.destroy();
    }
else
    {
        soap_send_fault(&uvw); // send fault to client
        uvw.soap_stream_fault(std::cerr);
    }
    soap_free_stream(&uvw); // free the copy
    uvw.destroy();
}
else
    abc.soap_stream_fault(std::cerr);
    abc.destroy();
...

The dispatch method parses the SOAP/XML request and invokes the service operations, unless there is no matching operation and SOAP_NO_METHOD is returned. The soap_copy_stream ensures that the service object uses the currently open socket. The copied streams are freed with soap_free_stream. Do not enable keep-alive support, as the socket may stay open indefinitely afterwards as a consequence. Also, the dispatch method does not send a fault to the client, which has to be explicitly done with the soap_send_fault operation when an error occurs.

In this way, multiple services can be chained to accept messages on the same port. This approach also works with SSL for HTTPS services.

However, this approach is not recommended for certain plugins, because plugins must be registered with all service objects and some plugins require state information to be used across the service objects, which will add significantly to the complexity.

When plugin complications arise, it is best to have all services share the same context. This means that soapcpp2 option -j should be used instead of option -i. Each service class has a pointer member
to a soap struct context. This member pointer should point to the same soap context.

With option -j and -q the code to chain the services is as follows, based on a single struct soap engine context:

```c
struct soap *soap = soap_new();
Abc::soapABCService abc(soap); // generated with soapcpp2 -j -S -qAbc
Uvw::soapUVWService uvw(soap); // generated with soapcpp2 -j -S -qUvw
Xyz::soapXYZService xyz(soap); // generated with soapcpp2 -j -S -qXyz

soap_bind(soap, NULL, 8080, 100);
soap_accept(soap);
if (soap_begin_serve(soap))
    ... error
else if (abc.dispatch() == SOAP_NO_METHOD)
    {
        if (uvw.dispatch() == SOAP_NO_METHOD)
            {
                if (xyz.dispatch() == SOAP_NO_METHOD)
                    ... error
            }
    }
soap_destroy(soap);
soap_end(soap);
soap_free(soap); // only safe when abc, uvw, xyz are also deleted
```

### 7.2.9 How to Generate WSDL Service Descriptions

The gSOAP stub and skeleton compiler soapcpp2 generates WSDL (Web Service Description Language) service descriptions and XML Schema files when processing a header file. The tool produces one WSDL file for a set of service operations, which must be provided. The names of the function prototypes of the service operations must use the same namespace prefix and the namespace prefix is used to name the WSDL file. If multiple namespace prefixes are used to define service operations, multiple WSDL files will be created and each file describes the set of service operations belonging to a namespace prefix.

In addition to the generation of the ns.wsdl file, a file with a namespace mapping table is generated by the gSOAP compiler. An example mapping table is shown below:

```c
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", http://www.w3.org/*/XMLSchema"},
    {"ns", "http://tempuri.org"},
    {NULL, NULL}
};
```
This file can be incorporated in the client/service application, see Section 10.4 for details on namespace mapping tables.

To deploy a Web service, copy the compiled CGI service application to the designated CGI directory of your Web server. Make sure the proper file permissions are set (chmod 755 calc.cgi for Unix/Linux). You can then publish the WSDL file on the Web by placing it in the appropriate Web server directory.

The gSOAP soapcpp2 compiler also generates XML Schema files for all C/C++ complex types (e.g. structs and classes) when declared with a namespace prefix. These files are named ns.xsd, where ns is the namespace prefix used in the declaration of the complex type. The XML Schema files do not have to be published as the WSDL file already contains the appropriate XML Schema definitions.

To customize the WSDL output, it is essential to use //gsoap directives to declare the service name, the endpoint port, and namespace:

```
//gsoap ns service name: example
//gsoap ns service port: http://www.mydomain.com/example
//gsoap ns service namespace: urn:example
```

These are minimal settings. More details and settings for the service operations should be declared as well. See Section 19.2 for more details.

### 7.2.10 Example

For example, suppose the following methods are defined in the header file:

```c
typedef double xsd_double;
int ns_add(xsd_double a, xsd_double b, xsd_double &result);
int ns_sub(xsd_double a, xsd_double b, xsd_double &result);
int ns_sqrt(xsd_double a, xsd_double &result);
```

Then, one WSDL file will be created with the file name ns.wsdl that describes all three service operations:

```xml
<?xml version="1.0" encoding="UTF-8"?>
<definitions name="Service"
 xmlns="http://schemas.xmlsoap.org/wsdl/
 targetNamespace="http://location/Service.wsdl"
 xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/
 xmlns:SOAP="http://schemas.xmlsoap.org/wsdl/soap/
 xmlns:WSDL="http://schemas.xmlsoap.org/wsdl/
 xmlns:xsd="http://www.w3.org/2000/10/XMLSchema"
 xmlns:tns="http://location/Service.wsdl"
 xmlns:ns="http://tempuri.org">
<types>
  <schema
```
<complexType name="addResponse">
  <all>
    <element name="result" type="xsd:double" minOccurs="0" maxOccurs="1"/>
  </all>
  <anyAttribute namespace="##other"/>
</complexType>
<complexType name="subResponse">
  <all>
    <element name="result" type="xsd:double" minOccurs="0" maxOccurs="1"/>
  </all>
  <anyAttribute namespace="##other"/>
</complexType>
<complexType name="sqrtResponse">
  <all>
    <element name="result" type="xsd:double" minOccurs="0" maxOccurs="1"/>
  </all>
  <anyAttribute namespace="##other"/>
</complexType>
</schema>
</types>
<message name="addRequest">
  <part name="a" type="xsd:double"/>
  <part name="b" type="xsd:double"/>
</message>
<message name="addResponse">
  <part name="result" type="xsd:double"/>
</message>
<message name="subRequest">
  <part name="a" type="xsd:double"/>
  <part name="b" type="xsd:double"/>
</message>
<message name="subResponse">
  <part name="result" type="xsd:double"/>
</message>
<message name="sqrtRequest">
  <part name="a" type="xsd:double"/>
</message>
<message name="sqrtResponse">
  <part name="result" type="xsd:double"/>
</message>
<portType name="ServicePortType">
  <operation name="add">
    <input message="tns:addRequest"/>
    <output message="tns:addResponse"/>
  </operation>
  <operation name="sub">
    <input message="tns:subRequest"/>
  </operation>
</portType>
<operation message="tns:subResponse"/>
</operation>
<operation name="sqrt">
<input message="tns:sqrtRequest"/>
<output message="tns:sqrtResponse"/>
</operation>
</portType>
<binding name="ServiceBinding" type="tns:ServicePortType">
<SOAP:binding style="rpc" transport="http://schemas.xmlsoap.org/soap/http"/>
<operation name="add">
<SOAP:operation soapAction="http://tempuri.org#add"/>
<input>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</input>
<output>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</output>
</operation>
<operation name="sub">
<SOAP:operation soapAction="http://tempuri.org#sub"/>
<input>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</input>
<output>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</output>
</operation>
<operation name="sqrt">
<SOAP:operation soapAction="http://tempuri.org#sqrt"/>
<input>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</input>
<output>
<SOAP:body use="encoded" namespace="http://tempuri.org"
encodingStyle="http://schemas.xmlsoap.org/soap/encoding/"/>
</output>
</operation>
</binding>
<port name="ServicePort" binding="tns:ServiceBinding">
<SOAP:address location="http://location/Service.cgi"/>
</port>
</service>
</definitions>
The above uses all default settings for the service name, port, and namespace which should be set in the header file with \texttt{//gsoap} directives (Section 19.2).

7.2.11 How to Use Client Functionalities Within a Service

A gSOAP service implemented with CGI may make direct client calls to other services from within its service operations, without setting up a new context. A stand-alone service application must setup a new soap struct context, e.g. using \texttt{soap\_copy} and delete it after the call.

The server-side client call is best illustrated with an example. The following example is a more sophisticated example that combines the functionality of two Web services into one new SOAP Web service. The service provides a currency-converted stock quote. To serve a request, the service in turn requests the stock quote and the currency-exchange rate from two XMethods services (these services are no longer available by XMethods, but are used here as an example).

In addition to being a client of two XMethods services, this service application can also be used as a client of itself to test the implementation. As a client invoked from the command-line, it will return a currency-converted stock quote by connecting to a copy of itself installed as a CGI application on the Web to retrieve the quote after which it will print the quote on the terminal.

The header file input to the gSOAP soapcpp2 compiler is given below. The example is for illustrative purposes only (the XMethods services are not operational):

\begin{verbatim}
// Contents of file "quotex.h":
int ns1_getQuote(char *symbol, float &result); // XMethods delayed stock quote service operation
int ns2_getRate(char *country1, char *country2, float &result); // XMethods currency-exchange service operation
int ns3_getQuote(char *symbol, char *country, float &result); // the new currency-converted stock quote service
\end{verbatim}

The \texttt{quotex.cpp} client/service application source is:

\begin{verbatim}
// Contents of file "quotex.cpp":
#include "soapH.h" // include generated proxy and SOAP support
int main(int argc, char **argv)
{
 struct soap soap;
 float q;
 soap_init(&soap);
 if (argc <= 2)
   soap Serve(&soap);
 else if (soap call ns3_getQuote(&soap, "http://www.cs.fsu.edu\symbol{126}engelen/quotex.cgi", "," , argv[1], argv[2], q))
   soap print fault(&soap, stderr);
 else
   printf("\nCompany %s: %f (%s)\n", argv[1], q, argv[2]);
 return 0;
}
\end{verbatim}
int ns3__getQuote(struct soap *soap, char *symbol, char *country, float &result)
{
    float q, r;
    int socket = soap->socket; // save socket (stand-alone service only, does not support keep-alive)
    if (soap_call_ns1__getQuote(soap, "http://services.xmethods.net/soap", ",", symbol, &q) == 0 &&
        soap_call_ns2__getRate(soap, "http://services.xmethods.net/soap", NULL, "us", country, &r) == 0)
    {
        result = q*r;
        soap->socket = socket;
        return SOAP_OK;
    }
    soap->socket = socket;
    return SOAPFAULT; // pass soap fault messages on to the client of this app
}

/* Since this app is a combined client-server, it is put together with
one header file that describes all service operations. However, as a consequence we
have to implement the methods that are not ours. Since these implementations are
never called (this code is client-side), we can make them dummies as below. */

int ns1__getQuote(struct soap *soap, char *symbol, float &result)
{ return SOAP_NO_METHOD; } // dummy: will never be called
int ns2__getRate(struct soap *soap, char *country1, char *country2, float &result)
{ return SOAP_NO_METHOD; } // dummy: will never be called

struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"},
    {"ns1", "urn:xmethods-delayed-quotes"},
    {"ns2", "urn:xmethods-CurrencyExchange"},
    {"ns3", "urn:quotex"},
    {NULL, NULL}
};

To compile:

> soapcpp2 quotex.h
> c++ -o quotex.cgi quotex.cpp soapC.cpp soapClient.cpp soapServer.cpp stdsoap2.cpp -lsocket
    -lnsl

Note: under Linux and Mac OS X you can often omit the -l libraries.
The quotex.cgi executable is installed as a CGI application on the Web by copying it in the designated
directory specific to your Web server. After this, the executable can also serve to test the service.
For example

> quotex.cgi IBM uk

64
returns the quote of IBM in UK pounds by communicating the request and response quote from the CGI application. See http://xmethods.com/detail.html?id=5 for details on the currency abbreviations.

When combining clients and service functionalities, it is required to use one header file input to the compiler. As a consequence, however, stubs and skeletons are available for all service operations, while the client part will only use the stubs and the service part will use the skeletons. Thus, dummy implementations of the unused service operations need to be given which are never called.

Three WSDL files are created by gSOAP: ns1.wsdl, ns2.wsdl, and ns3.wsdl. Only the ns3.wsdl file is required to be published as it contains the description of the combined service, while the others are generated as a side-effect (and in case you want to develop these separate services).

### 7.3 Asynchronous One-Way Message Passing

SOAP RPC client-server interaction is synchronous: the client blocks until the server responds to the request. gSOAP also supports asynchronous one-way message passing and the interoperable synchronous one-way message passing over HTTP. The two styles are similar, but only the latter is interoperable and is compliant to Basic Profile 1.0. The interoperable synchronous one-way message passing style over HTTP is discussed in Section 7.4 below.

SOAP messaging routines are declared as function prototypes, just like service operations for SOAP RPC. However, the output parameter is a void type to indicate the absence of a return value.

For example, the following header file specifies an event message for SOAP messaging:

```c
int ns_event(int eventNo, void);
```

The gSOAP soapcpp2 tool generates the following functions in soapClient.cpp:

```c
int soap_send_ns_event(struct soap *soap, const char URL, const char action, int event);
int soap_recv_ns_event(struct soap *soap, struct ns_event *dummy);
```

The `soap_send_ns_event` function transmits the message to the destination URL by opening a socket and sending the SOAP encoded message. The socket will remain open after the send and has to be closed with `soap_closesock()` function. The open socket connection can also be used to obtain a service response, e.g. with a `soap_recv` function call.

The `soap_recv_ns_event` function waits for a SOAP message on the currently open socket (soap.socket) and fills the `struct ns_event` with the `ns_event` parameters (e.g. `int eventNo`). The `struct ns_event` is automatically created by gSOAP and is a mirror image of the `ns_event` parameters:

```c
struct ns_event
{
    int eventNo;
}
```

The gSOAP generated soapServer.cpp code includes a skeleton routine to accept the message. (The skeleton routine does not respond with a SOAP response message.)
The skeleton routine calls the user-implemented ns_event(struct soap *soap, int eventNo) routine (note the absence of the void parameter!).

As usual, the skeleton will be automatically called by the service operation request dispatcher that handles both the service operation requests (RPCs) and messages:

```c
int main()
{
    soap_serve(soap_new());
}

int ns_event(struct soap *soap, int eventNo)
{
    ... // handle event
    return SOAP_OK;
}
```

### 7.4 Implementing Synchronous One-Way Message Passing over HTTP

One-way SOAP message passing over HTTP as defined by the SOAP specification and Basic Profile 1.0 is synchronuous, meaning that the server must respond with an HTTP OK header (or HTTP 202 Accepted) and an empty body. To implement synchronuous one-way messaging, the same setup for asynchronous one-way messaging discussed in Section 7.3 is used, but with one simple addition at the client and server side for HTTP transfer.

At the server side, we have to return an empty HTTP OK response. Normally with one-way messaging the gSOAP engine closes the socket when the service operation is finished, which is not desirable for synchronous one-way message exchanges over HTTP: an HTTP response should be send. This is accomplished as follows. For each one-way operation implemented in C/C++, we replace the `return SOAP_OK` with:

```c
int ns_event(struct soap *soap, int eventNo)
{
    ... // handle event
    return soap_send_empty_response(soap, SOAP_OK); // SOAP_OK: return HTTP 202 ACCEPTED
}
```

At the client side, the empty response header must be parsed as follows:

```c
if (soap_send_ns_event(soap, eventNo) != SOAP_OK
    || soap_recv_empty_response(soap) != SOAP_OK)
   soap_print_fault(soap, stderr);
...
```

The synchronous (and asynchronous) one-way messaging supports HTTP keep-alive and chunking.

Note: soap_send_empty_response returns the error code SOAP_STOP to force the engine to stop producing a response message after the service operation completed, which allows soap_send_empty_response to be used with any service operation that should return HTTP 202.
7.5 How to Use the SOAP Serializers and Deserializers to Save and Load Application Data using XML Data Bindings

The gSOAP XML databindings for C and C++ allow a seamless integration of XML in C and C++ applications. Data can be serialized in XML and vice versa. WSDL and XML schema files can be converted to C or C++ definitions. C and C++ definitions can be translated to WSDL and schemas to support legacy ANSI C applications for example.

7.5.1 Mapping XML Schema to C/C++ with wsdl2h

Command:

```
> wsdl2h [options] XSD and WSDL files ...
```

The WSDL 1.1 and 2.0 standards are supported. If you have trouble with WSDL 2.0 please contact the author. The entire XML schema 1.1 standard is supported, except XPath expressions and assertions. This covers all of the following schema components with their optional [ attributes ] shown:

```xml
<xs:any [minOccurs, maxOccurs] >
<xs:anyAttribute>
<xs:all>
<xs:choice [minOccurs, maxOccurs] >
<xs:sequence [minOccurs, maxOccurs] >
<xs:group [name, ref] >
<xs:attributeGroup [name, ref] >
<xs:attribute [name, ref, type, use, default, fixed, form, wsdl:arrayType] >
<xs:element [name, ref, type, default, fixed, form, nillable, abstract, substitutionGroup, minOccurs, maxOccurs] >
<xs:simpleType [name] >
<xs:complexType [name] >
```

The supported facets are:

```xml
<xs:enumeration>
<xs:simpleContent>
<xs:complexContent>
<xs:list>
<xs:extension>
<xs:restriction>
<xs:length>
<xs:minLength>
<xs:maxLength>
<xs:minInclusive>
<xs:maxInclusive>
<xs:minExclusive>
<xs:maxExclusive>
<xs:precision> maps to float/double with C formatted output
<xs:scale> maps to float/double with C formatted output
```
<xs:totalDigits> maps to float/double with C formatted output
<xs:fractionDigits> maps to float/double with C formatted output
<xs:pattern> content not automatically validated yet
<xs:union> maps to string, content not validated yet

Other:

<xs:import>
<xs:include>
<xs:redefine>
<xs:annotation>

All primitive XSD types are supported (with the default mapping shown):

xsd:string maps to string (char*, wchar_t*, std::string, std::wstring)
xsd:boolean maps to bool (C++) or enum xsd::boolean (C)
xsd:float maps to float
xsd:double maps to double
xsd:decimal maps to string, or use "#import "custom/decimal.h"
xsd:precisionDecimal maps to string
xsd:duration maps to string, or use "#import "custom/duration.h"
xsd:dateTime maps to time_t, or use "#import "custom/struct_tm.h"
xsd:time maps to string
xsd:date maps to string
xsd:gYearMonth maps to string
xsd:gYear maps to string
xsd:gMonth maps to string
xsd:hexBinary maps to struct xsd::hexBinary
xsd:base64Binary maps to struct xsd::base64Binary
xsd:anyURI maps to string
xsd:QName maps to QName (string normalization rules apply)
xsd:NOTION maps to string

Note: string targets are defined in the typemap.dat file used by wsdl2h to map XSD types. This allows the use of char*, wchar_t*, std::string, and std::wstring string types for all XSD types mapped to strings.

All non-primitive XSD types are supported (with the default mapping shown):

xsd:normalizedString maps to string
xsd:token maps to string
xsd:language maps to string
xsd:IDREFS maps to string
xsd:ENTITIES maps to string
xsd:NMTOKEN maps to string
xsd:NMTOKENS maps to string
xsd:Name maps to string
xsd:NCName maps to string
xsd:ID maps to string
xsd:IDREF maps to string
xsd:ENTITY maps to string
xsd:integer maps to string
xsd:nonPositiveInteger maps to string
xsd:negativeInteger maps to string
xsd:long maps to LONG64
xsd:int maps to int
xsd:short maps to short
xsd:byte maps to byte
xsd:nonNegativeInteger maps to string
xsd:unsignedLong maps to ULONG64
xsd:unsignedInt maps to unsigned int
xsd:unsignedShort maps to unsigned short
xsd:unsignedByte maps to unsigned byte
xsd:positiveInteger maps to string
xsd:yearMonthDuration maps to string
xsd:dayTimeDuration maps to string
xsd:dateTimeStamp maps to string

There are several initialization flags to control XML serialization at runtime:

- XML content validation is enforced with SOAP_XML_STRICT.
- XML namespaces are supported, unless disabled with SOAP_XML_IGNORENS.
- XML exclusive canonicalization is enabled with SOAP_XML_CANONICAL.
- XML default xmlns="..." namespace bindings are used with SOAP_XML_DEFAULTNS.
- XML is indented for enhanced readability with SOAP_XML-indent.
- XML xsi:nil for NULL elements is serialized with SOAP_XML_NIL.

To obtain C and/or C++ type definitions for XML schema components, run wsdl2h on the schemas to generate a header file. This header file defines the C/C++ type representations of the XML schema components. The header file is then processed by the soapcpp2 tool to generate the serializers for these types. See Section 1.4 for an overview to use wsdl2h and soapcpp2 to map schemas to C/C++ types to obtain XML data bindings.

### 7.5.2 Mapping C/C++ to XML Schema with soapcpp2

To generate serialization code, execute:

```
> soapcpp2 [options] header_file.h
```

The following C/C++ types are supported in the header file:

```cpp
bool
enum, enum* ('enum*' indicates serialized as a bitmask)
(unsigned) char, short, int, long, long long (also LONG64), size_t
float, double, longdouble (#import "custom/long_double.h")
std::string, std::wstring, char[], char*, wchar_t*
```
_XML (a char* type to hold literal XML string content)
_QName (a char* type with normalized QName content of the form prefix:name)
struct, class (with single inheritance)
std::vector, std::list, std::deque, std::set (#import "import/stl.h")
union (requires preceding discriminant member field)
typedef
timeType
template<> class (requires begin(), end(), size(), and insert() methods)
void* (requires a preceding _type field to indicate the object pointed to)
struct xsd_hexBinary (special pre-defined type to hold binary content)
struct xsd_base64Binary (special pre-defined type to hold binary content)
struct tm (#import "custom/struct_tm.h")
struct timeval (#import "custom/struct_timeval.h")
pointers to any of the above (any pointer-linked structures are serializable, including cyclic graphs)
fixed-size arrays of all of the above

Additional features and potential limitations:

- A header file should not include any code statements, only data type declarations.
- Nested classes and nested types are unnested.
- Use #import "file.h" instead of #include to import other header files. The #include and #define directives are accepted, but deferred to the generated code.
- C++ namespaces are supported (must cover entire header file content)
- Optional DOM support can be used to store mixed content or literal XML content. Otherwise, mixed content may be lost. Use soapcpp2 option -d for DOM support.
- Types are denoted transient using the 'extern' qualifier, which prevents serialization as desired:

  extern class name; // class 'name' is not serialized
  struct name { extern char *name; int num; }; // 'name' is not serialized

- Only public members of a class can be serialized:

  class name { private: char *secret; }; // 'secret' is not serialized

- Types are denoted "volatile", which means that they are declared elsewhere in the source code and should not be redenclared in the generated code nor augmented by the soapcpp2 tool:

  volatile class name { ... }; // defined here just to generate the serializers

- struct/class members are serialized as attributes when qualified with '@':

  struct record { @char *name; int num; }; // attribute name, element num

- Strings with 8-bit content can hold ASCII (default) or UTF8. The latter is possible by enabling the SOAP_C_UTFSTRING flag. When enabled, all std::string and char* strings MUST contain UTF8.
The soapcpp2 tool generates serializers and deserializers for all wsdl2h-generated or user-defined data structures that are specified in the header file input to the compiler. The serializers and deserializers can be found in the generated soapC.cpp file. These serializers and deserializers can be used separately by an application without the need to build a full client or service application. This is useful for applications that need to save or export their data in XML or need to import or load data stored in XML format.

7.5.3 Serializing C/C++ Data to XML

We assume that the wsdl2h tool was used to map XML schema types to C/C++ data types. The soapcpp2 tool then generates the (de)serializers for the C/C++ types. You can also use soapcpp2 directly on a header file that declares annotated C/C++ data types to serialize.

The following attributes can be set to control the destination and source for serialization and deserialization:

<table>
<thead>
<tr>
<th>Variable</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>int soap.socket</td>
<td>socket file descriptor for input and output (or set to SOAP_INVALID_SOCKET)</td>
</tr>
<tr>
<td>ostream *soap.os</td>
<td>(C++ only) output stream used for send operations</td>
</tr>
<tr>
<td>istream *soap.is</td>
<td>(C++ only) input stream used for receive operations</td>
</tr>
<tr>
<td>int soap.sendfd</td>
<td>when soap.socket=SOAP_INVALID_SOCKET, this fd is used for send operations</td>
</tr>
<tr>
<td>int soap.recvfd</td>
<td>when soap.socket=SOAP_INVALID_SOCKET, this fd is used for receive operations</td>
</tr>
</tbody>
</table>

The following initializing and finalizing functions can be used:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>void soap_begin_send(struct soap*)</td>
<td>start a send/write phase</td>
</tr>
<tr>
<td>int soap_end_send(struct soap*)</td>
<td>flush the buffer</td>
</tr>
<tr>
<td>int soap_begin_recv(struct soap*)</td>
<td>start a rec/read phase (if an HTTP header is present, parse it first)</td>
</tr>
<tr>
<td>int soap_end_recv(struct soap*)</td>
<td>perform a id/href consistency check on deserialized data</td>
</tr>
</tbody>
</table>

These operations do not open or close the connections. The application should open and close connections or files and set the soap.socket, soap.os or soap.sendfd, soap.is or soap.recvfd streams or descriptors. When soap.socket<0 and none of the streams and descriptors are set, then the standard input and output will be used.

The following options are available to control serialization:

```c
soap_encodingStyle = NULL; // to remove SOAP 1.1/1.2 encodingStyle
soap_mode(soap, SOAP_XML_TREE); // XML without id-ref (no cycles!)
soap_mode(soap, SOAP_XML_GRAPH); // XML with id-ref (including cycles)
soap_set_namespaces(soap, struct Namespace *nsmap); // to set xmlns bindings
```

See also Section 9.12 to control the I/O buffering and content encoding such as compression and DIME encoding.

We assume that the wsdl2h tool was used to map XML schema types to C/C++ data types. The soapcpp2 tool then generates the (de)serializers for the C/C++ types.

To serialize data to an XML stream, two functions should be called to prepare for serialization of the data and to send the data, respectively. The first function, soap_serialize, analyzes pointers and
determines if multi-references are required to encode the data and if cycles are present the object graph. The second function, soap_put, produces the XML output on a stream.

The soap_serialize and soap_put (and both combined by soap_write) functions are statically generated specific to a data type. For example, soap_serialize_float(&soap, &d) is called to serialize an float value and soap_put_float(&soap, &d, "number", NULL) is called to output the floating point value in SOAP tagged with the name <number>. The soap_write_float(&soap, &d) conveniently combines the initialization of output, writing the data, and finalizing the output.

To initialize data, the soap_default function of a data type can be used. For example, soap_default_float(&soap, &d) initializes the float to 0.0. The soap_default functions are useful to initialize complex data types such as arrays, structs, and class instances. Note that the soap_default functions do not need the gSOAP runtime context as a first parameter.

The following table lists the type naming conventions used by gSOAP:

<table>
<thead>
<tr>
<th>Type</th>
<th>Type Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>char*</td>
<td>string</td>
</tr>
<tr>
<td>wchar_t*</td>
<td>wstring</td>
</tr>
<tr>
<td>char</td>
<td>byte</td>
</tr>
<tr>
<td>bool</td>
<td>bool</td>
</tr>
<tr>
<td>double</td>
<td>double</td>
</tr>
<tr>
<td>int</td>
<td>int</td>
</tr>
<tr>
<td>float</td>
<td>float</td>
</tr>
<tr>
<td>long</td>
<td>long</td>
</tr>
<tr>
<td>LONGLONG</td>
<td>LONGLONG (Win32)</td>
</tr>
<tr>
<td>long long</td>
<td>LONGLONG (Unix/Linux)</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
</tr>
<tr>
<td>time_t</td>
<td>time</td>
</tr>
<tr>
<td>unsigned char</td>
<td>unsignedByte</td>
</tr>
<tr>
<td>unsigned int</td>
<td>unsignedInt</td>
</tr>
<tr>
<td>unsigned long</td>
<td>unsignedLong</td>
</tr>
<tr>
<td>ULONG64</td>
<td>ULONG64 (Win32)</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>unsignedLONG64 (Unix/Linux)</td>
</tr>
<tr>
<td>unsigned short</td>
<td>unsignedShort</td>
</tr>
<tr>
<td>T[N]</td>
<td>Array&lt;T&gt; where T is the type name of T</td>
</tr>
<tr>
<td>T*</td>
<td>Pointer&lt;T&gt; where T is the type name of T</td>
</tr>
<tr>
<td>struct Name</td>
<td>Name</td>
</tr>
<tr>
<td>class Name</td>
<td>Name</td>
</tr>
<tr>
<td>enum Name</td>
<td>Name</td>
</tr>
</tbody>
</table>

Consider for example the following C code with a declaration of p as a pointer to a struct ns_.Person:

```c
struct ns_.Person { char *name; } *p;
```

To serialize p, its address is passed to the function soap_serializePointerTons_.Person generated for this type by the gSOAP soapcpp2 compiler:

```c
soap_serializePointerTons_.Person(&soap, &p);
```

The address of p is passed, so the serializer can determine whether p was already serialized and to discover co-referenced objects and cycles in graph data structures that require SOAP encod-
ing with id-ref serialization. To generate the output, the address of p is passed to the function

```
soap_put_PointerTons__Person(soap, &p, "ns:element-name", "ns:type-name");
```

or the shorthand for the above (without the xsi type):

```
soap_write_PointerTons__Person(soap, &p);
```

This produces:

```
<ns:element-name xmlns:SOAP-ENV="..." xmlns:SOAP-ENC="..." xmlns:ns="..."
... xsi:type="ns:type-name">
<name xsi:type="xsd:string">...</name>
</ns:element-name>
```

The serializer is initialized with the `soap_begin_send(soap)` function and closed with `soap_end_send(soap)`. All temporary data structures and data structures deserialized on the heap are destroyed with the `soap_destroy` and `soap_end` functions (in this order).

The `soap_done` function should be used to reset the context, i.e. the last use of the context. To detach and deallocate the context, use `soap_free`.

To remove the temporary data only and keep the deserialized data on the heap, use `soap_free_temp`. Temporary data structures are only created if the encoded data uses pointers. Each pointer in the encoded data has an internal hash table entry to determine all multi-reference parts and cyclic parts of the complete data structure.

You can assign an output stream to `soap.os` or a file descriptor to `soap.sendfd`. For example

```
soap.sendfd = open(file, O_RDWR|O_CREAT, S_IWUSR|S_IWUSR);
soap_serialize_PointerTons__Person(&soap, &p);
soap_begin_send(&soap);
soap_put_PointerTons__Person(&soap, &p, "ns:element-name", "ns:type-name");
soap_end_send(&soap);
```

The above can be abbreviated to

```
soap.sendfd = open(file, O_RDWR|O_CREAT, S_IWUSR|S_IWUSR);
soap_write_PointerTons__Person(&soap, &p);
```

The `soap_serialize` function is optional. It MUST be used when the object graph contains cycles. It MUST be called to preserve the logical coherence of pointer-based data structures, where pointers may refer to co-referenced objects. By calling `soap_serialize`, data structures shared through pointers are serialized only once and referenced in XML using id-refs attributes. The actual id-refs used depend on the SOAP encoding. To turn off SOAP encoding, remove or avoid using the SOAP-ENV and SOAP-ENC namespace bindings in the namespace table. In addition, the SOAP_XML_TREE and
SOAP_XML_GRAPH flags can be used to control the output by restricting serialization to XML trees or by enabling multi-ref graph serialization with id-ref attribution.

To save the data as an XML tree (with one root) without any id-ref attributes, use the SOAP_XML_TREE flag. The data structure MUST NOT contain pointer-based cycles.

To preserve the exact structure of the data object graph and create XML with one root, use the SOAP_XML_GRAPH output-mode flag (see Section 9.12). Use this flag and the soap_serialize function to prepare the serialization of data with in-line id-ref attributes. Using the SOAP_XML_GRAPH flag assures the preservation of the logical structure of the data.

For example, to encode the contents of two variables var1 and var2 that may share data through pointer structures, the serializers are called before the output routines:

```c
T1 var1;
T2 var2;
struct soap soap;
...
soap_init(&soap); // initialize
[soap_omode(&soap, flags)]; // set output-mode flags (e.g. SOAP_ENC_XML|SOAP_ENC_ZLIB)
soap_begin(&soap); // start new (de)serialization phase
soap_set_omode(&soap, SOAP_XML_GRAPH);
soap_serialize_Type1(&soap, &var1);
soap_serialize_Type2(&soap, &var2);
...
soap_socket = a_socket_file_descriptor; // when using sockets
soap.os = an_output_stream; // C++
soap.sendfd = an_output_file_descriptor; // C
soap_begin_send(&soap);
soap.put_Type1(&soap, &var1, "[namespace-prefix:element-name1", "[namespace-prefix:type-name1");
soap.put_Type2(&soap, &var2, "[namespace-prefix:element-name2", "[namespace-prefix:type-name2");
...
soap_end_send(&soap); // flush
soap_destroy(&soap); // remove deserialized C++ objects
soap_end(&soap); // remove deserialized data structures
soap_done(&soap); // finalize last use of this context
...
```

where Type1 is the type name of T1 and Type2 is the type name of T2 (see table above). The strings [namespace-prefix:type-name1] and [namespace-prefix:type-name2] describe the schema types of the elements. Use NULL to omit this type information.

For serializing class instances, method invocations MUST be used instead of function calls, for example obj.soap_serialize(&soap) and obj.soap_put(&soap, "elt", "type"). This ensures that the proper serializers are used for serializing instances of derived classes.

You can serialize a class instance to a stream as follows:

```c
struct soap soap;
myClass obj;
soap_init(&soap); // initialize
soap_begin(&soap); // start new (de)serialization phase
```
When you declare a soap struct pointer as a data member in a class, you can overload the `<<` operator to serialize the class to streams:

```cpp
ostream &operator<<(ostream &o, const myClass &e) {
    if (!e.soap)
        // error: need a soap struct to serialize (could use global struct) ...
    else {
        ostream *os = e.soap->os;
        e.soap->os = &o;
        soap_set_omode(e.soap, SOAP_XML_GRAPH); e.serialize(e.soap);
        soap_begin_send(e.soap);
        e.put(e.soap, "myClass", NULL);
        soap_end_send(e.soap);
        e.soap->os = os;
        soap_clr_omode(e.soap, SOAP_XML_GRAPH);
    }
    return o;
}
```

Of course, when you construct an instance you must set its soap struct to a valid context. Deserialized class instances with a soap struct data member will have their soap structs set automatically, see Section 9.13.2.

In principle, XML output for a data structure can be produced with `soap_put` without calling the `soap_serialize` function first. In this case, the result is similar to `SOAP_XML_TREE` which means that no id-refs are output. Cycles in the data structure will crash the serialization algorithm, even when the `SOAP_XML_GRAPH` is set.

Consider the following `struct`:

```c
// Contents of file "tricky.h":
struct Tricky {
    int *p;
    int n;
    int *q;
};
```

The following fragment initializes the pointer fields `p` and `q` to the value of field `n`:

```c
...
What is special about this data structure is that \( n \) is 'fixed' in the `Tricky` structure, and \( p \) and \( q \) both point to \( n \). The gSOAP serializers strategically place the id-ref attributes such that \( n \) will be identified as the primary data source, while \( p \) and \( q \) are serialized with ref/href attributes.

The resulting output is:

```xml
<Tricky xsi:type="Tricky">
  <p href="#2"/> <n xsi:type="int">1</n> <q href="#2"/> <r xsi:type="int">2</r>
</Tricky>
<id id="2" xsi:type="int">1</id>
```

which uses an independent element at the end to represent the multi-referenced integer, assuming the SOAP-ENV and SOAP-ENC namespaces indicate SOAP 1.1 encoding.

With the SOAP_XML_GRAPH flag the output is:

```xml
<Tricky xsi:type="Tricky">
  <p href="#2"/> <n id="2" xsi:type="int">1</n> <q href="#2"/></Tricky>
```

In this case, the XML is self-contained and multi-referenced data is accurately serialized. The gSOAP generated deserializer for this data type will be able to accurately reconstruct the data from the XML (on the heap).

### 7.5.4 Deserializing C/C++ Data from XML

We assume that the `wsdl2h` tool was used to map XML schema types to C/C++ data types. The `soapcpp2` tool then generates the (de)serializers for the C/C++ types. You can also use `soapcpp2` directly on a header file that declares annotated C/C++ data types to serialize.

To deserialize a data type from XML, the `soap_get` (or the simpler `soap_read`) function for the data type to be deserialized is used. The outline of a program that deserializes two variables `var1` and `var2` is for example:

```c
T1 var1;
T2 var2;
struct soap soap;
...
soap_init(&soap); // initialize at least once
[soap_imode(&soap, flags)]; // set input-mode flags
soap_begin(&soap); // begin new decoding phase
```
soap.is = an input stream; // C++
soap.recvfd = an input file descriptor; // C
soap.begin_recv(&soap); // if HTTP/MIME/DIME/GZIP headers are present, parse them
if (!soap.get_Type1(&soap, &var1, "\[namespace-prefix:]element-name1", "\[namespace-prefix:]type-name1"))
    ... error ...
if (!soap.get_Type2(&soap, &var2, "\[namespace-prefix:]element-name2", "\[namespace-prefix:]type-name1"))
    ... error ...

soap.end_recv(&soap); // check consistency of id/hrefs
soap.destroy(&soap); // remove deserialized C++ objects
soap.end(&soap); // remove deserialized data
soap.done(&soap); // finalize last use of the context

The strings [namespace-prefix]:type-name1 and [namespace-prefix]:type-name2 are the schema types of the elements and should match the xsi:type attribute of the receiving message. To omit the match, use NULL as the type. For class instances, method invocation can be used instead of a function call if the object is already instantiated, i.e. obj.soap.get(&soap, "...", "...").

The soap.begin call resets the deserializers. The soap.destroy and soap.end calls remove the temporary data structures and the decoded data that was placed on the heap.

To remove temporary data while retaining the deserialized data on the heap, the function soap.free_temp should be called instead of soap.destroy and soap.end.

One call to the soap.get_Type function of a type Type scans the entire input to process its XML content and to capture SOAP 1.1 independent elements (which contain multi-referenced objects). As a result, soap.error will set to SOAP_EOF. Also storing multiple objects into one file will fail to decode them properly with multiple soap.get calls. A well-formed XML document should only have one root anyway, so don’t save multiple objects into one file. If you must save multiple objects, create a linked list or an array of objects and save the linked list or array. You could use the soap.in_Type function instead of the soap.get_Type function. The soap.in_Type function parses one XML element at a time.

You can deserialize class instances from a stream as follows:

myClass obj;
struct soap soap;
soap.init(&soap); // initialize
soap.is = &cin; // read from cin
soap.begin_recv(&soap); // if HTTP header is present, parse it
if (soap.get_myClass(&soap, &obj, "myClass", NULL) == NULL)
    ... error ...
soap.end_recv(&soap); // check consistency of id/hrefs

soap.destroy(&soap); // remove deserialized C++ objects
soap.end(&soap); // remove deserialized data
soap.done(&soap); // finalize last use of the context

This can be abbreviated to:
myClass obj;
struct soap soap;
soap_init(&soap); // initialize
soap.is = &cin; // read from cin
if (soap_read_myClass(&soap, &obj, NULL) != SOAP_OK)
    ... error ...

soap_destroy(&soap); // remove deserialized C++ objects
soap_end(&soap); // remove deserialized data
soap_done(&soap); // finalize last use of the context

When declaring a soap struct pointer as a data member in a class, you can overload the >> operator to parse and deserialize a class instance from a stream:

    istream &operator>>(istream &i, myClass &e)
    {
        if (!e.soap)
            ... error: need soap struct to deserialize (could use global struct)...
        istream *is = e.soap->is;
        e.soap->is = &i;
        if (soap_read_myClass(e.soap, &e) != SOAP_OK)
            ... error ...
        e.soap->is = is;
        return i;
    }

7.5.5 Example

As an example, consider the following data type declarations:

    // Contents of file "person.h":
    typedef char *xsd_string;
    typedef char *xsd_Name;
    typedef unsigned int xsd_unsignedInt;
    enum ns_Gender {male, female};
    class ns_Address
    {
        public:
            xsd_string street;
            xsd_unsignedInt number;
            xsd_string city;
    };
    class ns_Person
    {
        public:
            xsd_Name name;
            enum ns_Gender gender;
            ns_Address address;
            ns_Person *mother;
            ns_Person *father;
    };
The following program uses these data types to write to standard output a data structure that contains the data of a person named "John" living at Downing st. 10 in London. He has a mother "Mary" and a father "Stuart". After initialization, the class instance for "John" is serialized and encoded in XML to the standard output stream using gzip compression (requires the Zlib library, compile sources with -DWITH_GZIP):

```c
#include "soapH.h"
int main()
{
struct soap soap;
ns._Person mother, father, john;
mother.name = "Mary";
mother.gender = female;
mother.address.street = "Downing st.";
mother.address.number = 10;
mother.address.city = "London";
mother.mother = NULL;
mother.father = NULL;
father.name = "Stuart";
father.gender = male;
father.address.street = "Main st.";
father.address.number = 5;
father.address.city = "London";
father.mother = NULL;
father.father = NULL;
john.name = "John";
john.gender = male;
john.address = mother.address;
john.mother = &mother;
john.father = &father;
soap_init(&soap);
soap_omode(&soap, SOAP_ENC_ZLIB|SOAP_XML_GRAPH); // see 9.12
soap_begin(&soap);
soap_begin_send(&soap);
john.soap_serialize(&soap);
john.soap_put(&soap, "johnnie", NULL);
soap_end_send(&soap);
soap_destroy(&soap);
soap_end(&soap);
soap_done(&soap);
}
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "urn:person"}, // Namespace URI of the "Person" data type
    {NULL, NULL}
};```
The header file is processed and the application compiled on Linux/Unix with:

```
> soapcpp2 person.h
> c++ -DWITH_GZIP -o person person.cpp soapC.cpp stdsoap2.cpp -lsocket -lxnet -lnsl -lz
```

(Depending on your system configuration, the libraries libsocket.a, libxnet.a, libnsl.a are required. Compiling on Linux typically does not require the inclusion of those libraries.) See 19.27 for details on compression with gSOAP.

Running the person application results in the compressed XML output:

```xml
    xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
    xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
    xmlns:xsd="http://www.w3.org/2001/XMLSchema"
    xmlns:ns="urn:person"
    SOAP-ENV:encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
  <name xsi:type="xsd:Name">John</name>
  <gender xsi:type="ns:Gender">male</gender>
  <address xsi:type="ns:Address">
    <street id="3" xsi:type="xsd:string">Dowling st.</street>
    <number xsi:type="unsignedInt">10</number>
    <city id="4" xsi:type="xsd:string">London</city>
  </address>
  <mother xsi:type="ns:Person">
    <name xsi:type="xsd:Name">Mary</name>
    <gender xsi:type="ns:Gender">female</gender>
    <address xsi:type="ns:Address">
      <street href="#3"/>
      <number xsi:type="unsignedInt">5</number>
      <city href="#4"/>
    </address>
  </mother>
  <father xsi:type="ns:Person">
    <name xsi:type="xsd:Name">Stuart</name>
    <gender xsi:type="ns:Gender">male</gender>
    <address xsi:type="ns:Address">
      <street xsi:type="xsd:string">Main st.</street>
      <number xsi:type="unsignedInt">13</number>
      <city href="#4"/>
    </address>
  </father>
</johnnie>
```

The following program fragment decodes this content from standard input and reconstructs the original data structure on the heap:

```c
#include "soapH.h"

int main()
{
    struct soap soap;
```
ns_._Person *mother, *father, *john = NULL;
soap_init(&soap);
soap_imode(&soap, SOAP_ENC_ZLIB); // optional: gzip is detected automatically
soap_begin(&soap);
if ((john = soap_getns_._Person(&soap, NULL, NULL, NULL)) == NULL)
    ... error ...
mother = john->mother;
father = john->father;
...
soap_end_recv(&soap);
soap_free_temp(&soap); // Clean up temporary data but keep deserialized data

struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC","http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi","http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd","http://www.w3.org/2001/XMLSchema"},
    {"ns","urn:person"}, // Namespace URI of the “Person” data type
    {NULL, NULL}
};

It is REQUIRED to either pass NULL to the soap_get routine, or a valid pointer to a data structure that can hold the decoded content. If the data john was already allocated then it does not need to be allocated again as the following demonstrates. The following program fragment decodes the SOAP content in a struct ns_._Person allocated on the stack:

#include "soapH.h"
int main()
{
    struct soap soap;
    ns_._Person *mother, *father, john;
    soap_init(&soap);
    soap_default_ns_._Person(&soap, &john);
    soap_imode(&soap, SOAP_ENC_ZLIB); // optional
    soap_begin(&soap);
    soap_begin_recv(&soap);
    if (soap_getns_._Person(&soap, &john, "johnnie", NULL) == NULL)
        ... error ...
    ...
}

struct Namespace namespaces[] =
    ...

Note the use of soap_default_ns_._Person. This routine is generated by the gSOAP soapcpp2 tool and assigns default values to the fields of john.
7.5.6 Serializing and Deserializing Class Instances to Streams

C++ applications can define appropriate stream operations on objects for (de)serialization of objects on streams. This is best illustrated with an example. Section 7.5.3 gives details on serializing types in general. Consider the class

```cpp
class ns_person
{
    public:
        char *name;
        struct soap *soap; // we need this, see below
    ns_person();
    ~ns_person();
};
```

The `struct soap` member is used to bind the instances to a gSOAP context for (de)serialization. We use the gSOAP soapcpp2 compiler from the command prompt to generate the class (de)serializers (assuming that `person.h` contains the class declaration):

```bash
> soapcpp2 person.h
```

gSOAP generates the (de)serializers and an instantiation function for the class `soap_new_ns_person(struct soap *soap, int num)` to instantiate one or more objects and associate them with a gSOAP context for deallocation with `soap_destroy(soap)`. To instantiate a single object, omit the `num` parameter or set to -1. To instantiate an array of objects, set `num` ≥ 0.

```cpp
#include "soapH.h"
#include "ns.nsmap"
...
struct soap *soap = soap_new();
ns_person *p = soap_new_ns_person(soap);
...
cout << p; // serialize p in XML
...
in >> p; // parse XML and deserialize p
...
soap_destroy(soap); // deletes p too
soap_end(soap);
soap_done(soap);
```

The stream operations are implemented as follows

```cpp
ostream &operator<<(ostream &o, const ns_person &p)
{
    if (!p.soap)
        return o; // need a gSOAP context to serialize
    p.soap->os = &o;
    soap_omode(p.soap, SOAP_XML_TREE); // XML tree or graph
    p.soap_serialize(p.soap);
    soap_begin_send(p.soap);
    if (p.soap_put(p.soap, "person", NULL)
```

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|| soap_end_send(p.soap))
; // handle I/O error
return o;
}

istream &operator>>(istream &i, ns_person &p)
{
if (!p.soap)
    return o; // need a gSOAP context to parse XML and deserialize
p.soap->is = &i;
if (soap_begin_recv(p.soap)
    || p.soap_in(p.soap, NULL, NULL)
    || soap_end_recv(p.soap))
; // handle I/O error
return i;
}

7.5.7 How to Specify Default Values for Omitted Data

The gSOAP soapcpp2 compiler generates soap_default functions for all data types. The default values of the primitive types can be easily changed by defining any of the following macros in the stdsoap2.h file:

#define SOAP_DEFAULT_bool
#define SOAP_DEFAULT_byte
#define SOAP_DEFAULT_double
#define SOAP_DEFAULT_float
#define SOAP_DEFAULT_int
#define SOAP_DEFAULT_long
#define SOAP_DEFAULT_LONG64
#define SOAP_DEFAULT_short
#define SOAP_DEFAULT_string
#define SOAP_DEFAULT_time
#define SOAP_DEFAULT_unsignedByte
#define SOAP_DEFAULT_unsignedInt
#define SOAP_DEFAULT_unsignedLong
#define SOAP_DEFAULT_unsignedLONG64
#define SOAP_DEFAULT_unsignedShort
#define SOAP_DEFAULT_wstring

Instead of adding these to stdsoap2.h, you can also compile with option -DWITH_SOAPDEFS_H and include your definitions in file userdefs.h. The absence of a data value in a receiving SOAP message will result in the assignment of a default value to a primitive type upon deserialization.

Default values can also be assigned to individual struct and class fields of primitive type. For example,

struct MyRecord
{
    char *name = "Unknown";
    int value = 9999;
}
```
enum Status { active, passive } status = passive;
```

Default values are assigned to the fields on receiving a SOAP/XML message in which the data values are absent.

Because method requests and responses are essentially structs, default values can also be assigned to method parameters. The default parameter values do not control the parameterization of C/C++ function calls, i.e. all actual parameters must be present when calling a function. The default parameter values are used in case an inbound request or response message lacks the XML elements with parameter values. For example, a Web service can use default values to fill-in absent parameters in a SOAP/XML request:

```c
int ns_login(char *uid = "anonymous", char *pwd = "guest", bool granted);
```

When the request message lacks uid and pwd parameters, e.g.:

```
<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
 xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/
 xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
 xmlns:xsd="http://www.w3.org/2001/XMLSchema"
 xmlns:ns="http://tempuri.org">
 <SOAP-ENV:Body encodingStyle="http://schemas.xmlsoap.org/soap/encoding/">
  <ns:login/>
 </SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```

then the service uses the default values. In addition, the default values will show up in the SOAP/XML request and response message examples generated by the gSOAP compiler.

### 8 The `wsdl2h` WSDL and Schema Importer

The `wsdl2h` tool is an advanced application that converts one or more WSDLs to C/C++. It can also be used without WSDLs to convert XML schemas (XSD files) to C/C++ to implement XML data bindings in C and C++.

The creation of C and C++ applications from one of more WSDL service descriptions is a two-step process.

To convert a WSDL to C++, use:

```
> wsdl2h file.wsdl
```

to generate a C++ header file `file.h`. This generated header file is a Web service specification that contains the parameter types and service function definitions in an understandable format in C++ (or ANSI C as shown below). Web service operations are represented as function prototypes.
Schema types are represented by semantically equivalent C/C++ types that are convenient and natural to use in a C/C++ application. The generated header file also contains various annotations related to the Web service properties defined in the WSDL.

To generate ANSI C, use option -c:

```
> wsdl2h -c file.wsd1
```

Multiple WSDL specifications can be processed at once and saved to one file with the -o option:

```
> wsdl2h -o file.h file1.wsd1 file2.wsd1 file3.wsd1
```

You can retrieve WSDLs from one of more URLs:

```
> wsdl2h -o file.h http://www.example.com/example.wsd1
```

To convert XML schemas to C or C++ XML data binding code, use:

```
> wsdl2h -o file.h file1.xsd file2.xsd file3.xsd
```

The `wsdl2h`-generated header file `file.h` is processed by the `soapcpp2` tool to auto-generate the advanced data binding logic to convert the C/C++ data to XML and vice versa at runtime for your SOAP/XML application.

To process a gSOAP header file `file.h` (generated by `wsdl2h`) to generate advanced XML data bindings for C++, use:

```
> soapcpp2 -i -limport file.h
```

When the header file `file.h` was generated for C++, then this command generates a couple of C++ source files (more details will follow in Section 9) that implement XML encoders for the data binding. Option `-i` generates client proxy objects and service objects to invoke and serve SOAP/XML operations, respectively. Option `-limport` sets the import directory for imported files from the package’s `import`, such as `stlvector.h` for STL vector serialization support.

When the header file `file.h` was generated for ANSI C, then the above command generates a couple of C files that implement XML encoders, client stubs for remote invocation, and service skeletons for service operations.

Consider for example the following commands to implement a C++ client of a service:

```
> wsdl2h -o calc.h http://www.genivia.com/calc.wsd1
...
> soapcpp2 -i -limport calc.h
```

The first command generates `calc.h` from the WSDL at the specified URL. The header file is then processed by the `soapcpp2` tool to generate the proxies (and service objects that we will not use) for the client application.

The C++ client application uses the auto-generated `soapcalcProxy.h` class and `calc.nsmap` XML namespace table to access the Web service. Both need to be `#include`d in your source. Then compile and link the `soapcalcProxy.cpp`, `soapC.cpp` and `stdsoap2.cpp` sources to complete the build.
8.1 wsdl2h Options

The wsdl2h tool is an advanced XML data binding tool for converting WSDLs and XML schemas (XSD files) to C or C++. The tool takes WSDL and/or XSD files or URLs and converts these to a C or C++ specification in one easy-to-read C/C++ header file. **The header file is not intended to be included in your code directly!** It should be converted by soapcpp2 to generate the logic for the data bindings. It can however be safely converted by a documentation tool such as Doxygen to analyze and represent the service operations and data in a convenient layout. To this end, the header file is self-explanatory.

The wsdl2h tool generates only one file, the header file that includes all of the information obtained from all WSDL and schema files provided to the tool at the command-line prompt. The default output file name of wsdl2h is the first WSDL/schema input file name but with extension .h instead of .wsdl (or .xsd). When an input file is absent or a WSDL file from a Web location is accessed, the header output will be produced on the standard output unless option -o is used to direct the output to a file.

The wsdl2h command-line options are:
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>-a</td>
<td>generate indexed struct names for local elements with anonymous types</td>
</tr>
<tr>
<td>-b</td>
<td>generate C source code</td>
</tr>
<tr>
<td>-c</td>
<td>use DOM to populate xs:any and xsd:anyType elements</td>
</tr>
<tr>
<td>-d</td>
<td>don’t qualify enum names</td>
</tr>
<tr>
<td>-e</td>
<td>This option is for backward compatibility with gSOAP 2.4.1 and earlier. The option does not produce code that conforms to WS-I Basic Profile 1.0a.</td>
</tr>
<tr>
<td>-f</td>
<td>generate flat C++ class hierarchy for schema extensions</td>
</tr>
<tr>
<td>-g</td>
<td>generate global top-level element declarations</td>
</tr>
<tr>
<td>-h</td>
<td>print help information</td>
</tr>
<tr>
<td>-l path</td>
<td>use path to locate source files for #import</td>
</tr>
<tr>
<td>-i</td>
<td>don’t import (advanced option)</td>
</tr>
<tr>
<td>-j</td>
<td>don’t generate SOAP_ENV__Header and SOAP_ENV__Detail definitions</td>
</tr>
<tr>
<td>-k</td>
<td>don’t generate SOAP_ENV__Header mustUnderstand qualifiers</td>
</tr>
<tr>
<td>-l</td>
<td>include license information in output</td>
</tr>
<tr>
<td>-m</td>
<td>use xsd.h module to import primitive types</td>
</tr>
<tr>
<td>-N name</td>
<td>use name for service prefixes to produce a service for each binding</td>
</tr>
<tr>
<td>-n name</td>
<td>use name as the base namespace prefix name instead of ns</td>
</tr>
<tr>
<td>-o file</td>
<td>output to file</td>
</tr>
<tr>
<td>-P</td>
<td>don’t create polymorphic types inherited from xsd__anyType</td>
</tr>
<tr>
<td>-p</td>
<td>create polymorphic types inherited from base xsd__anyType</td>
</tr>
<tr>
<td>-q name</td>
<td>use name for the C++ namespace of all declarations</td>
</tr>
<tr>
<td>-r host[:port[:uid:pwd]]</td>
<td>connect via proxy host, port, and proxy credentials</td>
</tr>
<tr>
<td>-r uid:pwd</td>
<td>connect with authentication credentials (digest auth requires SSL)</td>
</tr>
<tr>
<td>-R</td>
<td>generate REST operations for REST bindings in the WSDL</td>
</tr>
<tr>
<td>-s</td>
<td>don’t generate STL code (no std::string and no std::vector)</td>
</tr>
<tr>
<td>-t file</td>
<td>use type map file instead of the default file typemap.dat</td>
</tr>
<tr>
<td>-u</td>
<td>don’t generate unions</td>
</tr>
<tr>
<td>-v</td>
<td>verbose output</td>
</tr>
<tr>
<td>-W</td>
<td>suppress warnings</td>
</tr>
<tr>
<td>-w</td>
<td>always wrap response parameters in a response struct</td>
</tr>
<tr>
<td>-x</td>
<td>don’t generate _XML any/anyAttribute extensibility elements</td>
</tr>
<tr>
<td>-y</td>
<td>generate typedef synonyms for structs and enums</td>
</tr>
<tr>
<td>-z1</td>
<td>compatibility with 2.7.6e: generate pointer-based arrays</td>
</tr>
<tr>
<td>-z2</td>
<td>compatibility with 2.7.15: qualify element/attribute referenced members</td>
</tr>
<tr>
<td>-z3</td>
<td>compatibility up to 2.8.16 to 2.8.7: qualify element/attribute references</td>
</tr>
<tr>
<td>-z4</td>
<td>compatibility up to 2.8.11: don’t generate union structs in std::vector</td>
</tr>
<tr>
<td>-z5</td>
<td>compatibility up to 2.8.15</td>
</tr>
<tr>
<td>-z6</td>
<td>compatibility up to 2.8.17</td>
</tr>
<tr>
<td>-z</td>
<td>don’t generate _USCORE (replace with UNICODE_x005f)</td>
</tr>
</tbody>
</table>

Note: see README.txt in the wsdl directory for the latest information on installation and options to of the wsdl2h WSDL/schema importer.

### 8.2 Customizing Data Bindings With The typemap.dat File

The typemap.dat file for the wsdl2h tool is intended to customize or optimize the type bindings by mapping schema types to C/C++ types. It contains custom XML Schema to C/C++ type bindings.
and a few bindings are defined for convenience.

Here is an example typemap file's content:

```
# This file contains custom definitions of the XML Schema types and
# C/C++ types for your project, and XML namespace prefix definitions.
# The wsdl2h WSDL importer consults this file to determine bindings.

[  
  // This comment will be included in the generated .h file
  // You can include any additional declarations, includes, imports, etc.
  // within [ ] sections. The brackets MUST appear at the start of a line
]
# XML namespace prefix definitions can be provided to override the
# default choice of ns1, ns2, ... prefixes. For example:

i = "http://www.soapinterop.org/

s = "http://www.soapinterop.org/xsd"
```

Type bindings can be provided to bind XML schema types to C/C++ types for your project. Type bindings have four parts:

```
prefix_type = declaration | use | ptr-use
```

where 'prefix_type' is the C/C++-translation of the schema type, 'declaration' introduces the C/C++ type in the header file, the optional 'use' specifies how the type is used directly, and the optional 'ptr-use' specifies how the type is used as a pointer type.

```
# Example XML Schema and C/C++ type bindings:

xsd_int = | int
xsd_string = | char* | char*
xsd_boolean = enum xsd_boolean false_, true_; | enum xsd_boolean
xsd_base64Binary = class xsd_base64Binary unsigned char * _ptr; int _size; ; |
xsd_base64Binary | xsd_base64Binary

# You can extend structs and classes with member data and functions.
# For example, adding a constructor to ns_myClass: ns_myClass = $ ns_myClass();
# The general form is # class_name = $ member;
```

The i and s prefixes are declared such that the header file output by the WSDL parser will use these to produce C/C++ code. XML Schema types are associated with an optional C/C++ type declaration, a use reference, and a pointer-use reference. The pointer-use reference of the xsd_byte type for example, is int* because char* is reserved for strings.

When a type binding requires only the usage to be changed, the declaration part can be given by an elipsis ..., as in:

```
prefix_type = ... | use | ptr-use
```
This ensures that the wsdl2h-generated type definition is preserved, while the use and ptr-use are remapped.

This method is useful to serialize dynamic types in C, where elements types int XML carry the xsi:type attribute.

The following example illustrates an "any" type mapping for the ns:sometype XSD type in a schema. This type will be replaced with a "any" type wrapper that supports dynamic serialization with xsi:type:

```
struct any {
    int __type;
    void *__item;
}
```

```
xsd_anyType = ... | struct any | struct any
```

where __type and __item are used to (de)serialize any data type in the wrapper, including base and its derived types based on xsi:type attribution.

To support complexType extensions that are dynamically bound in C code, i.e. polymorphic types based on inheritance hierarchies, we can redeclare the base type of a hierarchy as a wrapper type and use the __type to serialize base or derived types. One addition is needed to support base type serialization without the use of xsi:type attributes. The absence of this attribute requires the serialization of the base type.

Basically, we need to be able to both handle a base type and its extensions as per schema extensibility. Say base type ns:base is a complexType that is extended by several other complexTypes. To implement dynamic binding in C to serialize the base type and derived types, we define:

```
[  
    struct __ns__base  
    {  
        int __type;  
        void *__item;  
        struct ns__base *__self;  
    }  
]  
```

```
ns__base = ... | struct __ns__base | struct __ns__base
```

The __self field refers to the element tag (basically a struct member name) to which the ns:base type is associated. So for example, we see in the soapcpp2-generated output:

```
struct ns__data  
{  
    ...  
        struct __ns__base name;  
    ...  
};
```

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where _item represents name when the __ns_base is serialized with an xsi:type attribute, and __self represents name when the __ns_base is serialized without an xsi:type attribute. Therefore, the dynamic binding defaults to struct ns_base *__self when no dynamic type information in XML is available.

Additional data and function members can be provided to extend a generated struct or class. Class and struct extensions are of the form:

```
prefix_type = $ member-declaration
```

For example, to add a constructor and destructor to class myns_record:

```
  myns_record = $ myns_record(); myns_record = $ ~myns_record();
```

Type remappings can be given to map a type to another type:

```
  prefix_type1 == prefix_type2
```

which replaces prefix_type1 by prefix_type2 in the wsdl2h output. For example:

```
  SOAP_ENC_boolean == xsd_boolean
```

where SOAP_ENC_boolean is mapped to xsd_boolean, which in turn may be mapped to a C enum xsd_boolean type or C++ bool type.

9 Using the soapcpp2 Compiler and Code Generator

The soapcpp2 compiler and code generator is invoked from the command line and optionally takes the name of a header file as an argument or, when the file name is absent, parses the standard input:

```
> soapcpp2 [aheaderfile.h]
```

where aheaderfile.h is a C/C++ header file generated by wsdl2h or developed manually to specify the SOAP/XML service operations as function prototypes and the C/C++ data types to be auto-mapped to XML.

The soapcpp2 tool produces C/C++ source files. These files are used to implement SOAP/XML clients and services, and to implement the advanced XML data binding logic to convert C/C++ data into XML and vice versa.

The type of files generated by soapcpp2 are:
Both client and service applications are developed from a header file that specifies the service operations. If client and service applications are developed with the same header file, the applications are guaranteed to be compatible because the stub and skeleton routines use the same serializers and deserializers to encode and decode the parameters. Note that when client and service applications are developed together, an application developer does not need to know the details of the internal SOAP encoding used by the client and service.

The soapClientLib.cpp and soapServerLib.cpp can be used to build (dynamic) client and server libraries. The serialization routines are local (static) to avoid link symbol conflicts. You must create a separate library for SOAP Header and Fault handling, as described in Section 19.36.

The following files are part of the gSOAP package and are required to build client and service applications:

<table>
<thead>
<tr>
<th>File Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>stdsoap2.h</td>
<td>Header file of stdsoap2.cpp runtime library</td>
</tr>
<tr>
<td>stdsoap2.c</td>
<td>Runtime C library with XML parser and run-time support routines</td>
</tr>
<tr>
<td>stdsoap2.cpp</td>
<td>Runtime C++ library identical to stdsoap2.c</td>
</tr>
</tbody>
</table>

### 9.1 soapcpp2 Options

The soapcpp2 source-to-source compiler supports the following command-line options:
<table>
<thead>
<tr>
<th>Option</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>-1</td>
<td>Generate SOAP 1.1 bindings</td>
</tr>
<tr>
<td>-2</td>
<td>Generate SOAP 1.2 bindings</td>
</tr>
<tr>
<td>-0</td>
<td>No SOAP bindings, use REST</td>
</tr>
<tr>
<td>-C</td>
<td>Generate client-side code only</td>
</tr>
<tr>
<td>-S</td>
<td>Generate server-side code only</td>
</tr>
<tr>
<td>-T</td>
<td>Generate server auto-test code</td>
</tr>
<tr>
<td>-L</td>
<td>Do not generate soapClientLib/soapServerLib</td>
</tr>
<tr>
<td>-a</td>
<td>Use SOAPAction with WS-Addressing to invoke server-side operations</td>
</tr>
<tr>
<td>-A</td>
<td>Require SOAPAction to invoke server-side operations</td>
</tr>
<tr>
<td>-b</td>
<td>Serialize byte arrays char[N] as string</td>
</tr>
<tr>
<td>-c</td>
<td>Generate pure C code</td>
</tr>
<tr>
<td>-d &lt;path&gt;</td>
<td>Save sources in directory specified by &lt;path&gt;</td>
</tr>
<tr>
<td>-e</td>
<td>Generate SOAP RPC encoding style bindings</td>
</tr>
<tr>
<td>-f N</td>
<td>File split of N XML serializer implementations per file</td>
</tr>
<tr>
<td>-h</td>
<td>Print a brief usage message</td>
</tr>
<tr>
<td>-i</td>
<td>Generate service proxies and objects inherited from soap struct</td>
</tr>
<tr>
<td>-j</td>
<td>Generate C++ service proxies and objects that can share a soap struct</td>
</tr>
<tr>
<td>-l &lt;path&gt;</td>
<td>Use &lt;path&gt; for #import (paths separated with ‘;’ or ‘,’ for windows)</td>
</tr>
<tr>
<td>-k</td>
<td>Generate data structure walkers (experimental)</td>
</tr>
<tr>
<td>-l</td>
<td>Generate linkable modules (experimental)</td>
</tr>
<tr>
<td>-m</td>
<td>Generate Matlab® code for MEX compiler</td>
</tr>
<tr>
<td>-n</td>
<td>When used with -p, enables multi-client and multi-server builds:</td>
</tr>
<tr>
<td></td>
<td>Sets compiler option WITH_NONAMESPACES, see Section 9.11</td>
</tr>
<tr>
<td></td>
<td>Saves the namespace mapping table with name &lt;name&gt; names instead of namespaces</td>
</tr>
<tr>
<td></td>
<td>Renames soapserve() into &lt;name&gt;_serve() and soapdestroy() into &lt;name&gt;_destroy()</td>
</tr>
<tr>
<td>-p &lt;name&gt;</td>
<td>Save sources with file name prefix &lt;name&gt; instead of “soap”</td>
</tr>
<tr>
<td>-q &lt;name&gt;</td>
<td>Use name for the C++ namespace of all declarations</td>
</tr>
<tr>
<td>-s</td>
<td>Generates deserialization code with strict XML validation checks</td>
</tr>
<tr>
<td>-t</td>
<td>Generates code to send typed messages (with the xsi:type attribute)</td>
</tr>
<tr>
<td>-u</td>
<td>Uncomment comments in WSDL/schema output by suppressing XML comments</td>
</tr>
<tr>
<td>-v</td>
<td>Display version info</td>
</tr>
<tr>
<td>-w</td>
<td>Do not generate WSDL and schema files</td>
</tr>
<tr>
<td>-x</td>
<td>Do not generate sample XML message files</td>
</tr>
<tr>
<td>-y</td>
<td>Include C/C++ type access information in sample XML messages</td>
</tr>
<tr>
<td>-z1</td>
<td>Compatibility: generate old-style C++ service proxies and objects</td>
</tr>
<tr>
<td>-z2</td>
<td>Compatibility with 2.7.x: omit XML output for NULL pointers</td>
</tr>
</tbody>
</table>

For example

```
> soapcpp2 -cd '../projects' -pmy file.h
```

Saves the sources:

```
../projects/myH.h
../projects/myC.c
../projects/myClient.c
../projects/myServer.c
../projects/myStub.h
```

MS Windows users can use the usual “/” for options, for example:
Compiler options c, i, n, l, w can be set in the gSOAP header file using the //gsoapopt directive. For example,

```c
// Generate pure C and do not produce WSDL output:
//gsoapopt cw
int ns_.myMethod(char*,char**); // takes a string and returns a string
```

### 9.2 SOAP 1.1 Versus SOAP 1.2 and Dynamic Switching

gSOAP supports SOAP 1.1 by default. SOAP 1.2 support is automatically turned on when the appropriate SOAP 1.2 namespace is used, which shows up in the namespace mapping table:

```c
struct Namespace namespaces[] =
{
    {"SOAP-ENV", "http://www.w3.org/2003/05/soap-envelope", ... },
    {"SOAP-ENC", "http://www.w3.org/2003/05/soap-encoding, ... "},
    ...
}
```

Normally the soapcpp2-generated namespace table allows dynamic switching between SOAP 1.1 to SOAP 1.2 by providing the SOAP 1.2 namespace as a **pattern** in the third column of a namespace table:

```c
struct Namespace namespaces[] =
{
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/", "http://www.w3.org/*/soap-envelope"},
    ...
}
```

where the “*” in the third column of the namespace URI pattern is a meta wildcard. This is used to match and accept inbound namespaces.

This way, gSOAP Web services can respond to either SOAP 1.1 or SOAP 1.2 requests. gSOAP will automatically return SOAP 1.2 responses for SOAP 1.2 requests.

The gSOAP soapcpp2 tool generates a .nsmap file with SOAP-ENV and SOAP-ENC namespace patterns similar to the above. Since clients issue a send first, they will always use SOAP 1.1 for requests when the namespace table is similar as shown above. Clients can accept SOAP 1.2 responses by inspecting the response message.

To use SOAP 1.2 by default and allow SOAP 1.1 messages to be received, use the soapcpp2 -2 option to generate SOAP 1.2 conformant .nsmap and .wsdl files. Alternatively, add the following line to your service definitions header file (generated by wsdl2h) for soapcpp2:

```c
#import "import/soap12.h"
```

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Caution: SOAP 1.2 does not support partially transmitted arrays. So the offset field of a dynamic array is meaningless.

Caution: SOAP 1.2 requires the use of SOAP_ENV_Code, SOAP_ENV_Reason, and SOAP_ENV_Detail fields in a SOAP_ENV_Fault fault struct, while SOAP 1.1 uses faultcode, faultstring, and detail fields. Use soap_receiver_fault_subcode(struct soap *soap, const char *subcode, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 fault at the server-side with a fault subcode (SOAP 1.2). Use soap_sender_fault_subcode(struct soap *soap, const char *subcode, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 unrecoverable Bad Request fault at the server-side with a fault subcode (SOAP 1.2).

9.3 The soapdefs.h Header File

The soapdefs.h header file is included in stdsoap2.h when compiling with option -DWITH_SOAPDEFS_H:

```c++
c++ -DWITH_SOAPDEFS_H -c stdsoap2.cpp
```

The soapdefs.h file allows users to include definitions and add includes without requiring changes to stdsoap2.h. For example,

```c
// Contents of soapdefs.h
#define SOAP_BUFLEN 65536 // use large send/recv buffer
```

The following header file can now refer to ostream:

```c
extern class ostream; // ostream can’t be (de)serialized, but need to be declared to make it visible to gSOAP
class ns__myClass
{
    virtual void print(ostream &s) const; // need ostream here
...
};
```

See also Section 19.3.

9.4 How to Build Modules and Libraries with the #module Directive

The #module directive is used to build modules. A library can be build from a module and linked with multiple Web services applications. The directive should appear at the top of the header file and has the following formats:

```c
#module "name"
```

and
where \textit{name} must be a unique short name for the module. The name is case insensitive and MUST not exceed 4 characters in length. The \textit{fullname}, when present, represents the full name of the module.

The rest of the content of the header file includes type declarations and optionally the declarations of service operations and SOAP Headers/Faults. When the gSOAP \texttt{soapcpp2} compiler processes the header file module, it will generate the source codes for a library. The Web services application that uses the library should use a header file that imports the module with the \#\texttt{import} directive.

For example:

```c
/* Contents of module.h */

#module "test"
long;
char*;
struct ns_S
{
 ... }
```

The \texttt{module.h} header file declares a \texttt{long}, \texttt{char*}, and a \texttt{struct ns\_S}. The module name is "test", so the gSOAP \texttt{soapcpp2} compiler produces a \texttt{testC.cpp} file with the (de)serializers for these types. The \texttt{testC.cpp} library can be separately compiled and linked with an application that is built from a header file that imports "module.h" using \#\texttt{import} "module.h". You should also compile \texttt{testClient.cpp} when you want to build a library that includes the service operations that you defined in the module header file.

There are some limitations on a sequence of module imports. A module MUST be imported into another header to use the module content and you MUST place this import statement before all other statements in the file, including other imports (except when these are also modules). It is also advised to put all basic data type definitions in the root module of a module import hierarchy, e.g. using \texttt{typedef} to declare XSD types (see also Section 11.3).

You cannot use a module alone to build a SOAP or XML application. That is, the final gSOAP header file in the import chain SHOULD NOT be a module.

When multiple modules are linked, the types that they declare MUST be declared in one module only to avoid name clashes and link errors. You cannot create two modules that share the same type declaration and link the modules. When necessary, you should consider creating a module hierarchy such that types are declared only once and by only one module when these modules must be linked.

9.5 How to use the \#\texttt{import} Directive

The \#\texttt{import} directive is used to include gSOAP header files into other gSOAP header files for processing with the gSOAP compiler \texttt{soapcpp2}. The C \#\texttt{include} directive cannot be used to include gSOAP header files. The \#\texttt{include} directive is reserved to control the post-gSOAP compilation process, see 9.6.
The #import directive is used for two purposes: you can use it to include the contents of a header file into another header file and you can use it to import a module, see 9.4.

An example of the #import directive:

```c
#include "mydefs.gsoap"
int ns_.mymethod(xsd_string in, xsd_int *out);
```

where "mydefs.gsoap" is a gSOAP header file that defines xsd_string and xsd_int:

```c
typedef char *xsd_string;
typedef int xsd_int;
```

When importing a module, where the module content is declared with #module, then note that this module MUST place the import statement before all other statements in the header file, including other imports (except when these are also modules).

9.6 How to Use #include and #define Directives

The #include and #define directives are normally ignored by the gSOAP soapcpp2 compiler and just passed on to the generated code. Thus, the gSOAP compiler will not actually parse the contents of the header files provided by the #include directives in a header file. Instead, the #include and #define directives will be added to the generated soapH.h header file before any other header file is included. Therefore, #include and #define directives can be used to control the C/C++ compilation process of the sources of an application. However, they have no effect on soapcpp2.

The following example header file refers to ostream by including <ostream>:

```c
#include <ostream>
#define WITH_COOKIES // use HTTP cookie support (you must compile stdsoap2.cpp with -DWITH_COOKIES)
#define WITH_OPENSSL // enable HTTPS/SSL support (you must compile stdsoap2.cpp with -DWITH_OPENSSL)
#define WITH_GNUTLS // enable HTTPS/SSL support (you must compile stdsoap2.cpp with -DWITH_GNUTLS)
#define SOAP_DEFAULT_FLOAT FLT_NAN // use NaN instead of 0.0
extern class ostream; // ostream can’t be (de)serialized, but need to be declared to make it visible to gSOAP
class ns_.myClass
{
    virtual void print(ostream &s) const; // need ostream here
    ...
};
```

This example also uses #define directives for various settings in the target source code.

**Caution:** Note that the use of #define in the header file does not automatically result in compiling stdsoap2.cpp with these directives. You MUST use the -DWITH_COOKIES and -DWITH_OPENSSL (or -DWITH_GNUTLS) options when compiling stdsoap2.cpp before linking the object file with your codes. As an alternative, you can use #define WITH_SOAPDEFS_H and put the #define directives in the soapdefs.h file.

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9.7 Compiling a SOAP/XML Client Application with soapcpp2

After invoking the gSOAP soapcpp2 tool on a header file description of a service, the client application can be compiled on a Linux machine as follows:

```bash
> c++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp
```

Or on a Unix machine:

```bash
> c++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lxnet -lnsl
```

(Depending on your system configuration, the libraries libsocket.a, libxnet.a, libnsl.a or dynamic *.so versions of those libraries are required.)

The myclient.cpp file must include soapH.h and must define a global namespace mapping table. A typical client program layout with namespace mapping table is shown below:

```c
// Contents of file "myclient.cpp"
#include "soapH.h"
...
// A service operation invocation:
soap_call_some_remote_method(...);
...
struct Namespace namespaces[] =
{   /* ns-prefix */ "ns-name"
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns1", "urn:my-remote-method"},
    {NULL, NULL}
};
...
```

A mapping table is generated by the gSOAP soapcpp2 compiler that can be used in the source, see Section 7.2.9.

9.8 Compiling a SOAP/XML Web Service with soapcpp2

After invoking the gSOAP soapcpp2 tool on a header file description of the service, the server application can be compiled on a Linux machine as follows:

```bash
> c++ -o myserver myserver.cpp stdsoap2.cpp soapC.cpp soapServer.cpp
```

Or on a Unix machine:

```bash
> c++ -o myserver myserver.cpp stdsoap2.cpp soapC.cpp soapServer.cpp -lsocket -lxnet -lnsl
```
The myserver.cpp file must include soapH.h and must define a global namespace mapping table. A typical service program layout with namespace mapping table is shown below:

```c
#include "soapH.h"

int main()
{
    soap_serve(soap_new());
}
```

When the gSOAP service is compiled and installed as a CGI application, the soap_serve function acts as a service dispatcher. It listens to standard input and invokes the method via a skeleton routine to serve a SOAP client request. After the request is served, the response is encoded in SOAP and sent to standard output. The method must be implemented in the server application and the type signature of the method must be identical to the service operations specified in the header file. That is, the function prototype in the header file must be a valid prototype of the method implemented as a C/C++ function.

9.9 Compiling Web Services and Clients in ANSI C

The gSOAP soapcpp2 compiler can be used to create pure C Web services and clients. The gSOAP stub and skeleton compiler soapcpp2 generates .cpp files by default. The compiler generates .c files with the -c option. However, these files only use C syntax and data types if the header file input to soapcpp2 uses C syntax and data types. For example:

```bash
> soapcpp2 -c quote.h
> cc -o quote quote.c stdsoap2.c soapC.c soapClient.c
```

Warnings will be issued by the compiler when C++ class declarations occur in the header file.
9.10 Limitations of gSOAP

gSOAP is SOAP 1.1 and SOAP 1.2 compliant and supports SOAP RPC and document/literal operations.

From the perspective of the C/C++ language, a few C++ language features are not supported by gSOAP and these features cannot be used in the specification of SOAP service operations.

There are certain limitations for the following C++ language constructs:

**STL and STL templates** The gSOAP soapcpp2 compiler supports C++ strings std::string and std::wstring (see Section 11.3.6) and the STL containers std::deque, std::list, std::vector, and std::set, (see Section 11.11.8).

**Templates** The gSOAP soapcpp2 compiler is a preprocessor that cannot determine the template instantiations used by the main program, nor can it generate templated code. You can however implement containers similar to the STL containers.

**Multiple inheritance** Single class inheritance is supported. Multiple inheritance cannot be supported due to limitations of the SOAP protocol.

**Abstract methods** A class must be instantiatable to allow decoding of instances of the class.

**Directives** Directives and pragmas such as `#include` and `#define` are interpreted by the gSOAP soapcpp2 compiler. However, the interpretation is different compared to the usual handling of directives, see Section 9.6. If necessary, a traditional C++ preprocessor can be used for the interpretation of directives. For example, Unix and Linux users can use “cpp -B” to expand the header file, e.g. cpp -B myfile.h | soapcpp2. Use the gSOAP `#import` directive to import gSOAP header files, see 9.5.

**C and C++ programming statements** All class methods of a class should be declared within the class declaration in the header file, but the methods should not be implemented in code. All class method implementations must be defined within another C++ source file and linked to the application.

The following data types require some attention to ensure they are serialized:

**union types** A union data type can not be serialized unless run-time information is associated with a union in a struct/class as discussed in Section 11.7. An alternative is to use a struct with a pointer type for each field. Because NULL pointers are not encoded, the resulting encoding will appear as a union type if only one pointer field is valid (i.e. non-NULL) at the time that the data type is encoded.

**void and void* types** The void data type cannot be serialized unless run-time type information is associated with the pointer using a int _type field in the struct/class that contains the void*. The void* data type is typically used to point to some object or to some array of some type of objects at run-time. The compiler cannot determine the type of data pointed to and the size of the array pointed to. A struct or class with a void* field can be augmented to support the (de)serialization of the void* using a int _type field as described in Section 11.9.
**Pointers to sequences of elements in memory** Any pointer, except for C strings which are pointers to a sequence of characters, are treated by the compiler as if the pointer points to *only one element in memory* at run-time. Consequently, the encoding and decoding routines will ignore any subsequent elements that follow the first in memory. For the same reason, arrays of undetermined length, e.g. `float a[]` cannot be used. gSOAP supports dynamic arrays using a special type convention, see Section 11.11.

**Uninitialized pointers** Obviously, all pointers that are part of a data structure must be valid or `NULL` to enable serialization of the data structure at run time.

There are a number of programming solutions that can be adopted to circumvent these limitations. Instead of using `void*`, a program can in some cases be modified to use a pointer to a known type. If the pointer is intended to point to different types of objects, a generic base class can be declared and the pointer is declared to point to the base class. All the other types are declared to be derived classes of this base class. For pointers that point to a sequence of elements in memory dynamic arrays should be used instead, see 11.11.

**9.11 Library Build Flags**

The following macros (`#defines`) can be used to enable certain optional features when building the `libgsoap` library or when compiling and linking `stdsoap2.c` and `stdsoap2.cpp`:
### Macro Description

<table>
<thead>
<tr>
<th>Macro</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>WITH_SOAPDEFS H</td>
<td>includes the soapdefs.h file for custom settings, see Section 9.3</td>
</tr>
<tr>
<td>WITH_COOKIES</td>
<td>enables HTTP cookies, see Sections 19.28 19.29</td>
</tr>
<tr>
<td>WITH_OPENSSL</td>
<td>enables OpenSSL, see Sections 19.22 19.21</td>
</tr>
<tr>
<td>WITH_GNUTLS</td>
<td>enables GNUTLS, see Sections 19.22 19.21</td>
</tr>
<tr>
<td>WITH_IPV6</td>
<td>enables IPv6 support (compile ALL sources with this macro set)</td>
</tr>
<tr>
<td>WITH_IPV6_V6ONLY</td>
<td>IPv6-only server option (compile ALL sources with this macro set)</td>
</tr>
<tr>
<td>WITH_NO_IPV6_V6ONLY</td>
<td>resets IPv6-only server option (compile ALL sources with this macro set)</td>
</tr>
<tr>
<td>WITH_TCPFIN</td>
<td>use TCP FIN after sends when socket is ready to close</td>
</tr>
<tr>
<td>WITH_FASTCGI</td>
<td>enables FastCGI, see Sections 19.31</td>
</tr>
<tr>
<td>WITH_GZIP</td>
<td>enables gzip and deflate compression, see Section 19.27</td>
</tr>
<tr>
<td>WITH_ZLIB</td>
<td>enables deflate compression only, see Section 19.27</td>
</tr>
<tr>
<td>WITH_FAST</td>
<td>use faster memory allocation for WITH_LEAN/WITH_LEANER</td>
</tr>
<tr>
<td>WITH_NOIO</td>
<td>eliminates need for file IO and BSD socket library, see Section 19.33</td>
</tr>
<tr>
<td>WITH_NOIDREF</td>
<td>eliminates href/ref and id attributes to (de)serialize multi-ref data, or alternatively use the SOAP_XML_TREE runtime flag</td>
</tr>
<tr>
<td>WITH_NOHTTP</td>
<td>eliminates HTTP stack to reduce code size</td>
</tr>
<tr>
<td>WITH_NOZONE</td>
<td>silently ignores the timezone in time conversions</td>
</tr>
<tr>
<td>WITH_LEAN</td>
<td>creates a small-footprint executable, see Section 19.32</td>
</tr>
<tr>
<td>WITH_LEANER</td>
<td>creates an even smaller footprint executable, see Section 19.32</td>
</tr>
<tr>
<td>WITH_COMPAT</td>
<td>removes dependency on C++ stream libraries, eliminating C++ exceptions</td>
</tr>
<tr>
<td>WITH_NONAMESPACES</td>
<td>removes dependence on global namespaces table, MUST set it explicitly with soap_set_namespaces() see also Section 10.4</td>
</tr>
<tr>
<td>WITHPURE_VIRTUAL</td>
<td>for C++ abstract service classes with pure virtual methods</td>
</tr>
<tr>
<td>WITH_NOEMPTYSTRUCT</td>
<td>inserts a dummy member in empty structs to allow compilation</td>
</tr>
<tr>
<td>WITH_NOGLOBAL</td>
<td>omit SOAP Header and Fault serialization code</td>
</tr>
<tr>
<td>WITH_NOCDATA</td>
<td>do not retain the parsed CDATA sections in literal XML strings (convert)</td>
</tr>
<tr>
<td>WITH_CDATA</td>
<td>retain the parsed CDATA sections in literal XML strings (no conversion, default)</td>
</tr>
<tr>
<td>WITH_C_LOCALE</td>
<td>use locale functions when available to ensure locale-independent number conversions (force the use of C locale)</td>
</tr>
<tr>
<td>WITH_CASEINSENSITIVETAGS</td>
<td>enable case insensitive XML parsing</td>
</tr>
<tr>
<td>WITH_REPLACE_ILLEGAL_UTF8</td>
<td>replaces UTF8 content that is outside the allowed range of XML 1.0</td>
</tr>
</tbody>
</table>

### Other compile-time flags:

<table>
<thead>
<tr>
<th>Macro</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOCKET_CLOSE_ON_EXIT</td>
<td>prevents a server port from staying in listening mode after exit by internally setting fcntl(sock, F_SETFD, FD_CLOEXEC)</td>
</tr>
</tbody>
</table>

### Compile-time flags to change the default engine settings:

<table>
<thead>
<tr>
<th>Macro</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOAP_BUFSIZE</td>
<td>the length of the internal message buffer (affects socket comms)</td>
</tr>
<tr>
<td>SOAP_TAGLEN</td>
<td>maximum length of XML tags and URL domain names (buffering)</td>
</tr>
<tr>
<td>SOAP_SSL_RSA_BITS</td>
<td>the length of the RSA key (2048 by default)</td>
</tr>
<tr>
<td>SOAP_UNKNOWN_CHAR</td>
<td>an 8 bit code that represents a character that could not be converted to an ASCII char (e.g. from Unicode, applicable when SOAP_C.UTFSTRING is off)</td>
</tr>
</tbody>
</table>

**Caution:** it is important that all of these macros MUST be consistently defined to compile all sources, such as stdsoap2.cpp, soapC.cpp, soapClient.cpp, soapServer.cpp, and all application sources that
include stdsoap2.h or soapH.h. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP context.

9.12 Run Time Flags

gSOAP provides flags to control the input and output mode settings at runtime. These flags are divided into four categories: transport (IO), content encoding (ENC), XML marshalling (XML), and C/C++ data mapping (C).

Although gSOAP is fully SOAP 1.1 compliant, some SOAP implementations may have trouble accepting multi-reference data and/or require explicit nil data so these flags can be used to put gSOAP in “safe mode”. In addition, the embedding (or inlining) of multi-reference data is adopted in the SOAP 1.2 specification, which gSOAP automatically supports when handling with SOAP 1.2 messages.

To set and clear flags for inbound message processing use:

```c
soap_set_imode(soap, inflag);
soap_clr_imode(soap, inflag);
```

To set and clear the flags for outbound message processing use:

```c
soap_set_omode(soap, outflag);
soap_clr_omode(soap, outflag);
```

To allocate and initialize a gSOAP context with inbound and outbound flags use:

```c
soap_new2(soap, inflag, outflag);
```

To initialize an unitialized gSOAP context with inbound and outbound flags use:

```c
soap_init2(soap, inflag, outflag);
```

The input-mode and output-mode flags for inbound and outbound message processing are:
The flags can be selectively turned on/off at any time, for example when multiple Web services are accessed by a client that require special treatment.

All flags are orthogonal, except SOAP_IO_FLUSH, SOAP_IO_BUFFER, SOAP_IO_STORE, and SOAP_IO_CHUNK which are enumerations and only one of these I/O flags can be used. Also the XML serialization flags SOAP_XML_TREE and SOAP_XML_GRAPH should not be mixed.

The flags control the inbound and outbound message transport, encoding, and (de)serialization. The following functions are used to set and reset the flags for input and output modes:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>soap_init2(struct soap *soap, int imode, int omode)</td>
<td>Initialize the runtime and set flags</td>
</tr>
<tr>
<td>soap_imode(struct soap *soap, int imode)</td>
<td>Set all input mode flags</td>
</tr>
<tr>
<td>soap_omode(struct soap *soap, int omode)</td>
<td>Set all output mode flags</td>
</tr>
<tr>
<td>soap_set_imode(struct soap *soap, int imode)</td>
<td>Enable input mode flags</td>
</tr>
<tr>
<td>soap_set_omode(struct soap *soap, int omode)</td>
<td>Enable output mode flags</td>
</tr>
<tr>
<td>soap_clr_imode(struct soap *soap, int omode)</td>
<td>Disable input mode flags</td>
</tr>
<tr>
<td>soap_clr_omode(struct soap *soap, int omode)</td>
<td>Disable output mode flags</td>
</tr>
</tbody>
</table>

The default setting is SOAP_IO_DEFAULT for both input and output modes.

For example

```c
struct soap soap;
```
sends a compressed client request with keep-alive enabled and all data serialized as canonical XML trees.

In many cases, setting the input mode will have no effect, especially with HTTP transport because gSOAP will determine the optimal input buffering and the encoding used for an inbound message. The flags that have an effect on handling inbound messages are SOAP_IO_KEEPALIVE, SOAP_ENC_SSL (but automatic when "https:" endpoints are used or soap_ssl_accept), SOAP_C_NOIOB, SOAP_C_UTFSTRING, and SOAP_C_MBYTE.

**Caution:** The SOAP_XML_TREE serialization flag can be used to improve interoperability with SOAP implementations that are not fully SOAP 1.1 compliant. However, a tree serialization will duplicate data when necessary and will crash the serializer for cyclic data structures.

Additional run-time flags to control sockets.

Use the following selection of flags that are OS dependent to control sockets for send/sendto/recv/recvfrom operations:

<table>
<thead>
<tr>
<th>socket_flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MSG_NOSIGNAL</td>
<td>disables sigpipe (check your OS, this is not portable)</td>
</tr>
<tr>
<td>MSG_DONTROUTE</td>
<td>bypass routing, use direct interface</td>
</tr>
</tbody>
</table>

Use the following selection of flags to set client-side socket connection flags (setsockopt):

<table>
<thead>
<tr>
<th>connect_flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SO_NOSIGPIPE</td>
<td>disables sigpipe (check your OS, this is not portable)</td>
</tr>
<tr>
<td>SO_DEBUG</td>
<td>turns on recording of debugging information in the underlying protocol modules</td>
</tr>
<tr>
<td>SO_BROADCAST</td>
<td>permits sending of broadcast messages (e.g. with UDP) when permitted</td>
</tr>
<tr>
<td>SO_LINGER</td>
<td>set soap.linger_time (set this value as needed)</td>
</tr>
</tbody>
</table>

Use the following selection of flags to set server-side socket connection accept flags (setsockopt):

<table>
<thead>
<tr>
<th>accept_flags</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SO_NOSIGPIPE</td>
<td>disables sigpipe (check your OS, this is not portable)</td>
</tr>
<tr>
<td>SO_DEBUG</td>
<td>turns on recording of debugging information in the underlying protocol modules</td>
</tr>
<tr>
<td>SO_REUSEADDR</td>
<td>reuse bind address immediately (prevents bind reject)</td>
</tr>
<tr>
<td>SO_LINGER</td>
<td>set soap.linger_time (set this value as needed)</td>
</tr>
</tbody>
</table>

For example, soap.accept_flags = (SO_NOSIGPIPE — SO_LINGER) disables sigpipe signals and set linger time value given by soap.linger_time (zero by default).

### 9.13 Memory Management

Understanding gSOAP’s run-time memory management is important to optimize client and service applications by eliminating memory leaks and/or dangling references.
There are two forms of dynamic (heap) allocations made by gSOAP’s runtime for serialization and deserialization of data. Temporary data is created by the runtime such as hash tables to keep pointer reference information for serialization and hash tables to keep XML id/href information for multi-reference object deserialization. Deserialized data is created upon receiving SOAP messages. This data is stored on the heap and requires several calls to the malloc library function to allocate space for the data and new to create class instances. All such allocations are tracked by gSOAP’s runtime by linked lists for later deallocation. The linked list for malloc allocations uses some extra space in each malloced block to form a chain of pointers through the malloced blocks. A separate malloced linked list is used to keep track of class instance allocations.

If you want to preserve the deserialized data before deleting a soap context, you can assign management of the data and delegate responsibility of deletion to another soap context using soap DelegateDeletion(struct soap *soap_from, struct soap *soap_to). This moves all deserialized and temporary data to the other soap context soap_to, which will delete its data and all the delegated data it is responsible for when you call soap destroy and soap end. This can be particularly useful for making client calls inside a server operation, i.e. a mixed server/client. The client call inside the server operation requires a new soap context, e.g. copied from the server’s with soap_copy. Before destroying the client context with soap free, the data can be delegated to the server’s context with soap DelegateDeletion. See samples/mashup/machupserver.c code for an example.

Note that gSOAP does not per se enforce a deallocation policy and the user can adopt a deallocation policy that works best for a particular application. As a consequence, deserialized data is never deallocated by the gSOAP runtime unless the user explicitly forces deallocation by calling functions to deallocate data collectively or individually.

The deallocation functions are:

<table>
<thead>
<tr>
<th>Function Call</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>soap_destroy(struct soap *soap)</td>
<td>Remove all dynamically allocated C++ objects.</td>
</tr>
<tr>
<td></td>
<td>must be called before soap_end()</td>
</tr>
<tr>
<td>soap_end(struct soap *soap)</td>
<td>Remove temporary data and deserialized data except class instances</td>
</tr>
<tr>
<td>soap_free_temp(struct soap *soap)</td>
<td>Instead of soap_destroy and soap_end: remove temporary data only</td>
</tr>
<tr>
<td>soap_dealloc(struct soap *soap, void *p)</td>
<td>Remove malloced data at p. When p==NULL: remove all</td>
</tr>
<tr>
<td></td>
<td>dynamically allocated (deserialized) data except class instances</td>
</tr>
<tr>
<td>soap_delete(struct soap *soap, void *p)</td>
<td>Remove class instance at p. When p==NULL: remove all</td>
</tr>
<tr>
<td></td>
<td>dynamically allocated (deserialized) class instances</td>
</tr>
<tr>
<td></td>
<td>(this is identical to calling soap_destroy(struct soap *soap))</td>
</tr>
<tr>
<td>soap_unlink(struct soap *soap, void *p)</td>
<td>Unlink data/object at p from gSOAP’s deallocation chain so gSOAP won’t dealloc it</td>
</tr>
<tr>
<td>soap_done(struct soap *soap)</td>
<td>Detach context (reset runtime context)</td>
</tr>
<tr>
<td>soap_free(struct soap *soap)</td>
<td>Detach and free context (allocated with soap new)</td>
</tr>
</tbody>
</table>

Temporary data (i.e. the hash tables) are automatically removed with calls to the soap free temp function which is also made by soap_end and soap done or when the next call to a stub or skeleton routine is made to send a message or receive a message. Deallocation of non-class based data is straightforward: soap_end removes all dynamically allocated deserialized data (data allocated with soap malloc. That is, when the client/service application does not use any class instances that are (de)marshalled, but uses structs, arrays, etc., then calling the soap_end function is safe to remove
all deserialized data. The function can be called after processing the deserialized data of a service operation call or after a number of service operation calls have been made. The function is also typically called after `soap_serve`, when the service finished sending the response to a client and the deserialized client request data can be removed.

Individual data objects can be unlinked from the deallocation chain if necessary, to prevent deallocation by the collective `soap_end` or `soap_destroy` functions.

### 9.13.1 Memory Allocation and Management Policies

There are three situations to consider for memory deallocation policies for class instances:

1. the program code deletes the class instances and the class destructors in turn SHOULD delete and free any dynamically allocated data (deep deallocation) without calling the `soap_end` and `soap_destroy` functions,

2. or the class destructors SHOULD NOT deallocate any data and the `soap_end` and `soap_destroy` functions can be called to remove the data.

3. or the class destructors SHOULD mark their own deallocation and mark the deallocation of any other data deallocated by it’s destructors by calling the `soap_unlink` function. This allows `soap_destroy` and `soap_end` to remove the remaining instances and data without causing duplicate deallocations.

It is advised to use pointers to class instances that are used within other structs and classes to avoid the creation of temporary class instances during deserialization. The problem with temporary class instances is that the destructor of the temporary may affect data used by other instances through the sharing of data parts accessed with pointers. Temporaries and even whole copies of class instances can be created when deserializing SOAP multi-referenced objects. A dynamic array of class instances is similar: temporaries may be created to fill the array upon deserialization. To avoid problems, use dynamic arrays of pointers to class instances. This also enables the exchange of polymorphic arrays when the elements are instances of classes in an inheritance hierarchy. In addition, allocate data and class instances with `soap_malloc` and `soap_new_x` functions (more details below).

To summarize, it is advised to pass class data types by pointer to a service operation. For example:

```cpp
class X { ... };  
ns_.remoteMethod(X *in, ...);
```

Response elements that are class data types can be passed by reference, as in:

```cpp
class X { ... };  
class ns_.remoteMethodResponse { ... };  
ns_.remoteMethod(X *in, ns_.remoteMethodResponse &out);
```

But dynamic arrays declared as class data types should use a pointer to a valid object that will be overwritten when the function is called, as in:
typedef int xsd_int;
class X { ... };
class ArrayOfint { xsd_int * _ptr; int _size; };
ns_remotesMethod(X *in, ArrayOfint *out);

Or a reference to a valid or NULL pointer, as in:

typedef int xsd_int;
class X { ... };
class ArrayOfint { xsd_int * _ptr; int _size; };
ns_remotesMethod(X *in, ArrayOfint *&out);

The gSOAP memory allocation functions can be used in client and/or service code to allocate temporary data that will be automatically deallocated. These functions are:

<table>
<thead>
<tr>
<th>Function Call</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>void *soap_malloc(struct soap *soap, size_t n)</td>
<td>return pointer to n bytes</td>
</tr>
<tr>
<td>Class *soap_new_Class(struct soap *soap)</td>
<td>instantiate Class</td>
</tr>
<tr>
<td>Class *soap_new_Class(struct soap *soap, int n)</td>
<td>instantiate array of n objects</td>
</tr>
<tr>
<td>Class *soap_new_set_Class(struct soap *soap, m1, ..., mn)</td>
<td>instantiate and set members mi</td>
</tr>
<tr>
<td>Class *soap_new_req_Class(struct soap *soap, m1, ..., mn)</td>
<td>instantiate and set required-only mi</td>
</tr>
</tbody>
</table>

The soap_new_X functions are generated by the gSOAP soapcpp2 compiler for every class X in the header file.

Space allocated with soap_malloc will be released with the soap_end and soap_dealloc functions. All objects instantiated with soap_new_X(struct soap*) are removed altogether with soap_destroy(struct soap*). To remove just a single object, use soap_delete_X(struct soap*, X*).

For example, the following service uses temporary data in the service operation implementation:

```c
int main()
{
    ...
    struct soap soap;
    soap_init(&soap);
    soap_server(&soap);
    soap_end(&soap);
    ...
}
```

An example service operation that allocates a temporary string is:

```c
int ns_itoa(struct soap *soap, int i, char **a)
{
    *a = (char*)soap_malloc(soap, 11);
    sprintf(*a, "%d", i);
    return SOAP_OK;
}
```

This temporary allocation can also be used to allocate strings for the SOAP Fault data structure. For example:
int ns_mymethod(...) {
    ... 
    if (exception) {
        char *msg = (char*)soap_malloc(soap, 1024);  // allocate temporary space for detailed message
        sprintf(msg, "...", ...);  // produce the detailed message
        return soap_receiver_fault(soap, "An exception occurred", msg);  // return the server-side fault
    }
    ...
}

Use soap_receiver_fault(struct soap *soap, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 fault at the server-side. Use soap_sender_fault(struct soap *soap, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 unrecoverable Bad Request fault at the server-side. Sending clients are not supposed to retry messages after a Bad Request, while errors at the receiver-side indicate temporary problems.

The above functions do not include a SOAP 1.2 Subcode element. To include Subcode element, use soap_receiver_fault_subcode(struct soap *soap, const char *subcode, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 fault with Subcode at the server-side. Use soap_sender_fault_subcode(struct soap *soap, const char *subcode, const char *faultstring, const char *detail) to set a SOAP 1.1/1.2 unrecoverable Bad Request fault with Subcode at the server-side.

gSOAP provides a function to duplicate a string into gSOAP’s memory space:

    char *soap_strdup(struct soap *soap, const char *s)

The function allocates space for s with soap_malloc, copies the string, and returns a pointer to the duplicated string. When s is NULL, the function does not allocate and copy the string and returns NULL.

9.13.2 Intra-Class Memory Management

When a class declaration has a struct soap * field, this field will be set to point to the current gSOAP runtime context by gSOAP’s deserializers and by the soap_new_class functions. This simplifies memory management for class instances. The struct soap* pointer is implicitly set by the gSOAP deserializer for the class or explicitly by calling the soap_new_X function for class X. For example:

    class Sample
    { public:
        struct soap *soap;  // reference to gSOAP’s run-time
    ...
        Sample();
        ~Sample();
    };

The constructor and destructor for class Sample are:
The \texttt{soap\_unlink()} call removes the object from gSOAP's deallocation chain. In that way, \texttt{soap\_destroy} can be safely called to remove all class instances. The following code illustrates the explicit creation of a \texttt{Sample} object and cleanup:

```c
struct soap *soap = soap\_new(); // new gSOAP runtime
Sample *obj = soap\_new\_Sample(soap); // new Sample object with obj->soap set to runtime
...
delete obj; // also calls soap\_unlink to remove obj from the deallocation chain
soap\_destroy(soap); // deallocate all (other) class instances
soap\_end(soap); // clean up
```

Here is another example:

```c
\texttt{\textbf{class} ns\_myClass}
\{
  ... \\
  \texttt{struct} soap *soap; // set by soap\_new\_ns\_myClass() \\
  \texttt{char} *name; \\
  \texttt{void} setName(const \texttt{char} *s); \\
  ... 
\};
```

Calls to \texttt{soap\_new\_ns\_myClass(soap)} will set the \texttt{soap} field in the class instance to the current gSOAP context. Because the deserializers invoke the \texttt{soap\_new} functions, the \texttt{soap} field of the \texttt{ns\_myClass} instances are set as well. This mechanism is convenient when Web Service methods need to return objects that are instantiated in the methods. For example

```c
\texttt{int} ns\_myMethod(\texttt{struct} soap *soap, ...) 
\{
  \texttt{ns\_myClass} *p = soap\_new\_ns\_myClass(soap); \\
  p\->setName("SOAP"); \\
  \texttt{return} SOAP\_OK;
\}
\texttt{void} ns\_myClass::ns\_setName(const \texttt{char} *s) 
\{
  if (soap)
    name = (\texttt{char}*)soap\_malloc(soap, strlen(s)+1); \\
  else
    name = (\texttt{char}*)malloc(strlen(s)+1); \\
  strcpy(name, s);
\}
ns\_myClass::ns\_myClass() 
\{
  soap = NULL;
```

109
name = NULL;
}
ns_myClass::ns_myClass()
{
    if (!soap && name) free(name);
    soap_unlink(soap, this);
}

Calling soap_destroy right after soap_serve in the Web Service will destroy all dynamically allocated class instances.

9.14 Debugging

To activate debugging and message logging, set the #define DEBUG macro on the compiler’s command line (typically as a compiler option -DDEBUG) or in stdsoap2.h, and recompile your code together with stdsoap2.c or stdsoap2.cpp (instead of libgsoap). When using libgsoap and libgsoap++, reinstall the software with configure using option --enable-debug.

When your client and server applications run, they will log their activity in three separate files:

<table>
<thead>
<tr>
<th>File</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SENT.log</td>
<td>The SOAP content transmitted by the application</td>
</tr>
<tr>
<td>RECV.log</td>
<td>The SOAP content received by the application</td>
</tr>
<tr>
<td>TEST.log</td>
<td>A log containing various activities performed by the application</td>
</tr>
</tbody>
</table>

Caution: The client and server applications may run slow due to the logging activity.

Hint: Set macro DEBUG_STAMP instead of DEBUG to add time stamps to TEST.log. This works on platforms supporting the gettimeofday function.

Caution: When installing a CGI application on the Web with debugging activated, the log files may sometimes not be created due to file access permission restrictions imposed on CGI applications. To get around this, create empty log files with universal write permissions. Be careful about the security implication of this.

You can test a service CGI application without deploying it on the Web. To do this, create a client application for the service and activate message logging by this client. Remove any old SENT.log file and run the client (which connects to the Web service or to another dummy, but valid address) and copy the SENT.log file to another file, e.g. SENT.tst. Then redirect the SENT.tst file to the service CGI application. For example,

```
> ./myservice.cgi < SENT.tst
```

This should display the service response on the terminal.

The file names of the log files and the logging activity can be controlled at the application level. This allows the creation of separate log files by separate services, clients, and threads. For example, the following service logs all SOAP messages (but no debug messages) in separate directories:

```c
struct soap soap;
soap_init(&soap);
```
Likewise, messages can be logged for individual client-side service operation calls.

9.15 Generating an Auto Test Server for Client Testing

The soapcpp2 -T option generates an auto-test server application in soapTester.cpp, which is to be compiled and linked with the code generated for a server implementation, i.e. soapServer.cpp (or with the generated server object class) and soapC.cpp. The feature also supports C, so use the soapcpp2 -c option to generate C.

The auto-test server can be used to test a client application. Suppose the generated code is compiled into the executable named tester (compile soapServer.cpp, soapC.cpp, and stdsoap2.cpp or link libgsoap++). We can use the IO redirect to “send” it a message saved in a file, for example one of the sample request messages generated by soapcpp2:

```
> ./tester < example.req.xml
```

which then returns the response with default XML values displayed on the terminal.

To run the auto test service on a port to test a client against, use two command-line arguments. The first argument is the OR-ed values of the gSOAP runtime context flags such as SOAP\_IO\_KEEPALIVE (0x10 = 16) and the second argument is the port number:

```
> ./tester 16 8080
```

This starts an iterative stand-alone server on port 8080. This way, messages can be sent to http://localhost:8080 to test the client. The data in the response messages are copied from the request messages when possible, or XML default values, or empty otherwise.

9.16 Required Libraries

- The socket library is essential and requires the inclusion of the appropriate libraries with the compile command for Sun Solaris systems:

```
> c++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lxnet -lnsl
```

These library loading options are not required with Linux.

- The gSOAP runtime uses the math library for the NaN, INF, and -INF floating point representations. The library is not strictly necessary and the <math.h> header file import can be commented out from the stdsoap2.h header file. The application can be linked without the -lm math library e.g. under Sun Solaris:

```
> c++ -o myclient myclient.cpp stdsoap2.cpp soapC.cpp soapClient.cpp -lsocket -lxnet -lnsl
```
10 The gSOAP Service Operation Specification Format

A service operation is specified as a C/C++ function prototype in a header file. The function is REQUIRED to return `int`, which is used to represent a SOAP error code, see Section 10.2. Multiple service operations MAY be declared together in one header file.

The general format of a service operation specification is:

```
[int] [namespace_prefix_]method_name([inparam1, inparam2, ...],) outparam);
```

where

- `namespace_prefix_` is the optional namespace prefix of the method (see identifier translation rules 10.3)
- `method_name` is the service operation name (see identifier translation rules 10.3)
- `inparam` is the declaration of an input parameter of the service operation
- `outparam` is the declaration of the output parameter of the service operation

This simple form can only pass a single, non-`struct` and non-`class` type output parameter. See 10.1 for passing multiple output parameters. The name of the declared function `namespace_prefix_`method_name must be unique and cannot match the name of a `struct`, `class`, or `enum` declared in the same header file.

The method request is encoded in SOAP as an XML element and the namespace prefix, method name, and input parameters are encoded using the format:

```
<[namespace-prefix:]method_name xsi:type="[namespace-prefix:]method_name">
  <inparam-name1 xsi:type="...">...</inparam-name1>
  <inparam-name2 xsi:type="...">...</inparam-name2>
  ...
</[namespace-prefix:]method_name>
```

where the `inparam-name` accessors are the element-name representations of the `inparam` parameter name declarations, see Section 10.3. (The optional parts are shown enclosed in `[]`.)

The XML response by the Web service is of the form:

```
<[namespace-prefix:]method-nameResponse xsi:type="[namespace-prefix:]method-nameResponse">
  <outparam-name xsi:type="...">...</outparam-name>
</[namespace-prefix:]method-nameResponse>
```

where the `outparam-name` accessor is the element-name representation of the `outparam` parameter name declaration, see Section 10.3. By convention, the response element name is the method name ending in `Response`. See 10.1 on how to change the declaration if the service response element name is different.

The gSOAP `soapcpp2` tool generates a stub routine for the service operation. This stub is of the form:
int soap_call_{namespace_prefix_}method_name(struct soap *soap, char *URL, char *action, [inparam1, inparam2, ...], outparam);

This proxy can be called by a client application to perform the service operation call.

The gSOAP soapcpp2 tool generates a skeleton routine for the service operation. The skeleton function is:

    int soap_serve_{namespace_prefix_}method_name(struct soap *soap);

The skeleton routine, when called by a service application, will attempt to serve a request on the standard input. If no request is present or if the request does not match the method name, SOAP_NO_METHOD is returned. The skeleton routines are automatically called by the generated soap_serve routine that handles all requests.

10.1 Service Operation Parameter Passing

The input parameters of a service operation MUST be passed by value. Input parameters cannot be passed by reference with the & reference operator, but an input parameter value MAY be passed by a pointer to the data. Of course, passing a pointer to the data is preferred when the size of the data of the parameter is large. Also, to pass instances of (derived) classes, pointers to the instance need to be used to avoid passing the instance by value which requires a temporary and prohibits passing derived class instances. When two input parameter values are identical, passing them using a pointer has the advantage that the value will be encoded only once as multi-reference (hence, the parameters are aliases). When input parameters are passed using a pointer, the data pointed to will not be modified by the service operation and returned to the caller.

The output parameter MUST be passed by reference using & or by using a pointer. Arrays are passed by reference by default and do not require the use of the reference operator &.

The input and output parameter types have certain limitations, see Section 9.10

If the output parameter is a struct or class type, it is considered a service operation response element instead of a simple output parameter value. That is, the name of the struct or class is the name of the response element and the struct or class fields are the output parameters of the service operation, see also 7.1.7. Hence, if the output parameter has to be a struct or class, a response struct or class MUST be declared as well. In addition, if a service operation returns multiple output parameters, a response struct or class MUST be declared. By convention, the response element is the service operation name ending with “Response”.

The general form of a response element declaration is:

    struct [namespace_prefix_]response_element_name
    {
      outparam1;
      outparam2;
      ...
    };

where
namespace_prefix_ is the optional namespace prefix of the response element (see identifier translation rules 10.3)

response_element_name is the name of the response element (see identifier translation rules 10.3)

outparam is the declaration of an output parameter of the service operation

The general form of a service operation specification with a response element declaration for (multiple) output parameters is:

```
[int] [namespace_prefix_]method_name([inparam1, inparam2, ...]) struct [namespace_prefix_]response_element_name {
outparam1[, outparam2, ...]} &anyparam);
```

The choice of name for anyparam has no effect on the SOAP encoding and decoding and is only used as a place holder for the response.

The method request is encoded in SOAP as an independent element and the namespace prefix, method name, and input parameters are encoded using the format:

```
<[/namespace-prefix:]method-name xsi:type="[/namespace-prefix:]method-name">
<inparam-name1 xsi:type="...">...</inparam-name1>
<inparam-name2 xsi:type="...">...</inparam-name2>
...
</[/namespace-prefix:]method-name>
```

where the inparam-name accessors are the element-name representations of the inparam parameter name declarations, see Section 10.3. (The optional parts resulting from the specification are shown enclosed in [])

The method response is expected to be of the form:

```
<[/namespace-prefix:]response-element-name xsi:type="[/namespace-prefix:]response-element-name">
<outparam-name1 xsi:type="...">...</outparam-name1>
<outparam-name2 xsi:type="...">...</outparam-name2>
...
</[/namespace-prefix:]response-element-name>
```

where the outparam-name accessors are the element-name representations of the outparam parameter name declarations, see Section 10.3. (The optional parts resulting from the specification are shown enclosed in [])

The input and/or output parameters can be made anonymous, which allows the deserialization of requests/responses with different parameter names as is endorsed by the SOAP 1.1 specification, see Section 7.1.13.

10.2 Error Codes

The error codes returned by the stub and skeleton routines are listed below.
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOAP_OK</td>
<td>No error</td>
</tr>
<tr>
<td>SOAP_CLI_FAULT*</td>
<td>The service returned a client fault (SOAP 1.2 Sender fault)</td>
</tr>
<tr>
<td>SOAP_SVR_FAULT*</td>
<td>The service returned a server fault (SOAP 1.2 Receiver fault)</td>
</tr>
<tr>
<td>SOAP_TAG_MISMATCH</td>
<td>An XML element didn’t correspond to anything expected</td>
</tr>
<tr>
<td>SOAP_TYPE</td>
<td>An XML Schema type mismatch</td>
</tr>
<tr>
<td>SOAP_SYNTAX_ERROR</td>
<td>An XML syntax error occurred on the input</td>
</tr>
<tr>
<td>SOAP_NO_TAG</td>
<td>Begin of an element expected, but not found</td>
</tr>
<tr>
<td>SOAP_INDEX</td>
<td>Array index out of bounds</td>
</tr>
<tr>
<td>SOAP_MUSTUNNDERSTAND*</td>
<td>An element needs to be ignored that need to be understood</td>
</tr>
<tr>
<td>SOAP_NAMESPACE</td>
<td>Namespace name mismatch (validation error)</td>
</tr>
<tr>
<td>SOAP_FATAL_ERROR</td>
<td>Internal error</td>
</tr>
<tr>
<td>SOAP_USER_ERROR</td>
<td>User error (reserved for soap.user usage</td>
</tr>
<tr>
<td>SOAPFAULT</td>
<td>An exception raised by the service</td>
</tr>
<tr>
<td>SOAP_NO_METHOD</td>
<td>The dispatcher did not find a matching operation for a request</td>
</tr>
<tr>
<td>SOAP_NO_DATA</td>
<td>No data in HTTP message</td>
</tr>
<tr>
<td>SOAP_GET_METHOD</td>
<td>HTTP GET operation not handled, see Section 19.10</td>
</tr>
<tr>
<td>SOAP_EOM</td>
<td>Out of memory</td>
</tr>
<tr>
<td>SOAP_MOE</td>
<td>Memory overflow/corruption error (DEBUG mode)</td>
</tr>
<tr>
<td>SOAP_NULL</td>
<td>An element was null, while it is not supposed to be null</td>
</tr>
<tr>
<td>SOAP_DUPLICATE_ID</td>
<td>Element’s ID duplicated (multi-ref encoding)</td>
</tr>
<tr>
<td>SOAP_MISSING_ID</td>
<td>Element ID missing for an href/ref (multi-ref encoding)</td>
</tr>
<tr>
<td>SOAP_HREF</td>
<td>Reference to object is incompatible with the object refered to</td>
</tr>
<tr>
<td>SOAP_UTF_ERROR</td>
<td>An UTF-encoded message decoding error occurred</td>
</tr>
<tr>
<td>SOAP_UDP_ERROR</td>
<td>Message too large to store in UDP packet</td>
</tr>
<tr>
<td>SOAP_TCP_ERROR</td>
<td>A connection error occurred</td>
</tr>
<tr>
<td>SOAP_HTTP_ERROR</td>
<td>An HTTP error</td>
</tr>
<tr>
<td>SOAP_NTLM_ERROR</td>
<td>An NTLM authentication handshake error occurred</td>
</tr>
<tr>
<td>SOAP_SSL_ERROR</td>
<td>An SSL error</td>
</tr>
<tr>
<td>SOAP_ZLIB_ERROR</td>
<td>A Zlib error</td>
</tr>
<tr>
<td>SOAP_PLUGIN_ERROR</td>
<td>Failed to register plugin</td>
</tr>
<tr>
<td>SOAP_MIME_ERROR</td>
<td>MIME parsing error</td>
</tr>
<tr>
<td>SOAP_MIME_HREF</td>
<td>MIME attachment has no href from SOAP body error</td>
</tr>
<tr>
<td>SOAP_MIME_END</td>
<td>End of MIME attachments protocol error</td>
</tr>
<tr>
<td>SOAP_DIME_ERROR</td>
<td>DIME formatting error or DIME size exceeds SOAP_MAXDIMESIZE</td>
</tr>
<tr>
<td>SOAP_DIME_END</td>
<td>End of DIME attachments protocol error</td>
</tr>
<tr>
<td>SOAP_DIME_HREF</td>
<td>DIME attachment has no href from SOAP body (and no DIME callbacks were defined to save the attachment)</td>
</tr>
<tr>
<td>SOAP_DIME_MISMATCH</td>
<td>DIME version/transmission error</td>
</tr>
<tr>
<td>SOAP_VERSIONMISMATCH*</td>
<td>SOAP version mismatch or no SOAP message</td>
</tr>
<tr>
<td>SOAP_DATAENCODINGUNKNOWN</td>
<td>SOAP 1.2 DataEncodingUnknown fault</td>
</tr>
<tr>
<td>SOAP_REQUIRED</td>
<td>Attributed required validation error</td>
</tr>
<tr>
<td>SOAP_PROHIBITED</td>
<td>Attributed prohibited validation error</td>
</tr>
<tr>
<td>SOAP_OCCURS</td>
<td>Element minOccurs/maxOccurs validation error</td>
</tr>
<tr>
<td>SOAP_LENGTH</td>
<td>Element length validation error</td>
</tr>
<tr>
<td>SOAP_FD_EXCEEDED</td>
<td>Too many open sockets (for non-win32 systems not supporting poll())</td>
</tr>
<tr>
<td>SOAP_EOF</td>
<td>Unexpected end of file, no input, or timeout receiving data</td>
</tr>
<tr>
<td>SOAP_ERR</td>
<td>Error (for internal use)</td>
</tr>
</tbody>
</table>
The error codes that are returned by a stub routine (proxy) upon receiving a SOAP Fault from the server are marked (*). The remaining error codes are generated by the proxy itself as a result of problems with a SOAP payload. The error code is SOAP_OK when the service operation call was successful (the SOAP_OK predefined constant is guaranteed to be 0). The error code is also stored in soap.error, where soap is a variable that contains the current runtime context. The function soap_print_fault(struct soap *soap, FILE *fd) can be called to display an error message on fd where current value of the soap.error variable is used by the function to display the error. The function soap_print_fault_location(struct soap *soap, FILE *fd) prints the location of the error if the error is a result from parsing XML. Use soap_sprint_fault(struct soap*, char *buf, size_t len) to print the error to a string.

A service operation implemented in a SOAP service MUST return an error code as the function’s return value. SOAP_OK denotes success and SOAP_FAULT denotes an exception. The exception details can be assigned with the soap_receiver_fault(struct soap *soap, const char *faultstring, const char *detail) which sets the strings soap.fault->faultstring and soap.fault->detail for SOAP 1.1, and soap.fault->SOAP_ENV_.Reason and soap.fault->SOAP_ENV_.Detail for SOAP 1.2, where soap is a variable that contains the current runtime context, see Section 12. A receiver error indicates that the service can’t handle the request, but can possibly recover from the error. To return an unrecoverable SOAP 1.1/1.2 error, use soap_sender_fault(struct soap *soap, const char *faultstring, const char *detail).

To return a HTTP error code a service method can simply return the HTTP error code number. For example, return 404; returns a "404 Not Found" HTTP error back to the client. The soap.error is set to the HTTP error code at the client side. The HTTP 1.1 error codes are:
<table>
<thead>
<tr>
<th>#</th>
<th>Error</th>
</tr>
</thead>
<tbody>
<tr>
<td>201</td>
<td>Created</td>
</tr>
<tr>
<td>202</td>
<td>Accepted</td>
</tr>
<tr>
<td>203</td>
<td>Non-Authoritative Information</td>
</tr>
<tr>
<td>204</td>
<td>No Content</td>
</tr>
<tr>
<td>205</td>
<td>Reset Content</td>
</tr>
<tr>
<td>206</td>
<td>Partial Content</td>
</tr>
<tr>
<td>300</td>
<td>Multiple Choices</td>
</tr>
<tr>
<td>301</td>
<td>Moved Permanently</td>
</tr>
<tr>
<td>302</td>
<td>Found</td>
</tr>
<tr>
<td>303</td>
<td>See Other</td>
</tr>
<tr>
<td>304</td>
<td>Not Modified</td>
</tr>
<tr>
<td>305</td>
<td>Use Proxy</td>
</tr>
<tr>
<td>307</td>
<td>Temporary Redirect</td>
</tr>
<tr>
<td>400</td>
<td>Bad Request</td>
</tr>
<tr>
<td>401</td>
<td>Unauthorized</td>
</tr>
<tr>
<td>402</td>
<td>Payment Required</td>
</tr>
<tr>
<td>403</td>
<td>Forbidden</td>
</tr>
<tr>
<td>404</td>
<td>Not Found</td>
</tr>
<tr>
<td>405</td>
<td>Method Not Allowed</td>
</tr>
<tr>
<td>406</td>
<td>Not Acceptable</td>
</tr>
<tr>
<td>407</td>
<td>Proxy Authentication Required</td>
</tr>
<tr>
<td>408</td>
<td>Request Time-out</td>
</tr>
<tr>
<td>409</td>
<td>Conflict</td>
</tr>
<tr>
<td>410</td>
<td>Gone</td>
</tr>
<tr>
<td>411</td>
<td>Length Required</td>
</tr>
<tr>
<td>412</td>
<td>Precondition Failed</td>
</tr>
<tr>
<td>413</td>
<td>Request Entity Too Large</td>
</tr>
<tr>
<td>414</td>
<td>Request-URI Too Large</td>
</tr>
<tr>
<td>415</td>
<td>Unsupported Media Type</td>
</tr>
<tr>
<td>416</td>
<td>Requested range not satisfiable</td>
</tr>
<tr>
<td>417</td>
<td>Expectation Failed</td>
</tr>
<tr>
<td>500</td>
<td>Internal Server Error</td>
</tr>
<tr>
<td>501</td>
<td>Not Implemented</td>
</tr>
<tr>
<td>502</td>
<td>Bad Gateway</td>
</tr>
<tr>
<td>503</td>
<td>Service Unavailable</td>
</tr>
<tr>
<td>504</td>
<td>Gateway Time-out</td>
</tr>
<tr>
<td>505</td>
<td>HTTP Version not supported</td>
</tr>
</tbody>
</table>

The error codes are given for informational purposes only. The HTTP protocol requires the proper actions after an error is issued. gSOAP’s HTTP 1.0/1.1 handling is automatic.

### 10.3 C/C++ Identifier Name to XML Tag Name Mapping

One of the “secrets” behind the power and flexibility of gSOAP’s encoding and decoding of service operation names, class names, type identifiers, and struct or class fields is the ability to specify namespace prefixes with these names that are used to denote their encoding style. More specifically, a C/C++ identifier name of the form

\[ \text{[namespace\_prefix\_]}\text{element\_name} \]
where the prefix and the element name are separated by double underscores will be encoded in XML as

<\[namespace-prefix:]element-name ...>

The underscore pair (..) separates the namespace prefix from the element name. Each namespace prefix has a namespace URI specified by a namespace mapping table 10.4, see also Section 7.1.2. The namespace URI is a unique identification that can be associated with the service operations and data types. The namespace URI disambiguates potentially identical service operation names and data type names used by disparate organizations.

XML element names are NCNames (restricted strings) that MAY contain hyphens, dots, and underscores. The special characters in the XML element names of service operations, structs, classes, typedefs, and fields can be controlled using the following conventions: A single underscore in a namespace prefix or identifier name is replaced by a hyphen (\-) in the XML element name. For example, the identifier name SOAP\_ENC\_ur\_type is represented in XML as SOAP-ENC:ur-type. The sequence DOT is replaced by a dot (\.), and the sequence USCORE is replaced by an underscore (_). For example:

```cpp
class n\_s\_biz\_DOTcom
{
    char *n\_s\_biz\_USCOREname;
};
```

is encoded in XML as:

```xml
<n-s:biz.com xsi:type="n-s:biz.com">
    <n-s:biz name xsi:type="string">Bizybiz</n-s:biz name>
</n-s:biz.com>
```

Trailing underscores of an identifier name are not translated into the XML representation. This is useful when an identifier name clashes with a C++ keyword. For example, `return` is often used as an accessor name in a SOAP response element. The `return` element can be specified as `return` in the C++ source code. Note that XML should be treated as case sensitive, so the use of e.g. `Return` may not always work to avoid a name clash with the `return` keyword. The use of trailing underscores also allows for defining structs and classes with essentially the same XML Schema type name, but that have to be distinguished as separate C/C++ types.

For decoding, the underscores in identifier names act as wildcards. An XML element is parsed and matches the name of an identifier if the name is identical to the element name (case insensitive) and the underscores in the identifier name are allowed to match any character in the element name. For example, the identifier name `I\_want\_soap\_fun\_the\_bea\_DOTcom` matches the element name `I\_want\:SOAP4fun@the-beach.com`.

By default, soapcpp2 generates data bindings in which all XML elements are and attributes are unqualified:
where the `name` element and the `type` attribute are unqualified in the XML content (for example to facilitate SOAP RPC encoding).

The rules for SOAP services that are document style are different:

```c
struct x_record {
    char * type;
    char * name;
};
```

where `x` is associated with a service. For document style all elements are qualified and attributes are unqualified.

To force qualification of elements and attributes, use the “form” directive:

```c
struct x_record {
    @char * xsi_type;
    char * y_name;
};
```

You can also use “elementForm” and “attributeForm” directives to (un)qualify element and attributes of the schema, respectively.

Because the soapcpp2-generated serializers follow the qualified/unqualified forms of the schemas, there is normally no need to explicitly qualify struct/class members because automatic encoding rules will be used.

If explicit qualification is needed, this can be done using the prefix convention:

```c
struct x_record {
    @char * xsi_type;
    char * y_name;
};
```

which ensures that there cannot be any name clashes between members of the same name defined in different schemas (consider for example `name` and `y_name`), but this can clutter the representation when clashes do not occur.
An alternative to the prefix convention is the use of “colon notation” in the gSOAP header file. This deviation from the C/C++ syntax allows you to bind type names and struct and class members to qualified and unqualified XML tag names explicitly, thus bypassing the default mechanism that automatically qualifies or unqualifies element and attribute tag names based on the schema element/attribute form.

The colon notation for type names, struct/class names and members overrides the prefix qualification rules explicitly:

```c
//gsoap x schema namespace: urn:x
//gsoap y schema namespace: urn:y
struct x:record
{
    @char * xsi:type;
    char * y:name;
};
```

where x and y are namespace prefixes that MUST be declared with a directive. The xsi:type member is an XML attribute in the xsi namespace. The soapcpp2 tool maps this to the following struct without the annotations:

```c
// This code is generated from the above by soapcpp2 in soapStub.h:
struct record
{
    char *type; /* optional attribute of type xsd:string */
    char *name; /* optional element of type xsd:string */
};
```

The soapcpp2 tool also generates XML schemas with element and attribute references. That is, y:name is referenced from the y schema by the x:record complexType defined in the x schema.

The colon notation also allows you to override the element/attribute form to unqualified for qualified schemas:

```c
//gsoap x schema namespace: urn:x
//gsoap x schema form: qualified
struct x:record
{
    @char * :type;
    char * :name;
};
```

where the colon notation ensures that both type and name are unqualified in the XML content, which overrides the default qualified forms of the x schema.

Note that the use of colon notation to bind namespace prefixes to type names (typedef, enum, struct, and class names) translates to code without the prefixes. This means that name clashes can occur between types with identical unqualified names:

```c
enum x:color { RED, WHITE, BLUE };
enum y:color { YELLOW, ORANGE }; // illegal enum name: name clash with x:color
```
while prefixing with double underscores never lead to clashes:

```c
enum x_color { RED, WHITE, BLUE }
enum y_color { YELLOW, ORANGE }; // no name clash
```

Also note that colon notation has a very different role than the C++ scope operator ::. The scope operator cannot be used in places where we need colon notation, such as struct/class member fields. The default mechanism that associates XML tag names with the names of struct and class member fields can be overridden by "retagging" names with the annotation of 'tag' placed next to the member field name. This is particularly useful to support legacy code for which the fixed naming of member fields cannot be easily changed. For example:

```c
//gsoap x schema namespace: urn:x
//gsoap x schema form: qualified
struct x:record
{
    @char * t:type;
    char * s:full-name;
};
```

This maps the t member to the x:type XML attribute tag and s member to the x:full-name XML element tag. Note that both tags are namespace qualified as per schema declaration.

### 10.4 Namespace Mapping Table

A namespace mapping table MUST be defined by clients and service applications. The mapping table is used by the serializers and deserializers of the stub and skeleton routines to produce a valid SOAP payload and to validate an incoming SOAP payload. A typical mapping table is shown below:

```c
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name"}
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"}, // MUST be first
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"}, // MUST be second
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"}, // MUST be third
    {"xsd", "http://www.w3.org/2001/XMLSchema"}, // Required for XML Schema types
    {"ns1", "urn:my-service-URI"}, // The namespace URI of the service operations
    {NULL, NULL} // end of table
};
```

Each namespace prefix used by a identifier name in the header file specification (see Section 10.3) MUST have a binding to a namespace URI in the mapping table. The end of the namespace mapping table MUST be indicated by the NULL pair. The namespace URI matching is case insensitive. A namespace prefix is distinguished by the occurrence of a pair of underscores (\_\_) in an identifier.

An optional namespace pattern MAY be provided with each namespace mapping table entry. The patterns provide an alternative namespace matching for the validation of decoded SOAP messages.
In this pattern, dashes (-) are single-character wildcards and asterisks (*) are multi-character wildcards. For example, to decode different versions of XML Schema type with different authoring dates, four dashes can be used in place of the specific dates in the namespace mapping table pattern:

```csharp
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name", "ns-name validation pattern"}

    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/-----/XMLSchema"},

...
```

Or alternatively, asterisks can be used as wildcards for multiple characters:

```csharp
struct Namespace namespaces[] =
{
    // {"ns-prefix", "ns-name", "ns-name validation pattern"}

    {"xsd", "http://www.w3.org/2001/XMLSchema", "http://www.w3.org/*/XMLSchema"},

...
```

A namespace mapping table is automatically generated together with a WSDL file for each namespace prefix that is used for a service operation specified in the header file. This namespace mapping table has entries for all namespace prefixes. The namespace URIs need to be filled in. These appear as http://tempuri.org in the table. See Section 19.2 on how to specify the namespace URIs in the header file.

For decoding elements with namespace prefixes, the namespace URI associated with the namespace prefix (through the xmlns attribute of an XML element) is searched from the beginning to the end in a namespace mapping table, and for every row the following tests are performed as part of the validation process:

1. the string in the second column matches the namespace URI (case insensitive)
2. the string in the optional third column matches the namespace URI (case insensitive), where - is a one-character wildcard and * is a multi-character wildcard

When a match is found, the namespace prefix in the first column of the table is considered semantically identical to the namespace prefix used by the XML element to be decoded, though the prefix names may differ. A service will respond with the namespace that it received from a client in case it matches a pattern in the third column.

For example, let’s say we have the following structs:

```csharp
struct a_elt { ... };
struct b_elt { ... };
struct k_elt { ... };
```
and a namespace mapping table in the program:

```c
struct Namespace namespaces[] =
{ // {"ns-prefix", "ns-name", "ns-name validation pattern"}
    ...
    {"a", "some uri"},
    {"b", "other uri"},
    {"c", "his uri", "* uri"},
    ...
}
```

Then, the following XML elements will match the structs:

```xml
<n:elt xmlns:n="some URI"> matches the struct name a_elt
...
<m:elt xmlns:m="other URI"> matches the struct name b_elt
...
<k:elt xmlns:k="my URI"> matches the struct name c_elt
...
```

The response of a service to a client request that uses the namespaces listed above, will include my URI for the name space of element k.

It is possible to use a number of different namespace tables and select the one that is appropriate. For example, an application might contact many different Web services all using different namespace URIs. If all the URIs are stored in one table, each service operation invocation will dump the whole namespace table in the SOAP payload. There is no technical problem with that, but it can be ugly when the table is large. To use different namespace tables, declare a pointer to a table and set the pointer to a particular table before service operation invocation. For example:

```c
struct Namespace namespacesTable1[] = {...};
struct Namespace namespacesTable2[] = {...};
struct Namespace namespacesTable3[] = {...};
struct Namespace *namespaces;
...
struct soap soap;
...
soap_init(&soap);
soap_set_namespaces(&soap, namespacesTable1);
soap_call_remote_method(&soap, URL, Action, ...);
...
```

## 11 gSOAP Serialization and Deserialization Rules

This section describes the serialization and deserialization of C and C++ data types for SOAP 1.1 and 1.2 compliant encoding and decoding.
11.1 SOAP RPC Encoding Versus Document/Literal and xsi:type Info

The wsdl2h tool automatically generates a header file specialized for SOAP RPC encoding or document/literal style. The serialization and deserialization rules for C/C++ objects is almost identical for these styles, except for the following important issues.

With SOAP RPC encoding style, care must be taken to ensure typed messages are produced for interoperability and compatibility reasons. To ensure that the gSOAP engine automatically generates typed (xsi:type attributed) messages, use soapcpp2 option -t, see also Section 9.1. While gSOAP can handle untyped messages, some toolkits fail to find deserializers when the xsi:type information is absent.

When starting the development of a gSOAP application from a header file, the soapcpp2 compiler will generate WSDL and schema files for SOAP 1.1 document/literal style by default (use the //gsoap directives to control this, see Section 19.2). Use soapcpp2 options -2, -e, and -t to generate code for SOAP 1.2, RPC encoding, and typed messages.

With SOAP RPC encoding, generic complexTypes with maxOccurs="unbounded" are not allowed and SOAP encoded arrays must be used. Also XML attributes and unions (XML schema choice) are not allowed with SOAP RPC encoding.

Also with SOAP RPC encoding, multi-reference accessors are common to encode co-referenced objects and object digraphs. Multi-reference encoding is not supported in document/literal style, which means that cyclic object digraphs cannot be serialized (the engine will crash). Also DAGs are represented as XML trees in document/literal style messaging.

11.2 Primitive Type Encoding

The default encoding rules for the primitive C and C++ data types are given in the table below:

<table>
<thead>
<tr>
<th>Type</th>
<th>XSD Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>bool</td>
<td>boolean</td>
</tr>
<tr>
<td>char* (C string)</td>
<td>string</td>
</tr>
<tr>
<td>char</td>
<td>byte</td>
</tr>
<tr>
<td>long double</td>
<td>decimal (with #import &quot;custom/long_double.h&quot;)</td>
</tr>
<tr>
<td>double</td>
<td>double</td>
</tr>
<tr>
<td>float</td>
<td>float</td>
</tr>
<tr>
<td>int</td>
<td>int</td>
</tr>
<tr>
<td>long</td>
<td>long</td>
</tr>
<tr>
<td>LONG64</td>
<td>long</td>
</tr>
<tr>
<td>long long</td>
<td>long</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
</tr>
<tr>
<td>time_t</td>
<td>dateTime</td>
</tr>
<tr>
<td>struct tm</td>
<td>dateTime (with #import &quot;custom/struct_tm.h&quot;)</td>
</tr>
<tr>
<td>unsigned char</td>
<td>unsignedByte</td>
</tr>
<tr>
<td>unsigned int</td>
<td>unsignedInt</td>
</tr>
<tr>
<td>unsigned long</td>
<td>unsignedLong</td>
</tr>
<tr>
<td>ULONG64</td>
<td>unsignedLong</td>
</tr>
<tr>
<td>unsigned long long</td>
<td>unsignedLong</td>
</tr>
<tr>
<td>unsigned short</td>
<td>unsignedShort</td>
</tr>
<tr>
<td>wchar_t*</td>
<td>string</td>
</tr>
</tbody>
</table>
Objects of type `void` and `void*` cannot be encoded. Enumerations and bit masks are supported as well, see 11.4.

### 11.3 How to Represent Primitive C/C++ Types as XSD Types

By default, encoding of the primitive types will take place as per SOAP encoding style. The encoding can be changed to any XML Schema type (XSD type) with an optional namespace prefix by using a `typedef` in the header file input to the gSOAP `soapcpp2` tool. The declaration enables the implementation of built-in XML Schema types (also known as XSD types) such as `positiveInteger`, `xsd:anyURI`, and `xsd:date` for which no built-in data structures in C and C++ exist but which can be represented using standard data structures such as strings, integers, and floats.

The `typedef` declaration is frequently used for convenience in C. A `typedef` declares a type name for a (complex) type expression. The type name can then be used in other declarations in place of the more complex type expression, which often improves the readability of the program code.

The gSOAP `soapcpp2` compiler interprets `typedef` declarations the same way as a regular C compiler interprets them, i.e. as types in declarations. In addition however, the gSOAP `soapcpp2` compiler will also use the type name in the encoding of the data in SOAP. The `typedef` name will appear as the XML element name of an independent element and as the value of the `xsi:type` attribute in the SOAP payload.

Many built-in primitive and derived XSD types such as `xsd:anyURI`, `positiveInteger`, and `decimal` can be stored by standard primitive data structures in C++, such as strings, integers, floats, and doubles. To serialize strings, integers, floats, and doubles as built-in primitive and derived XSD types, a `typedef` declaration can be used to declare an XSD type.

For example, the declaration

```c
typedef unsigned int xsd_positiveInteger;
```

creates a named type `xsd_positiveInteger` which is represented by `unsigned int` in C++. For example, the encoding of a `xsd_positiveInteger` value 3 is

```xml
<xsd_positiveInteger xsi:type="xsd:positiveInteger">3</xsd_positiveInteger>
```

The built-in primitive and derived numerical XML Schema types are listed below together with their recommended `typedef` declarations. Note that the SOAP encoding schemas for primitive types are derived from the built-in XML Schema types, so `SOAP_ENC_` can be used as a namespace prefix instead of `xsd_`.

- `xsd:anyURI` Represents a Uniform Resource Identifier Reference (URI). Each URI scheme imposes specialized syntax rules for URIs in that scheme, including restrictions on the syntax of allowed fragment identifiers. It is recommended to use strings to store `xsd:anyURI` XML Schema types. The recommended type declaration is:

```c
typedef char *xsd_anyURI;
```

- `xsd:base64Binary` Represents Base64-encoded arbitrary binary data. For using the `xsd:base64Binary` XSD Schema type, the use of the base64Binary representation of a dynamic array is **strongly**
recommended, see Section 11.12. However, the type can also be declared as a string and the encoding will be string-based:

```c
typedef char *xsd_base64Binary;
```

With this approach, it is the responsibility of the application to make sure the string content is according to the Base64 Content-Transfer-Encoding defined in Section 6.8 of RFC 2045.

**xsd:boolean** For declaring an `xsd:boolean` XSD Schema type, the use of a `bool` is strongly recommended. If a pure C compiler is used that does not support the `bool` type, see Section 11.4.5. The corresponding type declaration is:

```c
typedef bool xsd_boolean;
```

Type `xsd_boolean` declares a Boolean (0 or 1), which is encoded as

```xml
<xsd:boolean xsi:type="xsd:boolean">...
</xsd:boolean>
```

**xsd:byte** Represents a byte (-128...127). The corresponding type declaration is:

```c
typedef char xsd_byte;
```

Type `xsd_byte` declares a byte which is encoded as

```xml
<xsd:byte xsi:type="xsd:byte">...
</xsd:byte>
```

**xsd:dateTime** Represents a date and time. The lexical representation is according to the ISO 8601 extended format CCYY-MM-DDThh:mm:ss where "CC" represents the century, "YY" the year, "MM" the month and "DD" the day, preceded by an optional leading "-" sign to indicate a negative number. If the sign is omitted, "+" is assumed. The letter "T" is the date/time separator and "hh", "mm", "ss" represent hour, minute and second respectively. It is recommended to use the `time_t` type to store `xsd:dateTime` XSD Schema types and the type declaration is:

```c
typedef time_t xsd_dateTime;
```

However, note that calendar times before the year 1902 or after the year 2037 cannot be represented. Upon receiving a date outside this range, the `time_t` value will be set to -1.

Strings (`char*`) can be used to store `xsd:dateTime` XSD Schema types. The type declaration is:

```c
typedef char *xsd_dateTime;
```

In this case, it is up to the application to read and set the `dateTime` representation.

**xsd:date** Represents a date. The lexical representation for date is the reduced (right truncated) lexical representation for dateTime: CCYY-MM-DD. It is recommended to use strings (`char*`) to store `xsd:date` XSD Schema types. The type declaration is:

```c
typedef char *xsd_date;
```

**xsd:decimal** Represents arbitrary precision decimal numbers. It is recommended to use the `double` type to store `xsd:decimal` XSD Schema types and the type declaration is:
typedef double xsd_decimal;

Type xsd_decimal declares a double floating point number which is encoded as

<xsd:double xsi:type="xsd:decimal">…</xsd:double>

xsd:double Corresponds to the IEEE double-precision 64-bit floating point type. The type declaration is:

typedef double xsd_double;

Type xsd_double declares a double floating point number which is encoded as

<xsd:double xsi:type="xsd:double">…</xsd:double>

xsd:duration Represents a duration of time. The lexical representation for duration is the ISO 8601 extended format PnYn MnDTnH nMnS, where nY represents the number of years, nM the number of months, nD the number of days, T is the date/time separator, nH the number of hours, nM the number of minutes and nS the number of seconds. The number of seconds can include decimal digits to arbitrary precision. It is recommended to use strings (char*) to store xsd:duration XSD Schema types. The type declaration is:

typedef char *xsd_duration;

xsd:float Corresponds to the IEEE single-precision 32-bit floating point type. The type declaration is:

typedef float xsd_float;

Type xsd_float declares a floating point number which is encoded as

<xsd:float xsi:type="xsd:float">…</xsd:float>

xsd:hexBinary Represents arbitrary hex-encoded binary data. It has a lexical representation where each binary octet is encoded as a character tuple, consisting of two hexadecimal digits ([0-9a-fA-F]) representing the octet code. For example, "0FB7" is a hex encoding for the 16-bit integer 4023 (whose binary representation is 11110110111. For using the xsd:hexBinary XSD Schema type, the use of the hexBinary representation of a dynamic array is strongly recommended, see Section 11.13. However, the type can also be declared as a string and the encoding will be string-based:

typedef char *xsd_hexBinary;

With this approach, it is solely the responsibility of the application to make sure the string content consists of a sequence of octets.

xsd:int Corresponds to a 32-bit integer in the range -2147483648 to 2147483647. If the C++ compiler supports 32-bit int types, the type declaration can use the int type:

typedef int xsd_int;

Otherwise, the C++ compiler supports 16-bit int types and the type declaration should use the long type:
typedef long xsd_int;

Type xsd_int declares a 32-bit integer which is encoded as

<xsd:int xsi:type="xsd:int">...</xsd:int>

xsd:integer Corresponds to an unbounded integer. Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef long long xsd_integer;

Type xsd_integer declares a 64-bit integer which is encoded as an unbounded xsd:integer:

<xsd:integer xsi:type="xsd:integer">...</xsd:integer>

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:long Corresponds to a 64-bit integer in the range -922372036854775808 to 922372036854775807. The type declaration is:

typedef long long xsd_long;

Or in Visual C++:

typedef LONG64 xsd_long;

Type xsd_long declares a 64-bit integer which is encoded as

<xsd:long xsi:type="xsd:long">...</xsd:long>

xsd:negativeInteger Corresponds to a negative unbounded integer (< 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef long long xsd_negativeInteger;

Type xsd_negativeInteger declares a 64-bit integer which is encoded as a xsd:negativeInteger:

<xsd:negativeInteger xsi:type="xsd:negativeInteger">...</xsd:negativeInteger>

Another possibility is to use strings to represent unbounded integers and do the translation in code.

xsd:nonNegativeInteger Corresponds to a non-negative unbounded integer (≥ 0). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

typedef unsigned long long xsd_nonNegativeInteger;

Type xsd_nonNegativeInteger declares a 64-bit unsigned integer which is encoded as a non-negative unbounded xsd:nonNegativeInteger:

<xsd:nonNegativeInteger xsi:type="xsd:nonNegativeInteger">...</xsd:nonNegativeInteger>

Another possibility is to use strings to represent unbounded integers and do the translation in code.
**xsd:nonPositiveInteger** Corresponds to a non-positive unbounded integer \((\leq 0)\). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

```
typedef long long xsd__nonPositiveInteger;
```

Type `xsd__nonPositiveInteger` declares a 64-bit integer which is encoded as a `xsd:nonPositiveInteger`:

```
<xsd:nonPositiveInteger xsi:type="xsd:nonPositiveInteger">...</xsd:nonPositiveInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

**xsd:normalizedString** Represents normalized character strings. Normalized character strings do not contain the carriage return (\#xCD), line feed (\#xCA) nor tab (\#xC9) characters. It is recommended to use strings to store `xsd:normalizeString` XSD Schema types. The type declaration is:

```
typedef char *xsd__normalizedString;
```

Type `xsd__normalizedString` declares a string type which is encoded as

```
<xsd:normalizedString xsi:type="xsd:normalizedString">...</xsd:normalizedString>
```

It is solely the responsibility of the application to make sure the strings do not contain carriage return (\#xCD), line feed (\#xCA) and tab (\#xC9) characters.

**xsd:positiveInteger** Corresponds to a positive unbounded integer \((\geq 0)\). Since C++ does not support unbounded integers as a standard feature, the recommended type declaration is:

```
typedef unsigned long long xsd__positiveInteger;
```

Type `xsd__positiveInteger` declares a 64-bit unsigned integer which is encoded as a `xsd:positiveInteger`:

```
<xsd:positiveInteger xsi:type="xsd:positiveInteger">...</xsd:positiveInteger>
```

Another possibility is to use strings to represent unbounded integers and do the translation in code.

**xsd:short** Corresponds to a 16-bit integer in the range -32768 to 32767. The type declaration is:

```
typedef short xsd__short;
```

Type `xsd__short` declares a short 16-bit integer which is encoded as

```
<xsd:short xsi:type="xsd:short">...</xsd:short>
```

**xsd:string** Represents character strings. The type declaration is:

```
typedef char *xsd__string;
```

Type `xsd__string` declares a string type which is encoded as

```
<xsd:string xsi:type="xsd:string">...</xsd:string>
```

The type declaration for wide character strings is:

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typedef wchar_t *xsd_string;

Both type of strings can be used at the same time, but requires one typedef name to be changed by appending an underscore which is invisible in XML. For example:

typedef wchar_t *xsd_string_;

xsd:time Represents a time. The lexical representation for time is the left truncated lexical representation for dateTime: hh:mm:ss.sss with optional following time zone indicator. It is recommended to use strings (char*) to store xsd:time XSD Schema types. The type declaration is:

typedef char *xsd_time;

xsd:token Represents tokenized strings. Tokens are strings that do not contain the line feed (#xA) nor tab (#x9) characters, that have no leading or trailing spaces (#x20) and that have no internal sequences of two or more spaces. It is recommended to use strings to store xsd:token XSD Schema types. The type declaration is:

typedef char *xsd_token;

Type xsd_token declares a string type which is encoded as

<xsd:token xsi:type="xsd:token">...</xsd:token>

It is solely the responsibility of the application to make sure the strings do not contain the line feed (#xA) nor tab (#x9) characters, that have no leading or trailing spaces (#x20) and that have no internal sequences of two or more spaces.

xsd:unsignedByte Corresponds to an 8-bit unsigned integer in the range 0 to 255. The type declaration is:

typedef unsigned char xsdUnsignedByte;

Type xsdUnsignedByte declares a unsigned 8-bit integer which is encoded as

<xsd:unsignedByte xsi:type="xsd:unsignedByte">...</xsd:unsignedByte>

xsd:unsignedInt Corresponds to a 32-bit unsigned integer in the range 0 to 4294967295. If the C++ compiler supports 32-bit int types, the type declaration can use the int type:

typedef unsigned int xsdUnsignedInt;

Otherwise, the C++ compiler supports 16-bit int types and the type declaration should use the long type:

typedef unsigned long xsdUnsignedInt;

Type xsdUnsignedInt declares an unsigned 32-bit integer which is encoded as

<xsd:unsignedInt xsi:type="xsd:unsignedInt">...</xsd:unsignedInt>

xsd:unsignedLong Corresponds to a 64-bit unsigned integer in the range 0 to 18446744073709551615. The type declaration is:
typedef unsigned long long xsd__unsignedLong;

Or in Visual C++:

typedef ULONG64 xsd__unsignedLong;

Type xsd__unsignedLong declares an unsigned 64-bit integer which is encoded as

<xsd:unsignedLong xsi:type="xsd:unsignedLong">...</xsd:unsignedLong>

xsd:unsignedShort Corresponds to a 16-bit unsigned integer in the range 0 to 65535. The type declaration is:

typedef unsigned short xsd__unsignedShort;

Type xsd__unsignedShort declares an unsigned short 16-bit integer which is encoded as

<xsd:unsignedShort xsi:type="xsd:unsignedShort">...</xsd:unsignedShort>

Other XSD Schema types such as gYearMonth, gYear, gMonthDay, gDay, xsd:gMonth, QName, NOTATION, etc., can be encoded similarly using a typedef declaration.

11.3.1 How to Use Multiple C/C++ Types for a Single Primitive XSD Type

Trailing underscores (see Section 10.3) can be used in the type name in a typedef to enable the declaration of multiple storage formats for a single XML Schema type. For example, one part of a C/C++ application’s data structure may use plain strings while another part may use wide character strings. To enable this simultaneous use, declare:

typedef char *xsd__string;
typedef wchar_t *xsd__string;

Now, the xsd__string and xsd__string types will both be encoded and decoded as XML string types and the use of trailing underscores allows multiple declarations for a single XML Schema type.

11.3.2 How to Use C++ Wrapper Classes to Specify Polymorphic Primitive Types

SOAP 1.1 supports polymorphic types, because XSD Schema types form a hierarchy. The root of the hierarchy is called xsd:anyType (xsd:ur-type in the older 1999 schema). So, for example, an array of xsd:anyType in SOAP may actually contain any mix of element types that are the derived types of the root type. The use of polymorphic types is indicated by the WSDL and schema descriptions of a Web service and can therefore be predicted/expected for each particular case.

On the one hand, the typedef construct provides a convenient way to associate C/C++ types with XML Schema types and makes it easy to incorporate these types in a (legacy) C/C++ application. However, on the other hand the typedef declarations cannot be used to support polymorphic XML Schema types. Most SOAP clients and services do not use polymorphic types. In case they do, the primitive polymorphic types can be declared as a hierarchy of C++ classes that can be used simultaneously with the typedef declarations.

The general form of a primitive type declaration that is derived from a super type is:
where \textbf{Type} is a primitive C type. The \_\_item field MUST be the first field in this wrapper class.

For example, the XML Schema type hierarchy can be copied to C++ with the following declarations:

\begin{verbatim}
class xsd\_anyType { }
class xsd\_anySimpleType: public xsd\_anyType { }
typedef char *xsd\_anyURI;
class xsd\_anyURI: public xsd\_anySimpleType { public: xsd\_anyURI \_\_item; }
typedef bool xsd\_boolean;
class xsd\_boolean: public xsd\_anySimpleType { public: xsd\_boolean \_\_item; }
typedef char *xsd\_date;
class xsd\_date: public xsd\_anySimpleType { public: xsd\_date \_\_item; }
typedef time\_t xsd\_dateTime;
class xsd\_dateTime: public xsd\_anySimpleType { public: xsd\_dateTime \_\_item; }
typedef double xsd\_double;
class xsd\_double: public xsd\_anySimpleType { public: xsd\_double \_\_item; }
typedef char *xsd\_duration;
class xsd\_duration: public xsd\_anySimpleType { public: xsd\_duration \_\_item; }
typedef float xsd\_float;
class xsd\_float: public xsd\_anySimpleType { public: xsd\_float \_\_item; }
typedef char *xsd\_time;
class xsd\_time: public xsd\_anySimpleType { public: xsd\_time \_\_item; }
typedef char *xsd\_decimal;
class xsd\_decimal: public xsd\_anySimpleType { public: xsd\_decimal \_\_item; }
typedef char *xsd\_integer;
class xsd\_integer: public xsd\_decimal { public: xsd\_integer \_\_item; }
typedef LONG64 xsd\_long;
class xsd\_long: public xsd\_integer { public: xsd\_long \_\_item; }
typedef long xsd\_int;
class xsd\_int: public xsd\_long { public: xsd\_int \_\_item; }
typedef short xsd\_short;
class xsd\_short: public xsd\_int { public: xsd\_short \_\_item; }
typedef char xsd\_byte;
class xsd\_byte: public xsd\_short { public: xsd\_byte \_\_item; }
typedef char *xsd\_nonPositiveInteger;
class xsd\_nonPositiveInteger: public xsd\_integer { public: xsd\_nonPositiveInteger \_\_item; }
typedef char *xsd\_negativeInteger;
class xsd\_negativeInteger: public xsd\_nonPositiveInteger { public: xsd\_negativeInteger \_\_item; }
typedef char *xsd\_nonNegativeInteger;
class xsd\_nonNegativeInteger: public xsd\_integer { public: xsd\_nonNegativeInteger \_\_item; }
typedef char *xsd\_positiveInteger;
class xsd\_positiveInteger: public xsd\_nonNegativeInteger { public: xsd\_positiveInteger \_\_item; }
\end{verbatim}
typedef ULONG64 xsd_unsignedLong;
class xsd_unsignedLong: public xsd_nonNegativeInteger { public: xsd_unsignedLong _item; };
typedef unsigned long xsd_unsignedInt;
class xsd_unsignedInt: public xsd_unsignedLong { public: xsd_unsignedInt _item; };
typedef unsigned short xsd_unsignedShort;
class xsd_unsignedShort: public xsd_unsignedInt { public: xsd_unsignedShort _item; };
typedef unsigned char xsd_unsignedByte;
class xsd_unsignedByte: public xsd_unsignedShort { public: xsd_unsignedByte _item; };
typedef char *xsd_string;
class xsd_string: public xsd_anySimpleType { public: xsd_string _item; };
typedef char *xsd_normalizedString;
class xsd_normalizedString: public xsd_string { public: xsd_normalizedString _item; };
typedef char *xsd_token;
class xsd_token: public xsd_normalizedString { public: xsd_token _item; };

Note the use of the trailing underscores for the class names to distinguish the typedef type names from the class names. Only the most frequently used built-in schema types are shown. It is also allowed to include the xsd:base64Binary and xsd:hexBinary types in the hierarchy:

class xsd_base64Binary: public xsd_anySimpleType { public: unsigned char * _ptr; int _size; };
class xsd_hexBinary: public xsd_anySimpleType { public: unsigned char * _ptr; int _size; };


Methods are allowed to be added to the classes above, such as constructors and getter/setter methods, see Section 11.6.4.

Wrapper structs are supported as well, similar to wrapper classes. But they cannot be used to implement polymorphism. Rather, the wrapper structs facilitate the use of XML attributes with a primitive typed object, see 11.6.7.

11.3.3 XSD Schema Type Decoding Rules

The decoding rules for the primitive C and C++ data types is given in the table below:
<table>
<thead>
<tr>
<th>Type</th>
<th>Allows Decoding of</th>
<th>Precision Lost?</th>
</tr>
</thead>
<tbody>
<tr>
<td>bool</td>
<td>bool</td>
<td>no</td>
</tr>
<tr>
<td>char* (C string)</td>
<td>any type, see 11.3.5</td>
<td>no</td>
</tr>
<tr>
<td>wchar_t* (wide string)</td>
<td>any type, see 11.3.5</td>
<td>no</td>
</tr>
<tr>
<td>float</td>
<td>float</td>
<td>no</td>
</tr>
<tr>
<td>double</td>
<td>double</td>
<td>no</td>
</tr>
<tr>
<td>long</td>
<td>long</td>
<td>no</td>
</tr>
<tr>
<td>int</td>
<td>int</td>
<td>no</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
<td>no</td>
</tr>
<tr>
<td>byte</td>
<td>byte</td>
<td>no</td>
</tr>
<tr>
<td>unsignedLong</td>
<td>unsignedLong</td>
<td>no</td>
</tr>
<tr>
<td>unsignedInt</td>
<td>unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td>unsignedShort</td>
<td>unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td>unsignedByte</td>
<td>unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td>decimal</td>
<td>decimal</td>
<td>possibly</td>
</tr>
<tr>
<td>integer</td>
<td>integer</td>
<td>possibly</td>
</tr>
<tr>
<td>positiveInteger</td>
<td>positiveInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>negativeInteger</td>
<td>negativeInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>nonPositiveInteger</td>
<td>nonPositiveInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>nonNegativeInteger</td>
<td>nonNegativeInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>long long</td>
<td>long</td>
<td>no</td>
</tr>
<tr>
<td>int</td>
<td>int</td>
<td>no</td>
</tr>
<tr>
<td>short</td>
<td>short</td>
<td>no</td>
</tr>
<tr>
<td>byte</td>
<td>byte</td>
<td>no</td>
</tr>
<tr>
<td>unsignedLong</td>
<td>unsignedLong</td>
<td>possibly</td>
</tr>
<tr>
<td>unsignedInt</td>
<td>unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td>unsignedShort</td>
<td>unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td>unsignedByte</td>
<td>unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td>integer</td>
<td>integer</td>
<td>possibly</td>
</tr>
<tr>
<td>positiveInteger</td>
<td>positiveInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>negativeInteger</td>
<td>negativeInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>nonPositiveInteger</td>
<td>nonPositiveInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>nonNegativeInteger</td>
<td>nonNegativeInteger</td>
<td>possibly</td>
</tr>
<tr>
<td>Type</td>
<td>Allows Decoding of</td>
<td>Precision Lost?</td>
</tr>
<tr>
<td>--------------</td>
<td>--------------------</td>
<td>----------------------------------</td>
</tr>
<tr>
<td><strong>long</strong></td>
<td>xsd: long</td>
<td>possibly, if long is 32 bit</td>
</tr>
<tr>
<td></td>
<td>xsd: int</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: short</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: byte</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedLong</td>
<td>possibly</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>int</strong></td>
<td>xsd: int</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: short</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: byte</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedInt</td>
<td>possibly</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>short</strong></td>
<td>xsd: short</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: byte</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>char</strong></td>
<td>xsd: byte</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>possibly</td>
</tr>
<tr>
<td><strong>unsigned long long</strong></td>
<td>xsd: unsignedLong</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: positiveInteger</td>
<td>possibly</td>
</tr>
<tr>
<td></td>
<td>xsd: nonNegativeInteger</td>
<td>possibly</td>
</tr>
<tr>
<td><strong>unsigned long</strong></td>
<td>xsd: unsignedLong</td>
<td>possibly, if long is 32 bit</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>unsigned int</strong></td>
<td>xsd: unsignedInt</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>unsigned short</strong></td>
<td>xsd: unsignedShort</td>
<td>no</td>
</tr>
<tr>
<td></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>unsigned char</strong></td>
<td>xsd: unsignedByte</td>
<td>no</td>
</tr>
<tr>
<td><strong>time_t</strong></td>
<td>xsd: dateTime</td>
<td>no(?)</td>
</tr>
</tbody>
</table>
Due to limitations in representation of certain primitive C++ types, a possible loss of accuracy may occur with the decoding of certain XSD Schema types as is indicated in the table. The table does not indicate the possible loss of precision of floating point values due to the textual representation of floating point values in SOAP.

All explicitly declared XSD Schema encoded primitive types adhere to the same decoding rules. For example, the following declaration:

```c
typedef unsigned long long xsd__nonNegativeInteger;
```

enables the encoding and decoding of `xsd:nonNegativeInteger` XSD Schema types (although decoding takes place with a possible loss of precision). The declaration also allows decoding of `xsd:positiveInteger` XSD Schema types, because of the storage as an `unsigned long long` data type.

11.3.4 Multi-Reference Strings

If more than one `char` pointer points to the same string, the string is encoded as a multi-reference value. Consider for example

```c
char *s = "hello", *t = s;
```

The `s` and `t` variables are assigned the same string, and when serialized, `t` refers to the content of `s`:

```xml
<string id="123" xsi:type="string">hello</string>
...<string href="#123"/>
```

The example assumed that `s` and `t` are encoded as independent elements.

Note: the use of `typedef` to declare a string type such as `xsd__string` will not affect the multi-reference string encoding. However, strings declared with different `typedef`s will never be considered multi-reference even when they point to the same string. For example

```c
typedef char *xsd__string;
typedef char *xsd__anyURI;
xsd__anyURI *s = "http://www.myservice.com";
xsds__string *t = s;
```

The variables `s` and `t` point to the same string, but since they are considered different types their content will not be shared in the SOAP payload through a multi-referenced string.

11.3.5 “Smart String” Mixed-Content Decoding

The implementation of string decoding in gSOAP allows for mixed content decoding. If the SOAP payload contains a complex data type in place of a string, the complex data type is decoded in the string as plain XML text.

For example, suppose the `getInfo` service operation returns some detailed information. The service operation is declared as:
// Contents of header file "getInfo.h":
getInfo(char *detail);

The proxy of the service is used by a client to request a piece of information and the service responds with:

HTTP/1.1 200 OK
Content-Type: text/xml
Content-Length: nnn

xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/
xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance
xmlns:xsd="http://www.w3.org/2001/XMLSchema"
<SOAP-ENV:Body>
<getInfoResponse>
<detail>
<picture>Mona Lisa by <i>Leonardo da Vinci</i></picture>
</detail>
</getInfoResponse>
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>

As a result of the mixed content decoding, the detail string contains "<picture>Mona Lisa by <i>Leonardo da Vinci</i></picture>".

11.3.6 C++ Strings

gSOAP supports C++ strings std::string and std::wstring wide character strings. For example:

typedef std::string xsd_string;
class ns_myClass
{
 public:
  xsd_string s; // serialized with xsi:type="xsd:string"
  std::string t; // serialized without xsi:type
  ...
};

Caution: Please avoid mixing std::string and C strings (char*) in the header file when using SOAP 1.1 encoding. The problem is that multi-referenced strings in SOAP encoded messages cannot be assigned simultaneously to a std::string and a char* string.

11.3.7 Changing the Encoding Precision of float and double Types

The double encoding format is by default set to "%.18G" (see a manual on printf text formatting in C), i.e. at most 18 digits of precision to limit a loss in accuracy. The float encoding format is by default "%.9G", i.e. at most 9 digits of precision.

The encoding format of a double type can be set by assigning a format string to soap.double_format, where soap is a variable that contains the current runtime context. For example:
struct soap soap;
soap_init(&soap); // sets double_format = "%.18G"
soap.double_format = "%e"; // redefine

which causes all doubles to be encoded in scientific notation. Likewise, the encoding format of a float type can be set by assigning a format string to the static soap.float_format string variable. For example:

struct soap soap;
soap_init(&soap); // sets float_format = "%.9G"
soap.float_format = "%.4f"; // redefine

which causes all floats to be encoded with four digits precision.

**Caution:** The format strings are not automatically reset before or after SOAP communications. An error in the format string may result in the incorrect encoding of floating point values.

A special case for C format string patterns is introduced in gSOAP 2.8.18. A C format string that is used as a pattern for a typedef float or double in the gSOAP header file is used to format the output of the floating point value in XML. For example:

```
typedef float time_ratio "%.5f";
```

This will output the float with 5 digits total and 2 digits after the decimal point.

When xs:totalDigits and xs:_fractionDigits are given in a XSD file, then also a C format string is produced to output floating point values with the proper precision and scale. For example:

```
<simpleType name="ratio">
  <restriction base="xsd:float">
    <totalDigits value="5"/>
    <fractionDigits value="2"/>
  </restriction>
</simpleType>
```

### 11.3.8 INF, -INF, and NaN Values of float and double Types

The gSOAP runtime stdsoap2.cpp and header file stdsoap2.h support the marshalling of IEEE INF, -INF, and NaN representations. Under certain circumstances this may break if the hardware and/or C/C++ compiler does not support these representations. To remove the representations, remove the inclusion of the `<math.h>` header file from the stdsoap2.h file. You can control the representations as well, which are defined by the macros:

```
#define FLT_NAN
#define FLT_PINFTY
#define FLT_NINFTY
#define DBL_NAN
#define DBL_PINFTY
#define DBL_NINFTY
```
11.4 Enumeration Serialization

Enumerations are generally useful for the declaration of named integer-valued constants, also called enumeration constants.

11.4.1 Serialization of Symbolic Enumeration Constants

The gSOAP soapcpp2 tool encodes the constants of enumeration-typed variables in symbolic form using the names of the constants when possible to comply to SOAP’s enumeration encoding style. Consider for example the following enumeration of weekdays:

```c
enum weekday {Mon, Tue, Wed, Thu, Fri, Sat, Sun};
```

The enumeration-constant `Mon`, for example, is encoded as:

```xml
<weekday xsi:type="weekday">Mon</weekday>
```

The value of the `xsi:type` attribute is the enumeration-type identifier’s name. If the element is independent as in the example above, the element name is the enumeration-type identifier’s name. The encoding of complex types such as enumerations requires a reference to an XML Schema through the use of a namespace prefix. The namespace prefix can be specified as part of the enumeration-type identifier’s name, with the usual namespace prefix conventions for identifiers. This can be used to explicitly specify the encoding style. For example:

```c
enum ns1_weekday {Mon, Tue, Wed, Thu, Fri, Sat, Sun};
```

The enumeration-constant `Sat`, for example, is encoded as:

```xml
<n1:weekday xsi:type="ns1:weekday">Sat</ns1:weekday>
```

The corresponding XML Schema for this enumeration data type would be:

```xml
<xsd:element name="weekday" type="tns:weekday"/>
<xsd:simpleType name="weekday">
  <xsd:restriction base="xsd:string">
    <xsd:enumeration value="Mon"/>
    <xsd:enumeration value="Tue"/>
    <xsd:enumeration value="Wed"/>
    <xsd:enumeration value="Thu"/>
    <xsd:enumeration value="Fri"/>
    <xsd:enumeration value="Sat"/>
    <xsd:enumeration value="Sun"/>
  </xsd:restriction>
</xsd:simpleType>
```
11.4.2 Encoding of Enumeration Constants

If the value of an enumeration-typed variable has no corresponding named constant, the value is encoded as a signed integer literal. For example, the following declaration of a `workday` enumeration type lacks named constants for Saturday and Sunday:

```c
enum ns1_workday {Mon, Tue, Wed, Thu, Fri};
```

If the constant 5 (Saturday) or 6 (Sunday) is assigned to a variable of the `workday` enumeration type, the variable will be encoded with the integer literals 5 and 6, respectively. For example:

```xml
<ns1:workday xsi:type="ns1:workday">5</ns1:workday>
```

Since this is legal in C++ and SOAP allows enumeration constants to be integer literals, this method ensures that non-symbolic enumeration constants are correctly communicated to another party if the other party accepts literal enumeration constants (as with the gSOAP soapcpp2 tool).

Both symbolic and literal enumeration constants can be decoded.

To enforce the literal enumeration constant encoding and to get the literal constants in the WSDL file, use the following trick:

```c
enum ns1_nums { .1 = 1, .2 = 2, .3 = 3 };
```

The difference with an enumeration type without a list of values and the enumeration type above is that the enumeration constants will appear in the WSDL service description.

11.4.3 Initialized Enumeration Constants

The gSOAP soapcpp2 compiler supports the initialization of enumeration constants, as in:

```c
enum ns1_relation {LESS = -1, EQUAL = 0, GREATER = 1};
```

The symbolic names LESS, EQUAL, and GREATER will appear in the SOAP payload for the encoding of the `ns1_relation` enumeration values -1, 0, and 1, respectively.

11.4.4 How to “Reuse” Symbolic Enumeration Constants

A well-known deficiency of C and C++ enumeration types is the lack of support for the reuse of symbolic names by multiple enumerations. That is, the names of all the symbolic constants defined by an enumeration cannot be reused by another enumeration. To force encoding of the same symbolic name by different enumerations, the identifier of the symbolic name can end in an underscore (_) or any number of underscores to distinguish it from other symbolic names in C++. This guarantees that the SOAP encoding will use the same name, while the symbolic names can be distinguished in C++. Effectively, the underscores are removed from a symbolic name prior to encoding.

Consider for example:
enum ns1::workday {Mon, Tue, Wed, Thu, Fri};
enum ns1::weekday {Mon, Tue, Wed, Thu, Fri, Sat, Sun};

which will result in the encoding of the constants of enum ns1::weekday without the underscore, for example as Mon.

As an alternative to the trailing underscores that can get quite long for commonly used symbolic enum names, you can use the following convention with double underscores to add the enum name to the enum constants:

enum prefixedname { prefixedname::enumconst1, prefixedname::enumconst2, ...};

where the type name of the enumeration prefixedname is a prefixed name, such as:

enum ns1::workday { ns1::workday::Mon, ns1::workday::Tue, ns1::workday::Wed, ns1::workday::Thu,
                   ns1::workday::Fri };
enum ns1::weekday { ns1::workday::Mon, ns1::workday::Tue, ns1::workday::Wed, ns1::workday::Thu,
                   ns1::workday::Fri, ns1::workday::Sat, ns1::workday::Sun };  

This ensures that the XML schema enumeration values are still simply Mon, Tue, Wed, Thu, Fri, Sat, and Sun.

Caution: The following declaration:

enum ns1::workday {Mon, Tue, Wed, Thu, Fri};
enum ns1::weekday {Sat = 5, Sun = 6};

will not properly encode the weekday enumeration when you assume that workdays are part of weekdays, because it lacks the named constants for workday in its enumeration list. All enumerations must be self-contained and cannot use enum constants of other enumerations.

11.4.5 Boolean Enumeration Serialization for C

When developing a C Web service application, the C++ bool type should not be used since it is not usually supported by the C compiler. Instead, an enumeration type should be used to serialize true/false values as xsd:boolean Schema type enumeration values. The xsd:boolean XML Schema type is defined as:

enum xsd:boolean {false, true};

The value false, for example, is encoded as:

<xsd:boolean xsi:type="xsd:boolean">false</xsd:boolean>

Peculiar of the SOAP boolean type encoding is that it only defines the values 0 and 1, while the built-in XML Schema boolean type also defines the false and true symbolic constants as valid values. The following example declaration of an enumeration type lacks named constants altogether to force encoding of the enumeration values as literal constants:
### 11.4.6 Bitmask Enumeration Serialization

A bitmask is an enumeration of flags such as declared with C#’s [Flags] `enum` annotation. gSOAP supports bitmask encoding and decoding for interoperability. However, bitmask types are not standardized with SOAP RPC.

A special syntactic convention is used in the header file input to the gSOAP `soapcpp2` compiler to indicate the use of bitmasks with an asterisk:

```c
enum * name { enum-constant, enum-constant, ... };
```

The gSOAP `soapcpp2` compiler will encode the enumeration constants as flags, i.e. as a series of powers of 2 starting with 1. The enumeration constants can be or-ed to form a bitvector (bitmask) which is encoded and decoded as a list of symbolic values in SOAP. For example:

```c
enum * ns_.machineStatus { ON, BELT, VALVE, HATCH};
int ns_.getMachineStatus(char *name, char *enum ns_.machineStatus result);
```

Note that the use of the `enum` does not require the asterisk, only the definition. The gSOAP `soapcpp2` compiler generates the enumeration:

```c
enum ns_.machineStatus { ON=1, BELT=2, VALVE=4, HATCH=8};
```

A service operation implementation in a Web service can return:

```c
int ns_.getMachineStatus(struct soap *soap, char *name, enum ns_.machineStatus result)
{
    ... *result = BELT — HATCH;
    return SOAP_OK;
}
```

### 11.5 Struct Serialization

A `struct` data type is encoded as an XML Schema complexType (SOAP-encoded compound data type) such that the `struct` name forms the data type’s element name and schema type and the fields of the `struct` are the data type’s accessors. This encoding is identical to the `class` instance encoding without inheritance and method declarations, see Section 11.6 for further details. However, the encoding and decoding of `structs` is more efficient compared to `class` instances due to the lack of inheritance and the requirement by the serialization routines to check inheritance properties at run time.
Certain type of fields of a **struct** can be (de)serialized as XML attributes using the @ type qualifier. See Section 11.6.7 for more details.

See Section 10.3 for more details on the struct/class member field serialization and the resulting element and attribute qualified forms.

11.6 Class Instance Serialization

A **class** instance is serialized as an XML Schema complexType (SOAP-encoded compound data type) such that the **class** name forms the data type’s element name and schema type and the data member fields are the data type’s accessors. Only the data member fields are encoded in the SOAP payload. Class methods are not encoded.

The general form of a **class** declaration is:

```
class [namespace_prefix_]class_name1 [:[public:] [private:] [protected:] [namespace_prefix_]class_name2
{
    [public:] [private:] [protected:]
    field1;
    field2;
    ...
    [public:] [private:] [protected:]
    method1;
    method2;

};
```

where

- `namespace_prefix_` is the optional namespace prefix of the compound data type (see identifier translation rules 10.3)
- `class_name1` is the element name of the compound data type (see identifier translation rules 10.3).
- `class_name2` is an optional base class.
- `field` is a field declaration (data member). A field MAY be declared **static** and **const** and MAY be initialized.
- `method` is a method declaration. A method MAY be declared **virtual**, but abstract methods are not allowed. The method parameter declarations are REQUIRED to have parameter identifier names.
- `[public:] [private:] [protected:]` are OPTIONAL. Only members with **public** access permission can be serialized.

A class name is REQUIRED to be unique and cannot have the same name as a **struct**, **enum**, or service operation name specified in the header file input to the gSOAP soapcpp2 compiler. The
reason is that service operation requests are encoded similarly to class instances in SOAP and they are in principle undistinguishable (the method parameters are encoded just as the fields of a class).

Only single inheritance is supported by the gSOAP soapcpp2 compiler. Multiple inheritance is not supported, because of the limitations of the SOAP protocol.

If a constructor method is present, there MUST also be a constructor declaration with empty parameter list.

Classes should be declared “volatile” if you don’t want gSOAP to add serialization methods to these classes, see Section 19.4 for more details.

Class templates are not supported by the gSOAP soapcpp2 compiler, but you can use STL containers, see Section 11.11.8. You can also define your own containers similar to STL containers.

Certain type of fields of a struct can be (de)serialized as XML attributes using the @ type qualifier. See Section 11.6.7 for more details.

See Section 10.3 for more details on the struct/class member field serialization and the resulting element and attribute qualified forms.

Arrays may be embedded within a class (and struct) using a pointer field and size information, see Section 11.11.7. This defines what is sometimes referred to in SOAP as “generics”.

Void pointers may be used in a class (or struct), but you have to add a type field so the gSOAP runtime can determine the type of object pointed to, see Section 11.9.

A class instance is encoded as:

```xml
<![namespace-prefix:]class-name xsi:type="[namespace-prefix:]class-name">
<basefield-name1 xsi:type="...">...</basefield-name1>
<basefield-name2 xsi:type="...">...</basefield-name2>
...
<field-name1 xsi:type="...">...</field-name1>
<field-name2 xsi:type="...">...</field-name2>
...
</[namespace-prefix:]class-name>
```

where the field-name accessors have element-name representations of the class fields and the basefield-name accessors have element-name representations of the base class fields. (The optional parts resulting from the specification are shown enclosed in []).

The decoding of a class instance allows any ordering of the accessors in the SOAP payload. However, if a base class field name is identical to a derived class field name because the field is overloaded, the base class field name MUST precede the derived class field name in the SOAP payload for decoding. gSOAP guarantees this, but interoperability with other SOAP implementations is cannot be guaranteed.

11.6.1 Example

The following example declares a base class ns_Object and a derived class ns_Shape:

```c
// Contents of file "shape.h":
class ns_Object
```
public:
    char *name;
};
class ns::Shape : public ns::Object
{
    public:
    int sides;
    enum ns::Color {Red, Green, Blue} color;
    ns::Shape();
    ns::Shape(int sides, enum ns::Green color);
    ~ns::Shape();
};

The implementation of the methods of class ns::Shape must not be part of the header file and need to be defined elsewhere.

An instance of class ns::Shape with name Triangle, 3 sides, and color Green is encoded as:

    <ns:Shape xsi:type="ns:Shape">
      <name xsi:type="string">Triangle</name>
      <sides xsi:type="int">3</sides>
      <color xsi:type="ns:Color">Green</color>
    </ns:Shape>

The namespace URI of the namespace prefix ns must be defined by a namespace mapping table, see Section 10.4.

11.6.2 Initialized static const Fields

A data member field of a class declared as static const is initialized with a constant value at compile time. This field is encoded in the serialization process, but is not decoded in the deserialization process. For example:

    // Contents of file "triangle.h":
    class ns::Triangle : public ns::Object
    {
        public:
        int size;
        static const int sides = 3;
    };

An instance of class ns::Triangle is encoded in SOAP as:

    <ns:Triangle xsi:type="ns:Triangle">
      <name xsi:type="string">Triangle</name>
      <size xsi:type="int">15</size>
      <sides xsi:type="int">3</sides>
    </ns:Triangle>

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Decoding will ignore the `sides` field’s value.

**Caution:** The current gSOAP implementation does not support encoding **static const** fields, due to C++ compiler compatibility differences. This feature may be provided in the future.

### 11.6.3 Class Methods

A **class** declaration in the header file input to the gSOAP `soapcpp2` compiler MAY include method declarations. The method implementations MUST NOT be part of the header file but are required to be defined in another C++ source that is externally linked with the application. This convention is also used for the constructors and destructors of the **class**.

Dynamic binding is supported, so a method MAY be declared **virtual**.

### 11.6.4 Getter and Setter Methods

Setter and getter methods are invoked at run time upon serialization and deserialization of class instances, respectively. The use of setter and getter methods adds more flexibility to the serialization and deserialization process.

A setter method is called in the serialization phase from the virtual `soap_serialization` method generated by the gSOAP `soapcpp2` compiler. You can use setter methods to process a class instance just before it is serialized. A setter method can be used to convert application data, such as translating transient application data into serializable data, for example. You can also use setter methods to retrieve dynamic content and use it to update a class instance right before serialization. Remember setters as “set to serialize” operations.

Getter methods are invoked after deserialization of the instance. You can use them to adjust the contents of class instances after all their members have been deserialized. Getters can be used to convert deserialized members into transient members and even invoke methods to process the deserialized data on the fly.

Getter and setter methods have the following signature:

```c++
virtual int get(struct soap *soap) const;
virtual int set(struct soap *soap);
```

The active `soap` struct will be passed to the `get` and `set` methods. The methods should return SOAP_OK when successful. A setter method should prepare the contents of the class instance for serialization. A getter method should process the instance after deserialization.

Here is an example of a base64 binary class:

```c++
class xsd_base64Binary
{
  public:
    unsigned char *__ptr;
    int __size;
    int get(struct soap *soap);
    int set(struct soap *soap);
};
```
Suppose that the type and options members of the attachment should be set when the class is about 
to be serialized. This can be accomplished with the set method from the information provided by 
the _ptr to the data and the soap struct passed to the set method (you can pass data via the 
void*soap.user field).

The get method is invoked after the base64 data has been processed. You can use it for post-
processing purposes.

Here is another example. It defines a primitive update type. The class is a wrapper for the time_t 
type, see Section 11.3.2. Therefore, elements of this type contain xsd:dateType data.

```cpp
class update
{
public:
  time_t _item;
  int set(struct soap *soap);
};
```

The setter method assigns the current time:

```cpp
int update::set(struct soap *soap)
{
  this->_item = time(NULL);
  return SOAP_OK;
}
```

Therefore, serialization results in the inclusion of a time stamp in XML.

**Caution:** a get method is invoked only when the XML element with its data was completely parsed. 
The method is not invoked when the element is an xsi:nil element or has an href attribute.

**Caution:** The soap::serialize method of a class calls the setter (when provided). However, the 
soap::serialize method is declared const while the setter should be allowed to modify the contents 
of the class instance. Therefore, the gSOAP-generated code recasts the instance and the const is 
removed when invoking the setter.

### 11.6.5 Streaming XML with Getter and Setter Methods

Getter methods enable streaming XML operations. A getter method is invoked when the object 
is deserialized and the rest of the SOAP/XML message has not been processed yet. For example, 
you can add a getter method to the SOAP Header class to implement header processing logic that 
is activated as soon as the SOAP Header is received. An example code is shown below:

```cpp
class h__Authentication
{
public:
  char *id;
  int get(struct soap *soap);
};
class SOAP_ENV__Header
{
public:
  h__Authentication *h__authentication;
};
```
The Authentication SOAP Header field is instantiated and decoded. After decoding, the getter method is invoked, which can be used to check the id before the rest of the SOAP message is processed.

11.6.6 Polymorphism, Derived Classes, and Dynamic Binding

Interoperability between client and service applications developed with gSOAP is established even when clients and/or services use derived classes instead of the base classes used in the declaration of the service operation parameters. A client application MAY use pointers to instances of derived classes for the input parameters of a service operation. If the service was compiled with a declaration and implementation of the derived class, the service operation base class input parameters are demarshalled and a derived class instance is created instead of a base class instance. If the service did not include a declaration of the derived class, the derived class fields are ignored and a base class instance is created. Therefore, interoperability is guaranteed even when the client sends an instance of a derived classes and when a service returns an instance of a derived class.

The following example declares Base and Derived classes and a service operation that takes a pointer to a Base class instance and returns a Base class instance:

```c
// Contents of file "derived.h"
class Base {
    char *name;
    Base();
    virtual void print();
};
class Derived : public Base {
    int num;
    Derived();
    virtual void print();
};
int method(Base *in, struct methodResponse { Base *out; } &result);
```

This header file specification is processed by the gSOAP soapcpp2 compiler to produce the stub and skeleton routines which are used to implement a client and service. The pointer of the service operation is also allowed to point to Derived class instances and these instances will be marshalled as Derived class instances and send to a service, which is in accord to the usual semantics of parameter passing in C++ with dynamic binding.

The Base and Derived class method implementations are:

```c
// Method implementations of the Base and Derived classes:
#include "soapH.h"
... Base::Base()
```
cout << "created a Base class instance" << endl;
}
Derived::Derived()
{
    cout << "created a Derived class instance" << endl;
}
Base::print()
{
    cout << "print(): Base class instance " << name << endl;
}
Derived::print()
{
    cout << "print(): Derived class instance " << name << num << endl;
}

Below is an example CLIENT application that creates a Derived class instance that is passed as the input parameter of the service operation:

    // CLIENT
    #include "soapH.h"
    int main()
    {
        struct soap soap;
        soap_init(&soap);
        Derived obj1;
        Base *obj2;
        struct methodResponse r;
        obj1.name = "X";
        obj1.num = 3;
        soap_call_method(&soap, url, action, &obj1, r);
        r.obj2->print();
    }
    ...

The following example SERVER1 application copies a class instance (Base or Derived class) from the input to the output parameter:

    // SERVER1
    #include "soapH.h"
    int main()
    {
        soapServe(soap_new());
    }
    int method(struct soap *soap, Base *obj1, struct methodResponse &result)
    {
        obj1->print();
        result.obj2 = obj1;
        return SOAP_OK;
    }
    ...
The following messages are produced by the CLIENT and SERVER1 applications:

CLIENT: created a Derived class instance
SERVER1: created a Derived class instance
SERVER1: print(): Derived class instance X 3
CLIENT: created a Derived class instance
CLIENT: print(): Derived class instance X 3

Which indicates that the derived class kept its identity when it passed through SERVER1. Note that instances are created both by the CLIENT and SERVER1 by the demarshalling process.

Now suppose a service application is developed that only accepts Base class instances. The header file is:

// Contents of file "base.h":

class Base
{
    public:
        char *name;
        Base();
        virtual void print();
    
    int method(Base *in, Base *out);
};

This header file specification is processed by the gSOAP soapcpp2 tool to produce skeleton routine which is used to implement a service (so the client will still use the derived classes).

The method implementation of the Base class are:

// Method implementations of the Base class:
#include "soapH.h"
...
Base::Base()
{
    cout << "created a Base class instance" << endl;
}
Base::print()
{
    cout << "print(): Base class instance" << name << endl;
}

And the SERVER2 application is that uses the Base class is:

// SERVER2
#include "soapH.h"
int main()
{
    soap Serve(soap_new());
}
int method(struct soap *soap, Base *obj1, struct methodResponse &result)
Here are the messages produced by the CLIENT and SERVER2 applications:

CLIENT: created a Derived class instance
SERVER2: created a Base class instance
SERVER2: print(): Base class instance X
CLIENT: created a Base class instance
CLIENT: print(): Base class instance X

In this example, the object was passed as a Derived class instance to SERVER2. Since SERVER2 only implements the Base class, this object is converted to a Base class instance and send back to CLIENT.

11.6.7 XML Attributes

The SOAP RPC/LIT and SOAP DOC/LIT encoding styles support XML attributes in SOAP messages while SOAP RPC with “Section 5” encoding does not support XML attributes other than the SOAP and XSD specific attributes. SOAP RPC “Section 5” encoding has advantages for cross-language interoperability and data encodings such as graph serialization. However, RPC/LIT and DOC/LIT enables direct exchange of XML documents, which may include encoded application data structures. Language interoperability is compromised, because no mapping between XML and the typical language data types is defined. The meaning of the RPC/LIT and DOC/LIT XML content is Schema driven rather than application/language driven.

gSOAP supports XML attribute (de)serialization of members in structs and classes. Attributes are primitive XSD types, such as strings, enumerations, boolean, and numeric types. To declare an XML attribute in a struct/class, the qualifier @ is used with the type of the attribute. The type must be primitive type (including enumerations and strings), which can be declared with or without a typedef to associate a XSD type with the C/C++ type. For example

```c
typedef char *xsd_string;
typedef bool *xsd_boolean;
enum ns_state { 0, 1, 2 };
struct ns_myStruct
{
    @ xsd_string ns_type; // encode as XML attribute 'ns:type' of type 'xsd:string'
    @ xsd_boolean ns_flag = false; // encode as XML attribute 'ns:flag' of type 'xsd:boolean'
    @ enum ns_state ns_state = 2; // encode as XML attribute 'ns:state' of type 'ns:state'
    struct ns_myStruct *next;
};
```

The @ qualifier indicates XML attribute encoding for the ns_type, ns_flag, and ns_state fields. Note that the namespace prefix ns is used to distinguish these attributes from any other attributes such as xsi:type (ns:type is not to be confused with xsi:type).

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Default values can be associated with any field that has a primitive type in a struct/class, as is illustrated in this example. The default values are used when the receiving message does not contain the corresponding values.

String attributes are optional. Other type of attributes should be declared as pointers to make them optional:

```c
struct ns_.myStruct
{
  @int *a;  // omitted when NULL
};
```

Because a service operation request and response is essentially a struct, XML attributes can also be associated with method requests and responses. For example

```c
int ns_.myMethod(@char *ns_.name, ...);
```

Attributes can also be attached to the dynamic arrays, binary types, and wrapper classes/structs of primitive types. Wrapper classes are described in Section 11.3.2. For example

```c
struct xsd_.string
{
  char *_.item;
  @ xsd_.boolean flag;
};
```

and

```c
struct xsd_.base64Binary
{
  unsigned char *_.ptr;
  int _.size;
  @ xsd_.boolean flag;
};
```

The attribute declarations MUST follow the _.item, _.ptr, and _.size fields which define the characteristics of wrapper structs/classes and dynamic arrays.

**Caution:** Do not use XML attributes with SOAP RPC encoding. You can only use attributes with RPC literal encoding.

### 11.6.8 QName Attributes and Elements

gSOAP ensures the proper decoding of XSD QNames. An element or attribute with type QName (Qualified Name) contains a namespace prefix and a local name. You can declare a QName type as a `typedef char *xsd_.QName`. Values of type QName are internally handled as regular strings. gSOAP takes care of the proper namespace prefix mappings when deserializing QName values. For example
typedef char *xsd__QName;
struct ns__myStruct
{
  xsd__QName elt = "ns:xyz"; // QName element with default value "ns:xyz"
  @ xsd__QName att = "ns:abc"; // QName attribute with default value "ns:abc"
};

When the elt and att fields are serialized, their string contents are just transmitted (which means that the application is responsible to ensure proper formatting of the QName strings prior to transmission). When the fields are deserialized however, gSOAP takes care mapping the qualifiers to the appropriate namespace prefixes. Suppose that the inbound value for the elt is x:def, where the namespace name associated with the prefix x matches the namespace name of the prefix ns (as defined in the namespace mapping table). Then, the value is automatically converted into ns:def. If the namespace name is not in the table, then x:def is converted to "URI":def where "URI" is the namespace URI bound to x in the message received. This enables an application to retrieve the namespace information, whether it is in the namespace mapping table or not.

Note: QName is a pre-defined typedef type and used by gSOAP to (de)serialize SOAP Fault codes which are QName elements.

11.7 Union Serialization

A union is only serialized if the union is used within a struct or class declaration that includes a int _union field that acts as a discriminant or selector for the union fields. The selector stores run-time usage information about the union fields. That is, the selector is used to enumerate the union fields such that the gSOAP engine is able to select the correct union field to serialize.

A union within a struct or class with a selector field represents xs:choice within a Schema complexType component. For example:

```
struct ns__PO
{ ... };
struct ns__Invoice
{ ... };
union ns__PO_or_Invoice
{
  struct ns__PO po;
  struct ns__Invoice invoice;
};
struct ns__composite
{
  char *name;
  int _union;
  union ns__PO_or_Invoice value;
};
```

The union ns__PO_or_Invoice is expanded as a xs:choice:

```
<complexType name="composite">
  <sequence>
```
Therefore, the name of the union and field can be freely chosen. However, the union name should be qualified (as shown in the example) to ensure instances of XML Schemas with elementFormDefault="qualified" are correctly serialized (po and invoice are ns: qualified).

The int _union field selector’s values are determined by the soapcpp2 compiler. Each union field name has a selector value formed by:

```
SOAP_UNION_union-name_field-name
```

These selector values enumerate the union fields starting with 1. The value 0 (or any negative value) can be assigned to omit the serialization of the union, but only if explicitly allowed by validation rules, which requires minOccurs="0" for the xs:choice as follows:

```
struct ns_composite
{
    char *name;
    int _union 0; // <choice minOccurs="0">
    union ns_PO_or_Invoice value;
};
```

This way we can treat the union as an optional data item by setting _union=0.

Since 2.7.16 it is also possible to use a '§' as a special marker to annotate a selector field that must be of type int and the field name is no longer relevant:

```
struct ns_composite
{
    char *name;
    §int select 0; // <choice minOccurs="0">
    union ns_PO_or_Invoice value;
};
```

The following example shows how the struct ns_composite instance is initialized for serialization using the above declaration:

```
struct ns_composite data;
data.name = "...";
data.select = SOAP_UNION ns_PO_or_Invoice.po; // select PO
data.value.po.number = ...; // populate the PO
```

Note that failing to set the selector to a valid union field can lead to a crash of the gSOAP serializer because it will attempt to serialize an invalid union field.
For deserialization of union types, the selector will be set to one of the union field selector values, as determined by the XML payload. The selector will be set to 0 or -1 when no union member was deserialized, where a negative value indicates that a member was required by validation rules. Strict validation enabled with SOAP.XML_STRICT results in a validation fault.

When more than one union is used in a struct or class, the _union selectors must be renamed to avoid name clashes by using suffixes as in:

```c
struct ns_composite
{
    char *name;
    int sel_value; // = SOAP_UNION ns_PO_or_Invoice[po—invoice]
    union ns_PO_or_Invoice value;
    int sel_data; // = SOAP_UNION ns_Email_or_Fax[email—fax]
    union ns_Email_or_Fax data;
};
```

### 11.8 Serializing Pointer Types

The serialization of a pointer to a data type amounts to the serialization of the data type in SOAP and the SOAP encoded representation of a pointer to the data type is indistinguishable from the encoded representation of the data type pointed to.

#### 11.8.1 Multi-Referenced Data

A data structure pointed to by more than one pointer is serialized as SOAP multi-reference data. This means that the data will be serialized only once and identified with a unique id attribute. The encoding of the pointers to the shared data is done through the use of href or ref attributes to refer to the multi-reference data. See Section 9.12 on options to control the serialization of multi-reference data. To turn multi-ref off, use SOAP.XML_TREE to process plain tree-based XML. To completely eliminate multi-ref (de)serialization use the WITH_NOIDREF compile-time flag to permanently disable id-href processing. Cyclic C/C++ data structures are encoded with multi-reference SOAP encoding. Consider for example the following a linked list data structure:

```c
typedef char *xsd_string;
struct ns_list
{
    xsd_string value;
    struct ns_list *next;
};
```

Suppose a cyclic linked list is created. The first node contains the value "abc" and points to a node with value "def" which in turn points to the first node. This is encoded as:

```xml
<ns:list id="1" xsi:type="ns:list">
    <value xsi:type="xsd:string">abc</value>
    <next xsi:type="ns:list">
        <value xsi:type="xsd:string">def</value>
    </next>
</ns:list>
```
In case multi-referenced data is received that “does not fit in a pointer-based structure”, the data is copied. For example, the following two structs are similar, except that the first uses pointer-based fields while the other uses non-pointer-based fields:

```c
typedef long xsd_int;
struct ns_record
{
    xsd_int *a;
    xsd_int *b;
} P;
struct ns_record
{
    xsd_int a;
    xsd_int b;
} R;
```

```c
P.a = &n;
P.b = &n;
```

Since both `a` and `b` fields of `P` point to the same integer, the encoding of `P` is multi-reference:

```xml
<ns:record xsi:type="ns:record">
    <a href="#1"/>
    <b href="#1"/>
</ns:record>
{id id="1" xsi:type="xsd:int">123</id>
```

Now, the decoding of the content in the `R` data structure that does not use pointers to integers results in a copy of each multi-reference integer. Note that the two structs resemble the same XML data type because the trailing underscore will be ignored in XML encoding and decoding.

### 11.8.2 NULL Pointers and Nil Elements

A NULL pointer is not serialized, unless the pointer itself is pointed to by another pointer (but see Section 9.12 to control the serialization of NULLs). For example:

```c
struct X
{
    int *p;
    int **q;
}
```

Suppose pointer `q` points to pointer `p` and suppose `p=NULL`. In that case the `p` pointer is serialized as
and the serialization of q refers to href="#123". Note that SOAP 1.1 does not support pointer to pointer types (!), so this encoding is specific to gSOAP. The pointer to pointer encoding is rarely used in codes anyway. More common is a pointer to a data type such as a struct with pointer fields.

Caution: When the deserializer encounters an XML element that has a xsi:nil="true" attribute but the corresponding C++ data is not a pointer or reference, the deserializer will terminate with a SOAP_NULL fault when the SOAP_XML_STRICT flag is set. The types section of a WSDL description contains information on the “nilability” of data.

11.9 Void Pointers

In general, void pointers (void*) cannot be (de)serialized because the type of data referred to is untyped. To enable the (de)serialization of the void pointers that are members of structs or classes, you can insert a int _type field right before the void pointer field. The int _type field contains run time information on the type of the data pointed to by void* member in a struct/class to enable the (de)serialization of this data. The int _type field is set to a SOAP_TYPE_X value, where X is the name of a type. gSOAP generates the SOAP_TYPE_X definitions in soapH.h and uses them internally to uniquely identify the type of each object. The type naming conventions outlined in Section 7.5.3 are used to determine the type name for X.

Here is an example to illustrate the (de)serialization of a void* field in a struct:

```c
struct myStruct
{
  int _type; // the SOAP_TYPE pointed to by p
  void *p;
};
```

The _type integer can be set to 0 at run time to omit the serialization of the void pointer field.

The following example illustrates the initialization of myStruct with a void pointer to an int:

```c
struct myStruct S;
int n;
S.p = &n;
S._type = SOAP_TYPE_int;
```

The serialized output of S contains the integer.

The deserializer for myStruct will automatically set the _type field and void pointer to the deserialized data, provided that the XML content for p carries the xsi:type attribute from which gSOAP can determine the type.

Important: when (de)serializing strings via a void* field, the void* pointer MUST directly point to the string value rather than indirectly as with all other types. For example:

```c
struct myStruct S;
S.p = (void*)"Hello";
```
This is the case for all string-based types, including types defined with `typedef char*`.
You may use an arbitrary suffix with the `_type` fields to handle multiple void pointers in structs/classes. For example:

```c
struct myStruct
{
    int _typeOfp; // the SOAP_TYPE pointed to by p
    void *p;
    int _typeOfq; // the SOAP_TYPE pointed to by q
    void *q;
};
```

Because service method parameters are stored within structs, you can use `_type` and `void*` parameters to pass polymorphic arguments without having to define a C++ class hierarchy (Section 11.6.6). For example:

```c
typedef char *xsd_string;
typedef int xsd_int;
typedef float xsd_float;
enum ns_status { on, off };
struct ns_widget { xsd_string name; xsd_int part; }; int ns_myMethod(int _type, void *data,
struct ns_myMethodResponse { int _type; void *return_; } *out);
```

This method has a polymorphic input parameter `data` and a polymorphic output parameter `return_`. The `_type` parameters can be one of `SOAP_TYPE_xsd_string`, `SOAP_TYPE_xsd_int`, `SOAP_TYPE_xsd_float`, `SOAP_TYPE_ns_status`, or `SOAP_TYPE_ns_widget`. The WSDL produced by the gSOAP soapcpp2 compiler declares the polymorphic parameters of type `xsd:anyType` which is "too loose" and doesn't allow the gSOAP importer to handle the WSDL accurately. Future gSOAP releases might replace `xsd:anyType` with a `choice` schema type that limits the choice of types to the types declared in the header file.

### 11.10 Fixed-Size Arrays

Fixed size arrays are encoded as per SOAP 1.1 one-dimensional array types. Multi-dimensional fixed size arrays are encoded by gSOAP as nested one-dimensional arrays in SOAP. Encoding of fixed size arrays supports partially transmitted and sparse array SOAP formats.

The decoding of (multi-dimensional) fixed-size arrays supports the SOAP multi-dimensional array format as well as partially transmitted and sparse array formats.

An example:

```c
/* Contents of header file "fixed.h": */
struct Example
{
    float a[2][3];
};
```
This specifies a fixed-size array part of the `struct` Example. The encoding of array a is:

```xml
<a xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="float[][2]">
    <float xsi:type="float">...</float>
    <float xsi:type="float">...</float>
    <float xsi:type="float">...</float>
  </SOAP-ENC:Array>
    <float xsi:type="float">...</float>
    <float xsi:type="float">...</float>
    <float xsi:type="float">...</float>
  </SOAP-ENC:Array>
</a>
```

**Caution:** Any decoded parts of a (multi-dimensional) array that do not “fit” in the fixed size array are ignored by the deserializer.

### 11.11 Dynamic Arrays

As the name suggests, dynamic arrays are much more flexible than fixed-size arrays and dynamic arrays are better adaptable to the SOAP encoding and decoding rules for arrays. In addition, a typical C application allocates a dynamic array using `malloc`, assigns the location to a pointer variable, and deallocates the array later with `free`. A typical C++ application allocates a dynamic array using `new`, assigns the location to a pointer variable, and deallocates the array later with `delete`. Such dynamic allocations are flexible, but pose a problem for the serialization of data: how does the array serializer know the length of the array to be serialized given only a pointer to the sequence of elements? The application stores the size information somewhere. This information is crucial for the array serializer and has to be made explicitly known to the array serializer by packaging the pointer and array size information within a `struct` or `class`.

#### 11.11.1 SOAP Array Bounds Limits

SOAP encoded arrays use the `SOAP-ENC:Array` type and the `SOAP-ENC:arrayType` attribute to define the array dimensionality and size. As a security measure to avoid denial of service attacks based on sending a huge array size value requiring the allocation of large chunks of memory, the total number of array elements set by the `SOAP-ENC:arrayType` attribute cannot exceed `SOAP_MAXARRAYSIZE`, which is set to 100,000 by default. This constant is defined in `stdsoap2.h`. This constant **only** affects multi-dimensional arrays and the dimensionality of the receiving array will be lost when the number of elements exceeds 100,000. One-dimensional arrays will be populated in sequential order as expected.

#### 11.11.2 One-Dimensional Dynamic SOAP Arrays

A special form of `struct` or `class` is used to define one-dimensional dynamic SOAP-encoded arrays. Each array has a pointer variable and a field that records the number of elements the pointer points to in memory.
The general form of the `struct` declaration that contains a one-dimensional dynamic SOAP-encoded array is:

```c
struct some_name
{
    Type *_.ptr; // pointer to array of elements in memory
    int _size; // number of elements pointed to
    [static const] int __offset [= ...]; // optional SOAP 1.1 array offset
    ... // anything that follows here will be ignored
};
```

where `Type` MUST be a type associated with an XML Schema or MUST be a primitive type. If these conditions are not met, a vector-like XML (de)serialization is used (see Section 11.11.7). A primitive type can be used with or without a `typedef`. If the array elements are structs or classes, then the `struct/class` type names should have a namespace prefix for schema association, or they should be other (nested) dynamic arrays.

An alternative to a `struct` is to use a `class` with optional methods that MUST appear after the `_.ptr` and `_.size` fields:

```c
class some_name
{
    public:
        Type *_.ptr;
        int _size;
        [static const] int __offset [= ...];
        method1;
        method2;
        ... // any fields that follow will be ignored
};
```

To encode the data type as an array, the name of the `struct` or `class` SHOULD NOT have a namespace prefix, otherwise the data type will be encoded and decoded as a generic vector, see Section 11.11.7. The deserializer of a dynamic array can decode partially transmitted and/or SOAP sparse arrays, and even multi-dimensional arrays which will be collapsed into a one-dimensional array with row-major ordering.

**Caution:** SOAP 1.2 does not support partially transmitted arrays. So the `__offset` field of a dynamic array is ignored.

### 11.11.3 Example

The following example header file specifies the XMethods Service Listing service `getAllSOAPServices` service operation and an array of `SOAPService` data structures:

```c
// Contents of file "listing.h":
class ns3__SOAPService
{
    public:
```
An example client application:

```c++
#include "soapH.h" ...
// ServiceArray class method implementations:
ServiceArray::ServiceArray()
{
    _ptr = NULL;
    _size = 0;
}
ServiceArray::ServiceArray()
{ // destruction handled by gSOAP
}
void ServiceArray::print()
{
    for (int i = 0; i < _size; i++)
        cout << _ptr[i].name << ": " << _ptr[i].homepage << endl;
}

// Request a service listing and display results:
{
    struct soap soap;
    ServiceArray result;
    const char *endpoint = "www.xmethods.net:80/socket/rpcrouter";
```
const char *action = "urn:xmethodsServicesManager#getAllSOAPServices";
...
soap_init(&soap);
soap.call_ns_.getAllSOAPServices(&soap, endpoint, action, result);
result.print();
...
soap.destroy(&soap); // dealloc class instances
soap_end(&soap); // dealloc deserialized data
soap_done(&soap); // cleanup and detach soap struct
}

11.11.4 One-Dimensional Dynamic SOAP Arrays With Non-Zero Offset

The declaration of a dynamic array as described in 11.11 MAY include an int _offset field. When set to an integer value, the serializer of the dynamic array will use this field as the start index of the array and the SOAP array offset attribute will be used in the SOAP payload. Note that array offsets is a SOAP 1.1 specific feature which is not supported in SOAP 1.2.

For example, the following header file declares a mathematical Vector class, which is a dynamic array of floating point values with an index that starts at 1:

```
// Contents of file "vector.h":
typedef float xsd_float;
class Vector
{
xsd_float *_ptr;
int _size;
int _offset;
Vector();
Vector(int n);
float& operator[](int i);
}
```

The implementations of the Vector methods are:

```
Vector::Vector()
{
    _ptr = NULL;
    _size = 0;
    _offset = 1;
}
Vector::Vector(int n)
{
    _ptr = (float*)malloc(n*sizeof(float));
    _size = n;
    _offset = 1;
}
Vector::~Vector()
{
    if (_ptr)
```
An example program fragment that serializes a vector of 3 elements:

```c
struct soap soap;
soap_init(&soap);
Vector v(3);
v[1] = 1.0;
v[2] = 2.0;
v[3] = 3.0;
soap_begin(&soap);
v.serialize(&soap);
v.put("vec");
soap_end(&soap);
```

The output is a partially transmitted array:

```xml
  <item xsi:type="xsd:float">1.0</item>
  <item xsi:type="xsd:float">2.0</item>
  <item xsi:type="xsd:float">3.0</item>
</vec>
```

Note that the size of the encoded array is necessarily set to 4 and that the encoding omits the non-existent element at index 0.

The decoding of a dynamic array with an _offset field is more efficient than decoding a dynamic array without an _offset field, because the _offset field will be assigned the value of the SOAP-ENC:offset attribute instead of padding the initial part of the array with default values.

### 11.11.5 Nested One-Dimensional Dynamic SOAP Arrays

One-dimensional dynamic arrays MAY be nested. For example, using class Vector declared in the previous section, class Matrix is declared:

```c
class Matrix
{
public:
    Vector *ptr;
    int _size;
    int _offset;
    Matrix();
    Matrix(int n, int m);
    ~Matrix();
};
```
Vector& operator[](int i);

The Matrix type is essentially an array of pointers to arrays which make up the rows of a matrix. The encoding of the two-dimensional dynamic array in SOAP will be in nested form.

11.11.6 Multi-Dimensional Dynamic SOAP Arrays

The general form of the struct declaration for K-dimensional ($K > 1$) dynamic arrays is:

```c
struct some_name
{
    Type *._ptr;
    int _size[K];
    int _offset[K];
    ...  // anything that follows here will be ignored
};
```

where Type MUST be a type associated with an XML Schema, which means that it must be a typedefed type in case of a primitive type, or a struct/class name with a namespace prefix for schema association, or another dynamic array. If these conditions are not met, a generic vector XML (de)serialization is used (see Section 11.11.7).

An alternative is to use a class with optional methods:

```c
class some_name
{
    public:
    Type *._ptr;
    int _size[K];
    int _offset[K];
    method1;
    method2;
    ...  // any fields that follow will be ignored
};
```

In the above, $K$ is a constant denoting the number of dimensions of the multi-dimensional array.

To encode the data type as an array, the name of the struct or class SHOULD NOT have a namespace prefix, otherwise the data type will be encoded and decoded as a generic vector, see Section 11.11.7.

The deserializer of a dynamic array can decode partially transmitted multi-dimensional arrays.

For example, the following declaration specifies a matrix class:

```c
typedef double xsd_double;
class Matrix
{
    public:
    xsd_double *._ptr;
    int _size[2];
};
In contrast to the matrix class of Section 11.11.5 that defined a matrix as an array of pointers to matrix rows, this class has one pointer to a matrix stored in row-major order. The size of the matrix is determined by the _size field: _size[0] holds the number of rows and _size[1] holds the number of columns of the matrix. Likewise, _offset[0] is the row offset and _offset[1] is the columns offset.

### 11.11.7 Encoding XML Generics Containing Dynamic Arrays

The XML “generics” concept discussed in the SOAP encoding protocols extends the concept of a SOAP struct by allowing repetitions of elements within the struct. This is just a form of a repetition of XML elements without the SOAP-encoded array requirements. While SOAP-encoded arrays are more expressive (offset information to encode sparse arrays for example), simple repetitions of values are used more frequently.

A simple generic repetition is an array-like data structure with a repetition of an element. To achieve this, declare a dynamic array as a struct or class with a name that is qualified with a namespace prefix. SOAP arrays are declared without prefix.

For example, we define a Map structure that contains a sequence of pairs of key-val:

```c
struct ns_Map {
    int _size; // number of pairs
    struct ns_Binding {char *key; char *val;} *pair;
};
```

Since 2.7.16 it is also possible to use a '$' as a special marker to annotate a size field that must be of type int or size_t and the field name is no longer relevant:

```c
struct ns_Map {
    $int length; // number of pairs
    struct ns_Binding {char *key; char *val;} *pair;
};
```

This declares a dynamic array pointed to by pair and size _size. The array will be serialized and deserialized as a sequence of pairs:

```xml
<ns:Map xsi:type="ns:Map">
    <pair xsi:type="ns:Binding">
        <key>Joe</key>
        <val>555 77 1234</val>
    </pair>
    <pair xsi:type="ns:Binding">
        <key>Susan</key>
        <val>555 12 6725</val>
    </pair>
</ns:Map>
```

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Deserialization is less efficient compared to a SOAP-encoded array, because the size of the sequence is not part of the SOAP encoding. Internal buffering is used by the deserializer to collect the elements. When the end of the list is reached, the buffered elements are copied to a newly allocated space on the heap for the dynamic array.

Multiple arrays can be used in a struct/class to support the concept of “generics”. Each array results in a repetition of elements in the struct/class. This is achieved with a `int _size` (or `$int`) field in the struct/class where the next field (i.e. below the `_size` field) is a pointer type. The pointer type is assumed to point to an array of values at run time. The _size field holds the number of values at run time. Multiple arrays can be embedded in a struct/class with _size fields that have a distinct names. To make the _size fields distinct, you can end them with a unique name suffix such as _sizeOfstrings, for example.

The general convention for embedding arrays is:

```c
struct ns_SomeStruct
{
    ...
    int _size name1; // number of elements pointed to
    Type1 *field1; // by this field
    ...
    int _size name2; // number of elements pointed to
    Type2 *field2; // by this field
    ...
};
```

where `name1` and `name2` are identifiers used as a suffix to distinguish the _size field. These names can be arbitrary and are not visible in XML.

In 2.7.16 and higher this is simplified with a `$` marker:

```c
struct ns_SomeStruct
{
    ...
    $int name1; // number of elements pointed to
    Type1 *field1; // by this field
    ...
    $int name2; // number of elements pointed to
    Type2 *field2; // by this field
    ...
};
```

For example, the following struct has two embedded arrays:
struct ns__Contact
{
    char *firstName;
    char *lastName;
    int nPhones; // number of phones
    ULONG64 *phoneNumber; // array of phone numbers
    int nEmails; // number of emails
    char **emailAddress; // array of email addresses
    char *socSecNumber;
};

The XML serialization of an example ns__Contact is:

<mymycontact xsi:type="ns:Contact">
    <firstName>Joe</firstName>
    <lastName>Smith</lastName>
    <phoneNumber>5551112222</phoneNumber>
    <phoneNumber>5551234567</phoneNumber>
    <phoneNumber>5552348901</phoneNumber>
    <emailAddress>Joe.Smith@mail.com</emailAddress>
    <emailAddress>Joe@Smith.com</emailAddress>
    <socSecNumber>9999999999</socSecNumber>
</mymycontact>

11.11.8 STL Containers

gSOAP supports the STL containers std::deque, std::list, std::set, and std::vector.

STL containers can only be used within classes to declare members that contain multiple values. This is somewhat similar to the embedding of arrays in structs in C as explained in Section 11.11.7, but the STL container approach is more flexible.

You need to import stddeque.h, stllist.h, stlset.h, or stlvector.h to enable std::deque, std::list, std::set, and std::vector (de)serialization. Here is an example:

#import "stlvector.h"
class ns__myClass
{
    public:
        std::vector<int> *number;
        std::vector<xsd_string> *name;
    ...
};

The use of pointer members is not required but advised. The reason is that interoperability with other SOAP toolkits may lead to copying of ns__myClass instances at run time when (de)serializing multi-referenced data. When a copy is made, certain parts of the containers will be shared between the copies which could lead to disaster when the classes with their containers are deallocated. Another way to avoid this is to declare class ns__myClass within other data types via a pointer. (Interoperability between gSOAP clients and services does not lead to copying.)

The XML Schema that corresponds to the ns__myClass type is
<complexType name="myClass">
    <sequence>
        <element name="number" type="xsd:int" minOccurs="1" maxOccurs="unbounded"/>
        <element name="name" type="xsd:string" minOccurs="1" maxOccurs="unbounded"/>
        ...
    </sequence>
</complexType>

You can specify the minOccurs and maxOccurs values as explained in Section 19.2.

You can also implement your own containers similar to STL containers. The containers must be
class templates and should define an iterator type, and void clear(), iterator begin(), iterator end(), and
iterator insert(iterator pos, const_reference val). The iterator should have a dereference operator to access
the container’s elements. The dereference operator is used by gSOAP to send a sequence of XML
element values. The insert method can be used as a setter method. gSOAP reads a sequence of
XML element values and inserts them in the container via this method.

Here is an example user-defined container template class:

    // simpleVector.h
    template <class T>
    class simpleVector
    {
    public:
        typedef T value_type;
        typedef value_type * pointer;
        typedef const value_type * const_pointer;
        typedef value_type & reference;
        typedef const value_type & const_reference;
        typedef pointer iterator;
        typedef const pointer const_iterator;
    protected:
        iterator start;
        iterator finish;
        size_t length;
    public:
        simpleVector() { clear(); } // simpleVector() { delete[] start; }
        void clear() { start = finish = NULL; }
        iterator begin() { return start; }
        const_iterator begin() const { return start; }
        iterator end() { return finish; }
        const_iterator end() const { return finish; }
        size_t size() const { return finish-start; }
        iterator insert(iterator pos, const_reference val)
        {
            if (!start)
                start = finish = new value_type[length = 4];
            else if (finish >= start + length)
            {
                iterator i = start;
                iterator j = new value_type[2 * length];
            }
        }
To enable the container, we add the following two lines to our gSOAP header file:

```cpp
#include "simpleVector.h"

template <class T> class simpleVector;
```

The container class should not be defined in the gSOAP header file. It must be defined in a separate header file (e.g. "simpleVector.h"). The template `<class T> class simpleVector` declaration ensures that gSOAP will recognize `simpleVector` as a container class.

**Caution:** when parsing XML content the container elements may not be stored in the same order given in the XML content. When gSOAP parses XML it uses the insert container methods to store elements one by one. However, element content that is “forwarded” with `href` attributes will be appended to the container. Forwarding can take place with multi-referenced data that is referred to from the main part of the SOAP 1.1 XML message to the independent elements that carry `ids`. Therefore, your application should not rely on the preservation of the order of elements in a container.

### 11.11.9 Polymorphic Dynamic Arrays and Lists

Polymorphic arrays (arrays of polymorphic element types) can be encoded when declared as an array of pointers to class instances. For example:

```cpp
class ns__Object
{
    public:
    ...
};
class ns__Data: public ns__Object
{
    public:
```
The pointers in the array can point to the ns.Object base class or ns.Data derived class instances which will be serialized and deserialized accordingly in SOAP. That is, the array elements are polymorphic.

Since we can’t use dynamic binding to support polymorphism in C, another mechanism is available based on the serialization of void pointers, that is, dynamic serialization of data referenced by void pointers, see Section 11.9.

11.11.10 How to Change the Tag Names of the Elements of a SOAP Array or List

The _ptr field in a struct or class declaration of a dynamic array may have an optional suffix part that describes the name of the tags of the SOAP array XML elements. The suffix is part of the field name:

```
Type *._ptrarray_elt_name
```

The suffix describes the tag name to be used for all array elements. The usual identifier to XML translations apply, see Section 10.3. The default XML element tag name for array elements is item (which corresponds to the use of field name _ptritem).
Consider for example:

```c
struct ArrayOfstring
{
  xsd_string * __ptrstring; int __size; );
}
```

The array is serialized as:

```xml
<array xsi:type="SOAP-ENC:Array" SOAP-ENC:arrayType="xsd:string[2]">
  <string xsi:type="xsd:string">Hello</string>
  <string xsi:type="xsd:string">World</string>
</array>
```

SOAP 1.1 and 1.2 do not require the use of a specific tag name for array elements. gSOAP will deserialize a SOAP array while ignoring the tag names. Certain XML Schemas used in doc/literal encoding may require the declaration of array element tag names.

### 11.12 Base64Binary XML Schema Type Encoding

The `base64Binary` XML Schema type is a special form of dynamic array declared with a pointer (`_ptr`) to an `unsigned char` array.

For example using a `struct`:

```c
struct xsd_base64Binary
{
  unsigned char * __ptr;
  int __size;
};
```

Or with a `class`:

```c
class xsd_base64Binary
{
  public:
    unsigned char * __ptr;
    int __size;
};
```

When compiled by the gSOAP soapcpp2 tool, this header file specification will generate `base64Binary` serializers and deserializers.

The `SOAP_ENC_base64` encoding is another type for base 64 binary encoding specified by the SOAP data type schema and some SOAP applications may use this form (as indicated by their WSDL descriptions). It is declared by:

```c
struct SOAP_ENC_base64
{
  unsigned char * __ptr;
  int __size;
};
```
Or with a `class`:

```cpp
class SOAP_ENC_base64
{
    unsigned char * _ptr;
    int _size;
};
```

When compiled by the gSOAP `soapcpp2` tool, this header file specification will generate `SOAP-ENC:base64` serializers and deserializers.

The advantage of using a `class` is that methods can be used to initialize and manipulate the `_ptr` and `_size` fields. The user can add methods to this class to do this. For example:

```cpp
class xsd_base64Binary
{
    public:
    unsigned char * _ptr;
    int _size;
    xsd_base64Binary(); // Constructor
    xsd_base64Binary(struct soap *soap, int n); // Constructor
    ~xsd_base64Binary(); // Destructor
    unsigned char *location(); // returns the memory location
    int size(); // returns the number of bytes
};
```

Here are example method implementations:

```cpp
xsd_base64Binary::xsd_base64Binary()
{
    _ptr = NULL;
    _size = 0;
}

taxd_base64Binary::xsd_base64Binary(struct soap *soap, int n)
{
    _ptr = (unsigned char*)soap_malloc(soap, n);
    _size = n;
}
taxd_base64Binary::~xsd_base64Binary()
{
}
unsigned char *xsd_base64Binary::location()
{
    return _ptr;
}
int xsd_base64Binary::size()
{
    return _size;
}
```

The following example in C/C++ reads from a raw image file and encodes the image in SOAP using the `base64Binary` type:
FILE *fd = fopen("image.jpg", "rb");
xsd_base64Binary image(&soap, filesize(fd));
fread(image.location(), image.size(), 1, fd);
fclose(fd);
soap_begin(&soap);
image.soap_serialize(&soap);
image.soap_put(&soap, "jpegimage", NULL);
soap_end(&soap);
...

where filesize is a function that returns the size of a file given a file descriptor.

Reading the xsd:base64Binary encoded image.

... 
xsd_base64Binary image;
soap_begin(&soap);
image.get(&soap, "jpegimage");
soap_end(&soap);
...

The struct or class name soap_enc_base64 should be used for SOAP-ENC:base64 schema type instead of xsd_base64Binary.

11.13 hexBinary XML Schema Type Encoding

The hexBinary XML Schema type is a special form of dynamic array declared with the name xsd_hexBinary and a pointer (_ptr) to an unsigned char array.

For example, using a struct:

```
struct xsd_hexBinary
{
  unsigned char * _ptr;
  int _size;
};
```

Or using a class:

```
class xsd_hexBinary
{
  public:
    unsigned char * _ptr;
    int _size;
};
```

When compiled by the gSOAP soapcpp2 tool, this header file specification will generate base64Binary serializers and deserializers.
11.14 Literal XML Encoding Style

gSOAP supports document/literal encoding by default. Just as with SOAP RPC encoding, literal encoding requires the XML Schema of the message data to be provided e.g. in WSDL in order for the gSOAP soapcpp2 compiler to generate the (de)serialization routines. Alternatively, the optional DOM parser (dom.c and dom++.cpp) can be used to handle generic XML or arbitrary XML documents can be (de)serialized into regular C strings or wide character strings (wchar_t*) by gSOAP (see Section 11.14.1).

The `//gsoap service encoding`, `//gsoap service method-encoding`, and `//gsoap service method-response-encoding` directives explicitly enable SOAP encoded or literal encoded messages. For example, to enable RPC encoding style for the entire service, use:

```
//gsoap ns service encoding: encoded
```

To enable encoding for particular service methods, use:

```
//gsoap ns service method-encoding: myMethod encoded
int ns__myMethod(...)
```

To enable encoding for particular service methods responses when the method request is literal, use:

```
//gsoap ns service method-response-encoding: myMethod encoded
int ns__myMethod(...)
```

Instead of the `encoded` value, you can use `literal`, or a specific encoding style value.

Consider the following example that uses the directive to make the literal encoding explicit. The `LocalTimeByZipCode` service operation of the `LocalTime` service provides the local time given a zip code and uses literal encoding (with MS .NET). The following header file declares the method:

```
int LocalTimeByZipCode(char *ZipCode, char **LocalTimeByZipCodeResult);
```

Note that none of the data types need to be namespace qualified using namespace prefixes.

```
//gsoap ns service name: localtime
//gsoap ns service encoding: literal
//gsoap ns service namespace: http://alethea.net/webservices/
int ns__LocalTimeByZipCode(char *ZipCode, char **LocalTimeByZipCodeResult);
```

In this case, the method name requires to be associated with a schema through a namespace prefix, e.g. `ns` is used in this example. See Section 19.2 for more details on gSOAP directives. With these directives, the gSOAP soapcpp2 compiler generates client and server sources with the specified settings.

The example client program is:

```c
#include "soapH.h"
#include "localtime.nsmap" // include generated map file
```
int main()
{
    struct soap soap;
    char *t;
    soap.init(&soap);
        soap.print_fault(&soap, stderr);
    else
        printf("Time = %s\n", t);
    return 0;
}

To illustrate the manual doc/literal setting, the following client program sets the required properties before the call:

#include "soapH.h"
#include "localtime.nsmap" // include generated map file
int main()
{
    struct soap soap;
    char *t;
    soap.init(&soap);
    soap.encodingStyle = NULL; // don’t use SOAP encoding
    soap.set_omode(&soap, SOAP_XML_TREE);" // don’t produce multi-ref data (but can accept)
        soap.print_fault(&soap, stderr);
    else
        printf("Time = %s\n", t);
    return 0;
}

The SOAP request is:

POST /webservices/LocalTime.asmx HTTP/1.0
Host: alethea.net
Content-Type: text/xml; charset=utf-8
Content-Length: 479
SOAPAction: "http://alethea.net/webservices/LocalTimeByZipCode"

<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
    xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/"
    xmlns:SOAP-ENC="http://schemas.xmlsoap.org/soap/encoding/"
    xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
    xmlns:xsd="http://www.w3.org/2001/XMLSchema"
    xmlns:LocalTimeByZipCode="http://alethea.net/webservices/"
    xmlns:ZipCode="http://alethea.net/webservices/"
>
<LocalTimeByZipCode xmlns="http://alethea.net/webservices/">
<ZipCode>32306</ZipCode></LocalTimeByZipCode>
11.14.1 Serializing and Deserializing Mixed Content XML With Strings

To declare a literal XML “type” to hold XML documents in regular strings, use:

```c
typedef char *XML;
```

To declare a literal XML “type” to hold XML documents in wide character strings, use:

```c
typedef wchar_t *XML;
```

Note: only one of the two storage formats can be used. The differences between the use of regular strings versus wide character strings for XML documents are:

- Regular strings for XML documents MUST hold UTF-8 encoded XML documents. That is, the string MUST contain the proper UTF-8 encoding to exchange the XML document in SOAP messages.
- Wide character strings for XML documents SHOULD NOT hold UTF-8 encoded XML documents. Instead, the UTF-8 translation is done automatically by the gSOAP runtime marshalling routines.

Here is a C++ example of a service operation specification in which the parameters of the service operation uses literal XML encoding to pass an XML document to a service and back:

```c
typedef char *XML;
ns::GetDocument(XML m_XMLDoc, XML &m_XMLDoc);
```

and in C:

```c
typedef char *XML;
ns::GetDocument(XML m_XMLDoc, XML *m_XMLDoc);
```

The ns::Document is essentially a `struct` that forms the root of the XML document. The use of the underscore in the `ns::Document` response part of the message avoids the name clash between the `structs`. Assuming that the namespace mapping table contains the binding of `ns` to `http://my.org/` and the binding of `m` to `http://my.org/mydoc.xsd`, the XML message is:

```xml
<?xml version="1.0" encoding="UTF-8"?>
<SOAP-ENV:Envelope
 xmlns:SOAP-ENV="http://schemas.xmlsoap.org/soap/envelope/">
<SOAP-ENV:Body>
...XML content...
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```
When using literal encoding of method parameters and response as shown in the example above, the literal XML encoding style MUST be specified by setting soap.encodingStyle. For example, to specify no constraints on the encoding style (which is typical) use NULL:

```
struct soap soap;
soap_init(&soap);
soap.encodingStyle = NULL;
```

As a result, the SOAP-ENV:encodingStyle attribute will not appear in the SOAP payload.

For interoperability with Apache SOAP, use

```
struct soap soap;
soap_init(&soap);
soap.encodingStyle = "http://xml.apache.org/xml-soap/literalxml";
```

When the response parameter is an XML type, it will store the entire XML response content but without the enveloping response element.

The XML type can be used as part of any data structure to enable the rendering and parsing of custom XML documents. For example:

```
typedef char *XML;
struct ns_Data /* data in namespace 'ns' */
{
    int number;
    char *name;
    XML m_document; /* XML document in default namespace 'm' */
};
ns_Example(struct ns_Data data, struct ns_ExampleResponse { struct ns_Data data; } *out);
```

### 12 SOAP Fault Processing

A predeclared standard SOAP Fault data structure is generated by the gSOAP soapcpp2 tool for exchanging exception messages. The built-in struct SOAP_ENV_.Fault data structure is defined as:

```
struct SOAP_ENV_.Fault
{
    _QName faultcode; // _QName is builtin
```
The first four fields in SOAP_ENV_Fault are SOAP 1.1 specific. The last five fields are SOAP 1.2 specific. You can redefine these structures in the header file. For example, you can use a class for the SOAP_ENV_Fault and add methods for convenience.

The data structure content can be changed to the need of an application, but this is generally not necessary because the application-specific SOAP Fault details can be serialized via the _type and fault fields in the SOAP_ENV_Detail field, see Section 11.9 on the serialization of data refered to by _type and fault.

The _type field allows application data to be serialized as part of the SOAP Fault. The application data SHOULD be defined as XML elements, which requires you to declare the type names with a leading underscore to ensure that the types are compatible with XML elements and not just simpleTypes and complexTypes.

When the skeleton of a service operation returns an error (see Section 10.2), then soap.fault contains the SOAP Fault data at the receiving side (client).

Server-side faults are raised with soap_sender_fault or soap_receiver_fault. The soap_sender_fault call should be used to inform that the sender is at fault and the sender (client) should not resend the request. The soap_receiver_fault call should be used to indicate a temporary server-side problem, so a sender (client) can resend the request later. For example:

```c
int ns1__myMethod(struct soap *soap, ...)
{
    ...
    return soap_receiver_fault(soap, "Resource temporarily unavailable", NULL); // return fault to sender
}
```

In the example, the SOAP Fault details were empty (NULL). You may pass an XML fragment, which will be literally included in the SOAP Fault message. For WS-I Basic Profile compliance, you must pass an XML string with one or more namespace qualified elements, such as:
When a service operation must raise an exception with application SOAP Fault details, it does so by assigning the soap.fault field of the current reference to the runtime context with appropriate data associated with the exception and by returning the error SOAP_FAULT. For example:

```c
soap_receiver_fault(soap, "Stack dump", NULL);
if (soap->version == 2) // SOAP 1.2 is used
{
    soap->fault->SOAP_ENV__Detail = (struct SOAP_ENV__Detail*)malloc(soap, sizeof(struct SOAP_ENV__Detail);
    soap->fault->SOAP_ENV__Detail->type = SOAP_TYPE_ns1__myStackDataType; // stack type
    soap->fault->SOAP_ENV__Detail->fault = sp; // point to stack
    soap->fault->SOAP_ENV__Detail->any = NULL; // no other XML data
} else
{
    soap->fault->detail = (struct SOAP_ENV__Detail*)malloc(soap, sizeof(struct SOAP_ENV__Detail);
    soap->fault->detail->type = SOAP_TYPE_ns1__myStackDataType; // stack type
    soap->fault->detail->fault = sp; // point to stack
    soap->fault->detail->any = NULL; // no other XML data
}
return SOAP_FAULT; // return from service operation call
```

When `soap_receiver_fault` allocates a fault struct, this data is removed with the `soap_end` call (or `soap_dealloc`). Note that the `soap_receiver_fault` function is called to allocate the fault struct and set the fault string and detail fields, i.e. `soap_receiver_fault(soap, "Stack dump", NULL)`. The advantage is that this is independent of SOAP 1.1 and SOAP 1.2. However, setting the custom detail fields requires inspecting the SOAP version used, using the `soap->version` attribute which is 1 for SOAP 1.1 and 2 for SOAP 1.2.

Each service operation implementation in a service application can return a SOAP Fault upon an exception by returning an error code, see Section 7.2.1 for details and an example. In addition, a SOAP Fault can be returned by a service application through calling the `soap_send_fault` function. This is useful in case the initialization of the application fails, as illustrated in the example below:

```c
int main()
{
    struct soap soap;
    soap_init(&soap);
    some initialization code
    if (initialization failed)
    {
        soap.error = soap_receiver_fault(&soap, "Init failed", NULL); // set the error condition (SOAP_FAULT)
        soap_send_fault(&soap); // Send SOAP Fault to client
        return 0; // Terminate
    }
}
```
13 SOAP Header Processing

A predeclared standard SOAP Header data structure is generated by the gSOAP soapcpp2 tool for exchanging SOAP messages with SOAP Headers. This predeclared data structure is:

```c
struct SOAP_ENV__Header { };
```

which declares and empty header (some C and C++ compilers don’t accept empty structs, use compile flag -DWITH_NOEMPTYSTRUCT to avoid these errors).

To adapt the data structure to a specific need for SOAP Header processing, a new `struct SOAP_ENV__Header` can be added to the header file input to the gSOAP compiler. A `class` for the SOAP Header data structure can be used instead of a `struct`.

For example, the following header can be used for transaction control:

```c
struct SOAP_ENV__Header
{ char *t__transaction;
};
```

with client-side code:

```c
struct soap soap;
soap_init(&soap);
...
soap.header = NULL; // do not use a SOAP Header for the request (as set with soap_init)
soap.actor = NULL; // do not use an actor (receiver is actor)
soap.call_method(&soap, ...);
if (soap.header) // a SOAP Header was received
  cout << soap.header->t__transaction;
// Can reset, modify, or set soap.header here before next call
soap.call_method(&soap, ...); // reuse the SOAP Header of the service response for the request
...
```

The SOAP Web service response can include a SOAP Header with a transaction number that the client is supposed to use for the next service operation invocation to the service. Therefore, the next request includes a transaction number:

```xml
...<SOAP-ENV:Envelope ...>
<SOAP-ENV:Header>
<transaction xmlns="..." xsi:type="int">12345</transaction>
</SOAP-ENV:Header>
<SOAP-ENV:Body>
...
</SOAP-ENV:Body>
</SOAP-ENV:Envelope>
```

This is just an example and the transaction control is not a feature of SOAP but can be added on by the application layer to implement stateful transactions between clients and services. At the
client side, the `soap.actor` attribute can be set to indicate the recipient of the header (the SOAP `SOAP-ENV:actor` attribute).

A Web service can read and set the SOAP Header as follows:

```c
int main()
{
    struct soap soap;
    soap.actor = NULL; // use this to accept all headers (default)
    soap.actor = "http://some/actor"; // accept headers destined for "http://some/actor" only
    soap.serve(&soap);
}
...
14 MIME Attachments

The gSOAP toolkit supports MIME attachments as per SOAP with Attachments (SwA) specification (http://www.w3.org/TR/SOAP-attachments). In the following discussion, MIME attachment data is assumed to be resident in memory for sending operations and MIME attachments received will be stored in memory. MTOM and DIME attachments on the other hand can be streamed and therefore MTOM/DIME attachment data does not need to be stored in memory, see Section 15 and 16.

Transmitting multipart/related MIME attachments with a SOAP/XML message is accomplished with two functions, soap_set_mime and soap_set_mime_attachment. The first function is for initialization purposes and the latter function is used to specify meta data and content data for each attachment.

14.1 Sending a Collection of MIME Attachments (SwA)

The following functions should be used to set up a collection of multipart/related MIME attachments for transmission with a SOAP/XML message.
Function

```c
void soap_set_mime(struct soap *soap, const char *boundary, const char *start)
```

This function must be called first to initialize MIME attachment send operations (receives are automatic). The function specifies a MIME boundary and start content ID used for the SOAP message body. When `boundary` is NULL, an appropriate MIME boundary will be chosen (important: boundaries cannot occur in the SOAP/XML message and cannot occur in any of the MIME attachments content). When a specific boundary value is provided, gSOAP will NOT verify that the boundary is valid. When `start` is NULL, the start ID of the SOAP message is `<SOAP-ENV:Envelope>`.

```c
int soap_set_mime_attachment(struct soap *soap, char *ptr, size_t size, enum soap_mime_encoding encoding, const char *type, const char *id, const char *location, const char *description)
```

This function adds a new attachment to the list of attachments, where `ptr` and `size` refer to the block of memory that holds the attachment data. The `encoding` parameter specifies the content encoding of this block, where the value of `encoding` is one of `SOAP_MIME_7BIT`, `SOAP_MIME_8BIT`, `SOAP_MIME_BINARY`, `SOAP_MIME_QUOTED_PRINTABLE`, `SOAP_MIME_BASE64`, `SOAP_MIME_IETF_TOKEN`, or `SOAP_MIME_X_TOKEN`. These constants reflect the content encoding defined in RFC2045 and you MUST adhere to the content encoding rules defined by RFC2045. When in doubt, use `SOAP_MIME_BINARY`, since this encoding type covers any content. The mandatory `type` string parameter is the MIME type of the data. The `id` string parameter is the content ID of the MIME attachment. The optional `location` string parameter is the content location of the attachment. The optional `description` string parameter holds a textual description of the attachment (it may not contain any control characters). All parameter values are copied, except `ptr` which must point to a valid location of the attachment data during the transfer. The value `SOAP_OK` is returned when the attachment was added. Otherwise a gSOAP error code is returned.

```c
void soap_clr_mime(struct soap *soap)
```

Disables MIME attachments, e.g. to avoid MIME attachments to be part of a SOAP Fault response message.

When providing a MIME boundary with `soap_set_mime`, you have to make sure the boundary cannot match any SOAP/XML message content. Or you can simply pass NULL and let gSOAP select a safe boundary for you.

The internal list of attachments is destroyed with `soap_end`, you should call this function sometime after the message exchange was completed (the content of the block of memory referred to by the `ptr` parameter is unaffected).

The following example shows how a multipart/related HTTP message with three MIME attachments is set up and transmitted to a server. The first attachment contains the SOAP message. The second and third attachments contain image data. In this example we let the SOAP message body refer to the attachments using `href` attributes. The `struct claim_form` data type includes a definition of a href attribute for this purpose.

```c
struct claim_form form1, form2;
form1.href = "cid:claim061400a.tiff@claiming-it.com";
form2.href = "cid:claim061400a.jpeg@claiming-it.com";
/* initialize and enable MIME */
soap_set_mime(soap, "MIME_boundary", "<claim061400a.xml@claiming-it.com>");
/* add a base64 encoded tiff image (tiffImage points to base64 data) */
soap_set_mime_attachment(soap, tiffImage, tiffLen, SOAP_MIME_BASE64, "image/tiff",
    "<claim061400a.tiff@claiming-it.com>", NULL, NULL);
/* add a raw binary jpeg image (jpegImage points to raw data) */
```
Note: the above example assumes that the boundary `MIME_boundary` does not match any part of the SOAP/XML message.

The `claim_form` struct is declared in the gSOAP header file as:

```c
struct claim_form {
    char *href;
};
```

This data type defines the parameter data of the operation. The claim forms in the SOAP/XML message consist of `href` to the claim forms attached. The produced message is similar to the last example shown in the SOAP with Attachments specification (http://www.w3.org/TR/SOAP-attachments). Note that the use of `href` or other attributes for referring to the MIME attachments is optional according to the SwA standard.

To associate MIME attachments with the request and response of a service operation in the generated WSDL, please see Section 16.1.

The server-side code to transmit MIME attachments back to a client is similar:

```c
int claim_insurance_claim_auto(struct soap *soap, ...) {
    soap_set_mime(soap, NULL, NULL); // enable MIME
    // add a HTML document (htmlDoc points to data, where the HTML doc is stored in compliance with 7bit encoding RFC2045)
    if (soap_set_mime_attachment(soap, htmlDoc, strlen(htmlDoc), SOAP_MIME_7BIT, "text/html", "<claim061400a.html@claiming-it.com>", NULL, NULL))
    {
        soap_clr_mime(soap); // don't want fault with attachments
        return soap->error;
    }
    return SOAP_OK;
}
```

It is also possible to attach data to a SOAP fault message.

**Caution:** DIME in MIME is supported. However, gSOAP will not verify whether the MIME boundary is present in the DIME attachments and therefore will not select a boundary that is guaranteed to be unique. Therefore, you must provide a MIME boundary with `soap_set_mime` that is unique when using DIME in MIME.
14.2 Retrieving a Collection of MIME Attachments (SwA)

MIME attachments are automatically parsed and stored in memory. After receiving a set of MIME attachments, either at the client-side or the server-side, the list of MIME attachments can be traversed to extract meta data and the attachment content. The first attachment in the collection of MIME attachments always contains meta data about the SOAP message itself (because the SOAP message was processed the attachment does not contain any useful data).

To traverse the list of MIME attachments in C, you use a loop similar to:

```c
struct soap_multipart *attachment;
for (attachment = soap.mime.list; attachment; attachment = attachment->next)
{
    printf("MIME attachment:\n");
    printf("Memory=%p\n", (*attachment).ptr);
    printf("Size=%ul\n", (*attachment).size);
    printf("Encoding=%d\n", (*attachment).encoding);
    printf("Type=%s\n", (*attachment).type?(*attachment).type:"null");
    printf("ID=%s\n", (*attachment).id?(*attachment).id:"null");
    printf("Location=%s\n", (*attachment).location?(*attachment).location:"null");
    printf("Description=%s\n", (*attachment).description?(*attachment).description:"null");
}
```

C++ programmers can use an iterator instead, as in:

```c
for (soap_multipart::iterator attachment = soap.mime.begin(); attachment != soap.mime.end(); ++attachment)
{
    cout << "MIME attachment:" << endl;
    cout << "Memory=" << (void*)(*attachment).ptr << endl;
    cout << "Size=" << (*attachment).size << endl;
    cout << "Encoding=" << (*attachment).encoding << endl;
    cout << "Type=" << ((*attachment).type?(*attachment).type:"null") << endl;
    cout << "ID=" << ((*attachment).id?(*attachment).id:"null") << endl;
    cout << "Location=" << ((*attachment).location?(*attachment).location:"null") << endl;
    cout << "Description=" << ((*attachment).description?(*attachment).description:"null") << endl;
}
```

Note: keep in mind that the first attachment is associated with the SOAP message and you may want to ignore it.

A call to `soap_end` removes all of the received MIME data. To preserve an attachment in memory, use `soap_unlink` on the `ptr` field of the `soap_multipart` struct. Recall that the `soap_unlink` function is commonly used to prevent deallocation of deserialized data.

15 DIME Attachments

The gSOAP toolkit supports DIME attachments as per DIME specification, see http://msdn.microsoft.com/library/us/dnglobspec/html/draft-nielsen-dime-02.txt
Applications developed with gSOAP can transmit binary DIME attachments with or without streaming messages. Without streaming, all data is stored and retrieved in memory, which can be prohibitive when transmitting large files on small devices. The maximum DIME attachment size is limited to 8 MB by default as set with SOAP_MAXDIMESIZE in stdsoap2.h. In contrast, with DIME streaming, data handlers are used to pass the data to and from a resource, such as a file or device. With DIME output streaming, raw binary data is sent from a data source in chunks on the fly without buffering the entire content to save memory. With DIME input streaming, raw binary data will be passed to data handlers (callbacks).

15.1 Sending a Collection of DIME Attachments

The following functions can be used to explicitly set up a collection of DIME attachments for transmission with a SOAP/XML message body. The attachments can be streamed, as described in Section 15.4. Without streaming, each attachment must refer to a block of data in memory.

**Function**

```c
void soap_set_dime(struct soap *soap)
This function must be called first to initialize DIME attachment send operations (receives are automatic).
```

```c
int soap_set_dime_attachment(struct soap *soap, char *ptr, size_t size, const char *type, const char *id, unsigned short optype, const char *option)
This function adds a new attachment to the list of attachments, where ptr and size refer to the block of memory that holds the attachment data (except when DIME streaming callback handlers are used as described in Section 15.4. The type string parameter is the MIME type of the data. The id string parameter is the content ID of the DIME attachment. The option string parameter holds optional text (gSOAP supports DIME options, but it can send only one) and optype is a user-defined option type (as per DIME option specification format). All parameter values are copied, except ptr. The value SOAP_OK is returned when the attachment was added. Otherwise a gSOAP error code is returned.
```

```c
void soap_clr_dime(struct soap *soap)
Disables DIME attachments, unless the serialized SOAP message contains attachments for transmission.
```

These functions allow DIME attachments to be added without requiring message body references. This is also referred to as the open DIME attachment style. The closed attachment style requires all DIME attachments to be referenced from the SOAP message body with href (or similar) references. For the closed style, gSOAP supports an automatic binary data serialization method, see Section 15.3.

15.2 Retrieving a Collection of DIME Attachments

DIME attachments are automatically parsed and stored in memory (or passed to the streaming handlers, when applicable). After receiving a set of DIME attachments, either at the client-side or the server-side, the list of DIME attachments can be traversed to extract meta data and the attachment content.

To traverse the list of DIME attachments in C, you use a loop similar to:
struct soap_multipart *attachment;
for (attachment = soap.dime.list; attachment; attachment = attachment->next)
{
    printf("DIME attachment:\n");
    printf("Memory=%p\n", (*attachment).ptr);
    printf("Size=%ul\n", (*attachment).size);
    printf("Type=%s\n", (*attachment).type?(*attachment).type:"null");
    printf("ID=%s\n", (*attachment).id?(*attachment).id:"null");
}

C++ programmers can use an iterator instead, as in:

for (soap_multipart::iterator attachment = soap.dime.begin(); attachment != soap.dime.end(); ++attachment)
{
    cout << "DIME attachment:" << endl;
    cout << "Memory=" << (void*)(*attachment).ptr << endl;
    cout << "Size=" << (*attachment).size << endl;
    cout << "Type=" << ((*attachment).type?(*attachment).type:"null") << endl;
    cout << "ID=" << ((*attachment).id?(*attachment).id:"null") << endl;
}

The options field is available as well. The options content is formatted according to the DIME specification: the first two bytes are reserved for the option type, the next two bytes store the size of the option data, followed by the (binary) option data.

A call to soap_end removes all of the received DIME data. To preserve an attachment in memory, use soap_unlink on the ptr field of the soap_multipart struct. Recall that the soap_unlink function is commonly used to prevent deallocation of deserialized data.

15.3 Serializing Binary Data in DIME

Binary data stored in extended xsd:base64Binary and xsd:hexBinary types can be serialized and deserialized as DIME attachments. These attachments will be transmitted prior to the sequence of secondary DIME attachments defined by the user with soap_set_dime_attachment as explained in the previous section. The serialization process is automated and DIME attachments will be send even when soap_set_dime or soap_set_dime_attachment are not used.

The xsd:base64Binary XSD type is defined in gSOAP as a struct or class by

```c
struct xsd_base64Binary
{
    unsigned char * _ptr; // pointer to raw binary data
    int _size; // size of the block of data
};
```

To enable serialization of the data in DIME, we extend this type with three additional fields:

```c
struct xsd_base64Binary
{
```
unsigned char *-_ptr;
int _size;
char *id;
char *type;
char *options;
};

The three additional fields consist of an id field for attachment referencing (typically a content id (CID) or UUID), a type field to specify the MIME type of the binary data, and an options field to piggy-back additional information with a DIME attachment. The order of the declaration of the fields is significant. In addition, no other fields or methods may be declared before any of these fields in the struct/class, but additional fields and methods may appear after the field declarations.

An extended xsd_hexBinary declaration is similar.

The id and type fields contain text. The set the DIME-specific options field, you can use the soap_dime_option function:

```
char *soap_dime_option(struct soap *soap, unsigned short type, const char *option)
```

returns a string with this encoding. For example

```
struct xsd_base64Binary image;
image._ptr = ...;
image._size = ...;
image.id = "uuid:09233523-345b-4351-b623-5dsf35sge5d6";
image.type = "image/jpeg";
image.options = soap_dime_option(soap, 0, "My wedding picture");
```

When either the id or type field values are non-NULL at run time, the data will be serialized as a DIME attachment. The SOAP/XML message refers to the attachments using href attributes. This generally works will with SOAP RPC, because href attributes are permitted. However, with document/literal style the referencing mechanism must be explicitly defined in the schema of the binary type. The gSOAP declaration of an extended binary type is

```
struct ns_myBinaryDataType
{
   unsigned char *-_ptr;
   int _size;
   char *id;
   char *type;
   char *options;
};
```

C++ programmers can use inheritance instead of textual extension required in C, as in

```
class xsd_base64Binary
{
   unsigned char *-_ptr;
   int _size;
};
```
This defines an extension of \texttt{xsd:base64Binary}, such that the data can be serialized as DIME attachments using \texttt{href} attributes for referencing. When a different attribute name is in fact used, it must be explicitly defined:

\begin{verbatim}
struct ns\_myBinaryDataType
{
    unsigned char *\_ptr;
    int \_size;
    char *id;
    char *type;
    char *options;
    @char *WSref\_location;
};
\end{verbatim}

The example above uses the \texttt{location} attribute defined in the content reference schema, as defined in one of the vendor's specific WSDL extensions for DIME (http://www.gotdotnet.com/team/xml\_wsspecs/dime/WSDL-Extension-for-DIME.htm).

When receiving DIME attachments, the DIME meta data and binary data content is stored in binary data types only when the XML parts of the message uses \texttt{href} attributes to refer to these attachments. The gSOAP toolkit may support automatic (de)serialization with other user-defined (or WSDL-defined) attributes in future releases.

Messages may contain binary data that references external resources not provided as attachments. In that case, the \texttt{\_ptr} field is NULL and the \texttt{id} field refers to the external data source.

The \texttt{dime\_id\_format} attribute of the current gSOAP run-time context can be set to the default format of DIME id fields. The format string MUST contain a \texttt{%d} format specifier (or any other int-based format specifier). The value of this specifier is a non-negative integer, with zero being the value of the DIME attachment id for the SOAP message. For example,

\begin{verbatim}
struct soap soap;
soap\_init(&soap);
soap.dime\_id\_format = "uuid:09233523-345b-4351-b623-5dsf35sgs5d6-%x";
\end{verbatim}

As a result, all attachments with a NULL \texttt{id} field will use a gSOAP-generated \texttt{id} value based on the format string.

\textbf{Caution:} Care must be taken not to introduce duplicate content \texttt{id} values, when assigning content \texttt{id} values to the \texttt{id} fields of DIME extended binary data types. Content \texttt{id}s must be unique.
15.4 Streaming DIME

Streaming DIME is achieved with callback functions to fetch and store data during transmission. Three function callbacks for streaming DIME output and three callbacks for streaming DIME input are available.
Callback (function pointer)

```c
void (*)(soap, void *handle, const char *id, const char *type, const char *options)
```

Called by the gSOAP run-time DIME attachment sender to start reading from a (binary) data source for outbound transmission. The content will be read from the application’s data source in chunks using the fdimeread callback and streamed into the SOAP/XML/DIME output stream. The handle contains the value of the _ptr field of an attachment struct/class, which could be a pointer to specific information such as a file descriptor or a pointer to a string to be passed to this callback. Both _ptr and _size fields should have been set by the application prior to the serialization of the content. The id, type, and options arguments are the DIME id, type, and options, respectively. The callback should return handle, or another pointer value which will be passed as a handle to fdimeread and fdimereadclose. The callback should return NULL and set soap->error when an error occurred. The callback should return NULL (and not set soap->error) when this particular DIME attachment is not to be streamed.

```c
size_t (*)(soap, void *handle, char *buf, size_t len)
```

Called by the gSOAP run-time DIME attachment sender to read more data from a (binary) data source for streaming into the output stream. The handle contains the value returned by the fdimereadopen callback. The buf argument is the buffer of length len into which a chunk of data should be stored. The actual amount of data stored in the buffer may be less than len and this amount should be returned by the application. A return value of 0 indicates an error (the callback may set soap->errnum to errno). The _size field of the attachment struct/class should have been set by the application prior to the serialization of the content. The value of _size indicates the total size of the content to be transmitted. When the _size is zero then DIME chunked transfers can be used under certain circumstances to stream content without prior determination of attachment size, see Section 15.5 below.

```c
void (*)(soap, void *handle)
```

Called by the gSOAP run-time DIME attachment sender at the end of the streaming process to close the data source. The handle contains the value returned by the fdimereadopen callback. The fdimewriteclose callback is called after successfully transmitting the data or when an error occurred.

```c
void (*)(soap, const char *id, const char *type, const char *options)
```

Called by the gSOAP run-time DIME attachment receiver to start writing an inbound DIME attachment to an application’s data store. The content is streamed into an application data store through multiple fdimewrite calls from the gSOAP attachment receiver. The id, type, and options arguments are the DIME id, type, and options respectively. The callback should return a handle which is passed to the fdimewrite and fdimewriteclose callbacks. The _ptr field of the attachment struct/class is set to the value of this handle. The _size field is set to the total size of the attachment after receiving the entire content. The size is unknown in advance because DIME attachments may be chunked.

```c
int (*)(soap, void *handle, const char *buf, size_t len)
```

Called by the gSOAP run-time DIME attachment receiver to write part of an inbound DIME attachment to an application’s data store. The handle contains the value returned by the fdimewriteopen callback. The buf argument contains the data of length len. The callback should return a gSOAP error code (e.g. SOAP_OK when no error occurred).

```c
void (*)(soap, void *handle)
```

Called by the gSOAP run-time DIME attachment receiver at the end of the streaming process to close the data store. The fdimewriteclose callback is called after successfully receiving the data or when an error occurred. The handle contains the value returned by the fdimewriteopen callback.

In addition, a void* user field in the struct soap data structure is available to pass user-defined data to the callbacks. This way, you can set soap.user to point to application data that the callbacks
The following example illustrates the client-side initialization of an image attachment struct to stream a file into a DIME attachment:

```c
int main()
{
    struct soap soap;
    struct xsd_base64Binary image;
    FILE *fd;
    struct stat sb;
    soap_init(&soap);
    if (!fstat(fileno(fd), &sb) && sb.st_size > 0)
    {
        // because we can get the length of the file, we can stream it
        soap.fdimereadopen = dime_read_open;
        soap.fdimereadclose = dime_read_close;
        soap.fdimeread = dime_read;
        image.ptr = (unsigned char*)fd; // must set to non-NULL (this is our fd handle which we need in the callbacks)
        image.size = sb.st_size; // must set size
    }
    else
    {
        // don’t know the size, so buffer it
        size_t i;
        int c;
        image.ptr = (unsigned char*)soap_malloc(&soap, MAX_FILE_SIZE);
        for (i = 0; i < MAX_FILE_SIZE; i++)
        {
            if ((c = fgetc(fd)) == EOF)
                break;
            image.ptr[i] = c;
        }
        fclose(fd);
        image.size = i;
    }
    image.type = "image/jpeg";
    image.options = soap_dime_option(&soap, 0, "My picture");
    soap_call_ns_method(&soap, ...);
    ...
}

void *dime_read_open(struct soap *soap, void *handle, const char *id, const char *type, const char *options)
{
    return handle;
}

void dime_read_close(struct soap *soap, void *handle)
{
    fclose((FILE*)handle);
}

size_t dime_read(struct soap *soap, void *handle, char *buf, size_t len)
{
    return fread(buf, 1, len, (FILE*)handle);
}
```

The following example illustrates the streaming of a DIME attachment into a file by a client:
int main()
{
    struct soap soap;
    soap_init(&soap);
    soap.fdimewriteopen = dime_write_open;
    soap.fdimewriteclose = dime_write_close;
    soap.fdimewrite = dime_write;
    soap_call_ns_method(&soap, ...);
    ...
}

void *dime_write_open(struct soap *soap, const char *id, const char *type, const char *options)
{
    FILE *handle = fopen("somefile", "wb");
    if (!handle)
    {
        soap->error = SOAP_EOF;
        soap->errnum = errno; // get reason
    }
    return (void*)handle;
}

void dime_write_close(struct soap *soap, void *handle)
{
    fclose((FILE*)handle);
}

int dime_write(struct soap *soap, void *handle, const char *buf, size_t len)
{
    size_t nwritten;
    while (len)
    {
        nwritten = fwrite(buf, 1, len, (FILE*)handle);
        if (!nwritten)
        {
            soap->errnum = errno; // get reason
            return SOAP_EOF;
        }
        len -= nwritten;
        buf += nwritten;
    }
    return SOAP_OK;
}

Note that compression can be used with DIME to compress the entire message. However, compression requires buffering to determine the HTTP content length header, which cancels the benefits of streaming DIME. To avoid this, you should use chunked HTTP (with the output-mode SOAP_IO.CHUNK flag) with compression and streaming DIME. At the server side, when you set SOAP_IO.CHUNK before calling soap_serve, gSOAP will automatically revert to buffering (SOAP_IO.STORE flag is set). You can check this flag with (soap->omode & SOAP_IO) == SOAP_IO.CHUNK to see if the client accepts chunking. More information about streaming chunked DIME can be found in Section 15.5.

Caution: The options field is a DIME-specific data structure, consisting of a 4 byte header containing the option type info (hi byte, lo byte), option string length (hi byte, lo byte), followed by a non-’\0’ terminated string. The gSOAP DIME handler recognizes one option at most.
15.5 Streaming Chunked DIME

gSOAP automatically handles inbound chunked DIME attachments (streaming or non-streaming). To transmit outbound DIME attachments, the attachment sizes MUST be determined in advance to calculate HTTP message length required to stream DIME over HTTP. However, gSOAP also supports the transmission of outbound chunked DIME attachments without prior determination of DIME attachment sizes when certain conditions are met. These conditions require either non-HTTP transport (use the output-mode SOAP
ENC_XML flag), or chunked HTTP transport (use the output-mode SOAP.IO
CHUNK flag). You can also use the SOAP.IO_STORE flag (which is also used automatically with compression to determine the HTTP content length header) but that cancels the benefits of streaming DIME.

To stream chunked DIME, set the _size field of an attachment to zero and enable HTTP chunking. The DIME fdimeread callback then fetches data in chunks and it is important to fill the entire buffer unless the end of the data has been reached and the last chunk is to be send. That is, fdimeread should return the value of the last len parameter and fill the entire buffer buf for all chunks except the last.

15.6 WSDL Bindings for DIME Attachments

The wsdl2h WSDL parser recognizes DIME attachments and produces an annotated header file. Both open and closed layouts are supported for transmitting DIME attachments. For closed formats, all DIME attachments must be referenced from the SOAP message, e.g. using hrefs with SOAP encoding and using the application-specific reference attribute included in the base64Binary struct/class for doc/lit.

The gSOAP compiler soapcpp2 does not produce a WSDL with DIME extensions. DIME is an older binary format that has no WSDL protocol support, unlike MIME and MTOM.

16 MTOM Attachments

MTOM (Message Transmission Optimization Mechanism) is a relatively new format for transmitting attachments with SOAP messages (see http://www.w3.org/TR/soap12-mtom). MTOM is a W3C working draft as of this writing. MTOM attachments are essentially MIME attachments with standardized mechanisms for cross referencing attachments from the SOAP body, which is absent in (plain) MIME attachments and optional with DIME attachments.

Unlike the name suggests, the speed by which attached data is transmitted is not increased compared to MIME, DIME, or even XML encoded base64 data (at least the performance differences in gSOAP will be small). The advantage of the format is the standardized attachment reference mechanism, which should improve interoperability.

The MTOM specification mandates SOAP 1.2 and the use of the XOP namespace. The XOP Include element xop:Include is used to reference attachment(s) from the SOAP message body.

Because references from within the SOAP message body to attachments are mandatory with MTOM, the implementation of the serialization and deserialization of MTOM MIME attachments
in gSOAP uses the extended binary type comparable to DIME support in gSOAP. This binary type is predefined in the import/xop.h file:

```c
//gsoap xop schema import: http://www.w3.org/2004/08/xop/include
struct _xop_Include
{
    unsigned char *-_ptr;
    int _size;
    char *id;
    char *type;
    char *options;
};
typedef struct _xop_Include _xop_Include;
```

The additional id, type, and option fields enable MTOM attachments for the data pointed to by _ptr of size _size. The process for sending and receiving MTOM XOP attachments is fully automated. The id field references the attachment (typically a content id CID or UUID). When set to NULL, gSOAP assigns a unique CID. The type field specifies the required MIME type of the binary data, and the optional options field can be used to piggy-back descriptive text with an attachment. The order of the declaration of the fields is significant.

You can explicitly import the xop.h in your header file to use the MTOM attachments in your service, for example:

```c
#include "import/soap12.h"
/* alternatively, without the import above, use:
   //gsoap SOAP-ENV schema namespace: http://www.w3.org/2003/05/soap-envelope
   //gsoap SOAP-ENC schema namespace: http://www.w3.org/2003/05/soap-encoding
   /
   #import "import/xop.h"
   #import "import/xmime5.h"
   //gsoap x schema namespace: http://my.first.mtom.net
struct x_.myData
{
    _xop_Include xop_Include; // attachment
    @char *xmime5_.contentType; // and its contentType
};
int x_.myMTOMtest(struct x_.myData *in, struct x_.myData *out);
```

As you can see, there is really no difference between the specification of MTOM and DIME attachments in a gSOAP header file. Except that you MUST use SOAP 1.2 and the _xop_Include element.

When an instance of x_.myDataType is serialized and either or both the id and type fields are non-NULL, the data is transmitted as MTOM MIME attachment if the SOAP_ENC_MTOM flag is set in the gSOAP’s soap struct context:

```c
struct soap *soap = soap_new1(SOAP_ENC_MTOM);
```
Without this flag, the attachments will be transmitted in DIME format (Section 15). If your current clients and services are based on non-streaming DIME attachments using the SOAP body reference mechanism (thus, without using the soap_set_dime_attachment function) or plain base64 binary XML data elements, it is very easy to adopt MTOM by renaming the binary types to xop_IncId and using the SOAP_ENC_MTOM flag with the SOAP 1.2 namespace.

16.1 Generating MultipartRelated MIME Attachment Bindings in WSDL

To generate multipart-related bindings in the WSDL file, use the //gsoap ... service method-mime-type directive (see also Section 19.2). The directive can be repeated for each attachment you want to associate with a method’s request and response messages.

For example:

```c
#import "import/soap12.h"
#import "import/xop.h"
#import "import/xmime5.h"

//gsoap x schema namespace: http://my.first.mtom.net
struct x__myData
{
  xop_IncId xop__IncId; // attachment
  char *xmime5__contentType; // and its contentType
};
//gsoap x service method-mime-type: myMTOMtest text/xml
int x__myMTOMtest(struct x__myData *in, struct x__myData *out);
```

The //gsoap x service method-mime-type directive indicates that this operation accepts text/xml MIME attachments. See the SOAP-with-Attachment specification for the MIME types to use (for example, */* is a wildcard). If the operation has more than one attachment, just repeat this directive for each attachment you want to bind to the operation.

To bind attachments only to the request message of an operation, use //gsoap x service method-input-mime-type. Similarly, to bind attachments only to the response message of an operation, use //gsoap x service method-output-mime-type.

The wsdl2h WSDL parser recognizes MIME attachments and produces an annotated header file. However, the ordering of MIME parts in the multipart-related elements is not reflected in the header file. Application developers should adhere to the standards and ensure that multipart/related attachments are transmitted in compliance with the WSDL operation declarations.

16.2 Sending and Receiving MTOM Attachments

A receiver must be informed to recognize MTOM attachments by setting the SOAP_ENC_MTOM flag of the gSOAP context. Otherwise, the regular MIME attachment mechanism (SwA) will be used to store attachments.

When using wsdl2h to build clients and/or services, you should use the typemap.dat file included in the distribution package. The typemap.dat file defines the XOP namespace and XML MIME
namespaces as imported namespaces:

```xml
xop = <http://www.w3.org/2004/08/xop/include>
xmime5 = <http://www.w3.org/2005/05/xmlmime>
xmime4 = <http://www.w3.org/2004/11/xmlmime>
```

The `wsdl2h` tool uses the `typemap.dat` file (see also option `-t`) to convert WSDL into a gSOAP header file. In this case we don’t want the `wsdl2h` tool to read the XOP schema and translate it, since we have a pre-defined `xop.Include` element to handle XOP for MTOM. This `xop.Include` element is defined in `xop.h`. Therefore, the bindings shown above will not translate the XOP and XML MIME schemas to code, but generates `#import` statements instead:

```c
#import "xop.h"
#import "xmime5.h"
```

The `#import` statements are only added for those namespaces that are actually used by the service. Let’s take a look at an example. The `wsdl2h` importer generates a header file with `#import "xop.h"` from a WSDL that references XOP, for example:

```c
#include "xop.h"
#include "xmime5.h"
struct ns_Data {
    xop.Include xop.Include;
    @char *xmime5.contentType;
};
```

Suppose the WSDL defines an operation:

```c
int ns_echoData(struct ns_Data *in, struct ns_Data *out);
```

After generating the stubs/proxies with the `soapcpp2` compiler, we can invoke the stub at the client side with:

```c
struct soap *soap = soap_new1(SOAP_ENC_MTOM);
struct ns_Data data;
data.xop.Include.ptr = (unsigned char*)"<b>Hello world!</b>";
data.xop.Include.size = 20;
data.xop.Include.id = NULL; // CID automatically generated by gSOAP engine
data.xop.Include.type = "text/html"; // MIME type
data.xop.Include.options = NULL; // no descriptive info added
data.xmime5.contentType = "text/html"; // MIME type
if (soap_call_ns_echoData(soap, endpoint, action, &data, &data)) soap_print_fault(soap, stderr);
else
    printf("Got data\n");
soap_destroy(soap); // remove deserialized class instances
soap_end(soap); // remove temporary and deserialized data
soap_free(soap); // detach and free context
```
Note that the `xop_includes.type` field must be set to transmit MTOM attachments, otherwise plain base64 XML will be used.

At the server side, we show an example of an operation handler that just copies the input data to output:

```c
int ns_.echoData(struct soap *soap, struct ns_.Data *in, struct ns_.data *out)
{
    *out = *in;
    return SOAP_OK;
}
```

The server must use the `SOAP_ENC_MTOM` flag to initialize the soap struct to receive and send MTOM attachments.

### 16.3 Streaming MTOM/MIME

Streaming MTOM/MIME is achieved with callback functions to fetch and store data during transmission. Three function callbacks for streaming MTOM/MIME output and three callbacks for streaming MTOM/MIME input are available.
Callback (function pointer)

 void (*soap.fmimereadopen)(struct soap *soap, void *handle, const char *id, const char *type, const char *description)

 Called by the gSOAP run-time MTOM/MIME attachment sender to start reading from a (binary) data source for outbound transmission. The content will be read from the application’s data source in chunks using the fmimeread callback and streamed into the SOAP/XML/MTOM/MIME output stream. The handle contains the value of the _ptr field of an attachment struct/class, which could be a pointer to specific information such as a file descriptor or a pointer to a string to be passed to this callback. Both _ptr and _size fields should have been set by the application prior to the serialization of the content. The id, type, and description arguments are the MTOM/MIME id, type, and description, respectively. The callback should return handle, or another pointer value which will be passed as a handle to fmimeread and fmimereadclos. The callback should return NULL and set soap->error when an error occurred. The callback should return NULL (and not set soap->error) when this particular MTOM/MIME attachment is not to be streamed.

 size_t (*soap.fmimeread)(struct soap *soap, void *handle, char *buf, size_t len)

 Called by the gSOAP run-time MTOM/MIME attachment sender to read more data from a (binary) data source for streaming into the output stream. The handle contains the value returned by the fmimereadopen callback. The buf argument is the buffer of length len into which a chunk of data should be stored. The actual amount of data stored in the buffer may be less than len and this amount should be returned by the application. A return value of 0 indicates an error (the callback may set soap->errnum to errno). The _size field of the attachment struct/class should have been set by the application prior to the serialization of the content. The value of _size indicates the total size of the content to be transmitted. When the _size is zero then MTOM/MIME chunked transfers can be used under certain circumstances to stream content without prior determination of size, see Section 16.5 below.

 void(*soap.fmimereadclos)(struct soap *soap, void *handle)

 Called by the gSOAP run-time MTOM/MIME attachment sender at the end of the streaming process to close the data source. The handle contains the value returned by the fmimereadopen callback. The fmimereadclos callback is called after successfully transmitting the data or when an error occurred.

 void (*)(struct soap *soap, void *handle, const char *id, const char *type, const char *description, enum soap_mime_encoding encoding)

 Called by the gSOAP run-time MTOM/MIME attachment receiver to start writing an inbound MTOM/MIME attachment to an application’s data store. The content is streamed into an application data store through multiple fmimewrite calls from the gSOAP attachment receiver. The handle argument is normally NULL, unless soap_get_mime_attachment is used that passes the handle to the callback, see Section 16.4. The id, type, and description arguments are the MTOM/MIME id, type, and description respectively. The encoding enumeration value indicates the MIME content transfer encoding, which is one of SOAP_MIME_NONE, SOAP_MIME_7BIT, SOAP_MIME_8BIT, SOAP_MIME_BINARY, SOAP_MIME_QUOTED_PRINTABLE, SOAP_MIME_BASE64, SOAP_MIME_IETF_TOKEN, SOAP_MIME_X_TOKEN. Content decoding may have to be considered by the application based on this value. The callback should return a non-NULL handle which is passed to the fmimewrite and fmimereadclos callbacks. The _ptr field of the attachment struct/class is set to the value of this handle. The _size field is set to the total size of the attachment after receiving the entire content. The size is unknown in advance because MTOM/MIME attachments may be chunked.

 int (*)(struct soap *soap, void *handle, const char *buf, size_t len)

 Called by the gSOAP run-time MTOM/MIME attachment receiver to write part of an inbound MTOM/MIME attachment to an application’s data store. The handle contains the value returned by the fmimewriteopen callback. The buf argument contains the data of length len. The callback should return a gSOAP error code (e.g. SOAP_OK when no error occurred).

 void(*soap.fmimewriteclose)(struct soap *soap, void *handle)

 Called by the gSOAP run-time MTOM/MIME attachment receiver at the end of the streaming process to close the data store. The fmimewriteclose callback is called after successfully receiving the data or when an error occurred. The handle contains the value returned by the fmimewriteopen callback.
In addition, a `void*` user field in the `struct soap` data structure is available to pass user-defined data to the callbacks. This way, you can set `soap.user` to point to application data that the callbacks need such as a file name for example.

The following example illustrates the client-side initialization of an image attachment struct to stream a file into a MTOM attachment without HTTP chunking (HTTP streaming chunked MTOM transfer is presented in Section 16.5):

```c
int main()
{
    struct soap soap;
    struct xsd__base64Binary image;
    FILE *fd;
    struct stat sb;
    soap_init1(&soap, SOAP_ENC_MTOM); // mandatory to enable MTOM
    if (!fstat(fileno(fd), &sb) && sb.st_size > 0)
    {
        // because we can get the length of the file, we can stream it without chunking
        soap.fmimereadopen = mime_read_open;
        soap.fmimereadclose = mime_read_close;
        soap.fmimeread = mime_read;
        image._ptr = (unsigned char*)fd; // must set to non-NULL (this is our fd handle which we need in the callbacks)
        image._size = sb.st_size; // must set size
    }
    else
    {
        // don't know the size, so buffer it
        size_t i;
        int c;
        image._ptr = (unsigned char*)soap_malloc(&soap, MAX_FILE_SIZE);
        for (i = 0; i < MAX_FILE_SIZE; i++)
        {
            if ((c = fgetc(fd)) == EOF)
                break;
            image._ptr[i] = c;
        }
        fclose(fd);
        image._size = i;
    }
    image.type = "image/jpeg"; // MIME type
    image.options = "This is my picture"; // description of object
    soap_call_ns_method(&soap, ...);
    ...
}

void *mime_read_open(struct soap *soap, void *handle, const char *id, const char *type, const char *description)
{ return handle; }
}

void mime_read_close(struct soap *soap, void *handle)
{ fclose((FILE*)handle); }

size_t mime_read(struct soap *soap, void *handle, char *buf, size_t len)
{ return fread(buf, 1, len, (FILE*)handle); }
```
The following example illustrates the streaming of a MTOM/MIME attachment into a file by a client:

```c
int main()
{
    struct soap soap;
    soap_init(&soap);
    soap.fmimewriteopen = mime_write_open;
    soap.fmimewriteclose = mime_write_close;
    soap.fmimewrite = mime_write;
    soap.call_ns_method(&soap, ...);
    ...
}

void *mime_write_open(struct soap *soap, const char *id, const char *type, const char *description, enum soap_mime_encoding encoding)
{
    FILE *handle = fopen("somefile", "wb");
    // We ignore the MIME content transfer encoding here, but should check
    if (!handle)
    {
        soap->error = SOAP_EOF;
        soap->errnum = errno; // get reason
    }
    return (void*)handle;
}

void mime_write_close(struct soap *soap, void *handle)
{
    fclose((FILE*)handle);
}

int mime_write(struct soap *soap, void *handle, const char *buf, size_t len)
{
    size_t nwritten;
    while (len)
    {
        nwritten = fwrite(buf, 1, len, (FILE*)handle);
        if (!nwritten)
        {
            soap->errnum = errno; // get reason
            return SOAP_EOF;
        }
        len -= nwritten;
        buf += nwritten;
    }
    return SOAP_OK;
}
```

Note that compression can be used with MTOM/MIME to compress the entire message. However, compression requires buffering to determine the HTTP content length header, which cancels the benefits of streaming MTOM/MIME. To avoid this, you should use chunked HTTP (with the output-mode SOAP_IO_CHUNK flag) with compression and streaming MTOM/MIME. At the server side, when you set SOAP_IO_CHUNK before calling soap_serve, gSOAP will automatically revert to
buffering (SOAP_IO_STORE flag is set). You can check this flag with

```
(soap==SOAP_IO_STORE) ==
```

SOAP.IO_CHUNK to see if the client accepts chunking. More information about streaming chunked MTOM/MIME can be found in Section 16.5.

Note that the example above for mime_read uses a handle that points to the open file FILE*. The simple example above is not recommended when the platform imposes a limit on the number of open file descriptors. You can use the handle to pass along more information than just the file descriptor. So for example, when the number of open file descriptors is limited on your platform, you should let the handle point to a structure with file-related information. The C++ example below illustrates this:

```c++
file.xop_.Include = soap_new_xop_.Include(soap);
file.xop_.Include:id = NULL;
file.xop_.Include:type = type;
file.xop_.Include:options = NULL;

file.xmime5_.contentType = type;
file.filename = filename;

// The object holding all information to read data
FileStreamIn *ins = new FileStreamIn(errorhandler);
ins->setFilePath(path);
ins->setFileName(filename);

file.xop_.Include->.size = size;
file.xop_.Include->.ptr = (unsigned char*)ins;
```

To read the MTOM data for transmission:

```c++
void *mime_read_open(struct soap *soap, void *handle, const char *id, const char *type, const char *description)
{
    if (!handle)
        return NULL;
    FileStreamIn *ins = (FileStreamIn*)handle;
    if (!ins->open())
    {
        soap->error = SOAP_ERR;
        return NULL;
    }
    return handle;
}
void mime_read_close(struct soap *soap, void *handle)
{
    if (!handle)
        return;
    FileStreamIn *ins = (FileStreamIn*)handle;
    delete ins;
}
size_t mime_read(struct soap *soap, void *handle, char *buf, size_t len)
{
```
if (!handle)
    return 0;
FileStreamIn *ins = (FileStreamIn*)handle;
size_t nread = ins->read(buf, len);
if (ins->streamError())
{
    soap->error = ins->streamError();
    return 0;
}
return nread;

16.4 Redirecting Inbound MTOM/MIME Streams Based on SOAP Body Content

When it is preferable or required to redirect inbound MTOM/MIME attachment streams based on SOAP message body content, where for example the names of the resources are listed in the SOAP message body, an alternative mechanism must be used. This mechanism can be used both at the client and server side.

Because the routing of the streams is accomplished with explicit function calls, this method should only be used when required and should not be considered optional. That is, when you enable this method, you MUST check for pending MTOM/MIME attachments and handle them appropriately. This is true even when you don’t expect MTOM/MIME attachments in the payload, because the peer may trick you by sending attachments anyway and you should be prepared to accept or reject them.

The explicit MTOM/MIME streaming mechanism consists of three API functions:

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>void soap_post_check_mime_attachments(struct soap *soap)</td>
<td>Enables post-message body inbound streaming MTOM/MIME attachments. The presence of attachments must be explicitly checked using the function below.</td>
</tr>
<tr>
<td>int soap_check_mime_attachments(struct soap *soap)</td>
<td>Should be called after a client-side call (e.g. soap_call_ns_method) to check the presence of attachments. Returns 1 (true) when attachments are present. If present, each attachment MUST be processed with the function below.</td>
</tr>
<tr>
<td>struct soap_multipart *soap_get_mime_attachment(struct soap *soap, void *handle)</td>
<td>Parses an attachment and invokes the MIME callbacks (when set). The handle parameter is passed to fmimewriteopen. The handle may contain any data that is extracted from the SOAP message body to guide the redirection of the stream in the callbacks. The return value is a struct with a char *ptr field that contains the handle value returned by the fmimewriteopen callback, and char *id, char *type, and char *description fields with the optional MIME id, type, and description info.</td>
</tr>
</tbody>
</table>

Example client-side code in C:

```c
struct soap *soap = soap_new1(SOAP_ENC_MTOM);
soap_post_check_mime_attachments(soap);
...```

203
if (soap_call_ns__myMethod(soap, ...))
    soap_print_fault(soap, stderr); // an error occurred
else
{
    if (soap_check_mime_attachments(soap))  // attachments are present, channel is still open
    {
        do
        {
            ... // get data 'handle' from SOAP response and pass to callbacks
            ... // set the fmime callbacks, if needed
            struct soap_multipart *content = soap_get_mime_attachment(soap, (void*)handle);
            printf("Received attachment with id=%s and type=%s\n", content->id?content->id:"",
                content->type?content->type:"");
        } while (content);
        if (soap->error)
            return soap->error;
    }
}

... // server-side processing logic
return SOAP_OK;

The server-side service operations are implemented as usual, but with additional checks for MTOM/MIME attachments:

struct soap *soap = soap_new1(SOAP_ENC_MTOM);
soap_post_check_mime_attachments(soap);
...
soap_serve(soap);
...
int ns__myMethod(struct soap *soap, ...)
{
    ... // server-side processing logic
    if (soap_check_mime_attachments(soap))  // attachments are present, channel is still open
    {
        do
        {
            ... // get data 'handle' from SOAP request and pass to callbacks
            ... // set the fmime callbacks, if needed
            struct soap_multipart *content = soap_get_mime_attachment(soap, (void*)handle);
            printf("Received attachment with id=%s and type=%s\n", content->id?content->id:"",
                content->type?content->type:"");
        } while (content);
        if (soap->error)
            return soap->error;
    }
    ...
    // server-side processing logic
    return SOAP_OK;
}
16.5 Streaming Chunked MTOM/MIME

gSOAP automatically handles inbound chunked MTOM/MIME attachments (streaming or non-streaming). To transmit outbound MTOM/MIME attachments, the attachment sizes MUST be determined in advance to calculate HTTP message length required to stream MTOM/MIME over HTTP. However, gSOAP also supports the transmission of outbound chunked MTOM/MIME attachments without prior determination of MTOM/MIME attachment sizes when certain conditions are met. These conditions require either non-HTTP transport (use the output-mode SOAP_ENC_XML flag), or chunked HTTP transport (use the output-mode SOAP_IO_CHUNK flag). You can also use the SOAP_IO_STORE flag (which is also used automatically with compression to determine the HTTP content length header) but that cancels the benefits of streaming MTOM/MIME.

To stream chunked MTOM/MIME, set the _size field of an attachment to zero and enable HTTP chunking. The MTOM/MIME fmimeread callback then fetches data in chunks of any size between 1 and the value of the len argument. The fmimeread callback should return 0 upon reaching the end of the data stream.

17 XML Validation

The gSOAP XML parser applies basic rules to validate content. Constraints are not automatically verified unless explicitly set using flags. This helps to avoid interoperability problems with toolkits that do not strictly enforce validation rules. In addition, we cannot always use strict validation for SOAP RPC encoded messages, since SOAP RPC encoding adopts a very loose serialization format.

Validation constraints are enabled with the SOAP(XML)_STRICT input mode flag set, e.g. with soap_set_imode(soap, SOAP_XML_STRICT) or soap_new(SOAP_XML_STRICT), see Section 9.12 for the complete list of flags.

17.1 Occurrence Constraints

17.1.1 Default Values

Default values can be defined for optional elements and attributes, which means that the default value will be used when the element or attribute value is not present in the parsed XML. See also Section 7.5.7 and examples in subsequent subsections below.

Default values must be primitive types, integer, float, string, etc. Default values can be specified for struct and class members, as shown in the example below:

```c
struct ns__MyRecord
{
    int n = 5;  // optional element with default value 5
    char *name = "none";  // optional element with default value "none"
    @enum ns__color { RED, WHITE, BLUE } color = RED;  // optional attribute with default value RED
};
```
Upon deserialization of absent data, these members will be set accordingly. When classes are instantiated with `soap_new_ClassName` the instance will be initialized with default values.

17.1.2 Elements with minOccurs and maxOccurs Restrictions

To force the validation of minOccurs and maxOccurs contraints the SOAP_XML_STRICT input mode flag must be set. The minOccurs and maxOccurs constraints are specified for fields of a struct and members of a class in a header file using the following syntax:

```
Type fieldname [minOccurs:maxOccurs] [ = value]
```

The minOccurs and maxOccurs values must be integer literals. A default value can be provided. When minOccurs is not specified, it is assumed to be zero.

For example

```c
struct ns__MyRecord
{
    int n = 5; // element with default value 5, minOccurs=0, maxOccurs=1
    int m 1; // element with minOccurs=1
    int __size 0:10; // sequence jitemj with minOccurs=0, maxOccurs=10
    int *item;
    std::vector<double> nums 2; // sequence jnumsj with minOccurs=2, maxOccurs=unbounded
};
struct arrayOfint
{
    int *__ptr 1:100; // minOccurs=1, maxOccurs=100
    int size;
};
```

Pointer-based struct fields and class members are allowed to be nillable when minOccurs is zero.

17.1.3 Required and Prohibited Attributes

Similar to the minOccurs and maxOccurs annotations defined in the previous section, attributes in a struct or class can be annotated with occurrence constraints to make them optional (0), required (1), or prohibited (0:0). Default values can be assigned to optional attributes.

For example

```c
struct ns__MyRecord
{
    @int m 1; // required attribute (occurs at least once)
    @int n 5; // optional attribute with default value 5
    @int o 0; // optional attribute (may or may not occur)
    @int p 0:0; // prohibited attribute
};
```

Remember to set the SOAP_XML_STRICT input mode flag to enable the validation of attribute occurrence constraints.
17.2 Value Constraints

17.2.1 Data Length Restrictions

A schema simpleType is defined with a typedef by taking a base primitive to defined a derived simpleType. For example:

```c
typedef int time_seconds;
```

This defines the following schema type in time.xsd:

```xml
<simpleType name="seconds">
  <restriction base="xsd:int"/>
</simpleType>
```

A complexType with simpleContent is defined with a wrapper struct/class:

```c
struct time_date
{
  char *__item; // some custom format date (restriction of string)
  @enum time_zone { EST, GMT, ... } zone;
}
```

This defines the following schema type in time.xsd:

```xml
<complexType name="date">
  <simpleContent>
    <extension base="xsd:string"/>
  </simpleContent>
  <attribute name="zone" type="time:zone" use="optional"/>
</complexType>
<simpleType name="zone">
  <restriction base="xsd:string">
    <enumeration value="EST"/>
    <enumeration value="GMT"/>
    ...
  </restriction>
</simpleType>
```

Data value length constraints of simpleTypes and complexTypes with simpleContent are defined as follows.

```c
typedef char *ns_string256 0:256; // simpleType restriction of string with max length 256 characters
typedef char *ns_string10 10:10; // simpleType restriction of string with length of 10 characters
typedef std::string *ns_string8 8; // simpleType restriction of string with at least 8 characters
struct ns_data // simpleContent wrapper
{
  char *__item :256; // simpleContent with at most 256 characters
  @char *name 1; // required name attribute
};
```
struct time._date // simpleContent wrapper
{
    char * _item :100;
    @enum time._zone { EST, GMT, ... } zone = GMT;
}

Remember to set the SOAP.XML_STRICT input mode flag to enable the validation of value length constraints.

17.2.2 Value Range Restrictions

Similar to data length constraints for string-based data, integer data value range constraints of numeric simpleTypes and complexTypes with simpleContent are defined as follows.

typedef int ns_int10 0:10; // simpleType restriction of int 0..10
typedef LONG64 ns_long -1000000:1000000; // simpleType restriction of long64 -1000000..1000000
typedef float ns_float100 -100:100; // simpleType restriction of float -100..100
struct ns_data // simpleContent wrapper
{
    int _item 0:10; // simpleContent range 0..10
    @char *name 1; // required name attribute
};

Currently the value bounds must be integer valued. Therefore, floating point ranges are limited to integer bounds. This may change in future releases.

17.2.3 Pattern Restrictions

Patterns can be defined for simpleType content. However, patterns are currently not enforced in the validation process though possibly in future releases.

To associate a pattern with a simpleType, you can define a simpleType with a typedef and a pattern string:

    typedef int time_second "[1-5]?[0-9]—60";

This defines the following schema type in time.xsd:

    <simpleType name="second">
        <restriction base="xsd:int">
            <pattern value="[1-5]?[0-9]-60"/>
        </restriction>
    </simpleType>

The pattern string MUST contain a valid regular expression.

A special case for C format string patterns is introduced in gSOAP 2.8.18. When xs:totalDigits and xs:fractionDigits are given in a XSD file, then a C format string is produced to output floating point values with the proper precision and scale. For example:
<simpleType name="ratio">
    <restriction base="xsd:float">
        <totalDigits value="5"/>
        <fractionDigits value="2"/>
    </restriction>
</simpleType>

produces:

typedef float time_ratio "%.5f";

The format string is used to format the output the floating point value in XML.

17.3 Element and Attribute Qualified/Unqualified Forms

Struct, class, and union members represent elements and attributes that are automatically qualified or unqualified depending on the schema element and attribute default forms. The gSOAP engine always validates the prefixes of elements and attributes. When a namespace mismatch occurs, the element or attribute is not consumed which can lead to a validation error (unless the complexType is extensible or when SOAP/XML_STRICT is turned off).

See Section 10.3 for details on the struct/class/union member identifier translation rules. Consider for example:

```c
  //gsoap ns schema elementForm: qualified
  //gsoap ns schema attributeForm: unqualified
  struct ns_record
  {
    @char * type;
    char * :name;
  };
```

Here, the ns_record struct is serialized with qualified element name and unqualified attribute type:

```
<ns:record type="...">
  <ns:name>...</ns:name>
</ns:record>
```

The “colon notation” for struct/class/union member field names is used to override element and attribute qualified or unqualified forms. To override the form for individual members that represent elements and attributes, use a namespace prefix and colon with the member name:

```c
  //gsoap ns schema elementForm: qualified
  //gsoap ns schema attributeForm: unqualified
  struct ns_record
  {
    @char * ns:type;
    char * :name;
  };
```
where name is unqualified and type is qualified:

<ns:record ns:type="...">
  <name>...</name>
</ns:record>

The colon notation is a syntactic notation used only in the gSOAP header file syntax, it is not translated to the C/C++ output.

The colon notation does not avoid name clashes between members. For example:

```c
struct x_record
{
  char * :name;
  char * x:name;
};
```

results in a redefinition error, since both members have the same name. To avoid name clashes, use a underscore suffix:

```c
struct x_record
{
  char * :name;
  char * x:name;
};
```

Not that the namespace prefix convention can be used instead:

```c
struct x_record
{
  char * :name;
  char * x:_name;
};
```

which avoids the name clash. However, the resulting schema is different since the last example generates a global name element definition that is referenced by the local element.

More specifically, the difference between the namespace prefix convention with double underscores and colon notation is that the namespace prefix convention generates schema element/attribute references to elements/attributes at the top level, while the colon notation only affects the local element/attribute namespace qualification by form overriding. This is best illustrated by an example:

```c
struct x_record
{
  char * :name;
  char * x:phone;
  char * x:_fax;
  char * y:_zip;
};
```
which generates the following x.xsd schema:

```xml
<complexType name="record">
  <sequence>
    <element name="name" type="xsd:string" minOccurs="0" maxOccurs="1" nillable="true" form="unqualified"/>
    <element name="phone" type="xsd:string" minOccurs="0" maxOccurs="1" nillable="true" form="qualified"/>
    <element ref="x:fax" minOccurs="0" maxOccurs="1"/>
    <element ref="y:zip" minOccurs="0" maxOccurs="1"/>
  </sequence>
</complexType>
<element name="fax" type="xsd:string"/>
```

and the y.xsd schema defines contains:

```xml
<element name="zip" type="xsd:string"/>
```

### 18 SOAP/XML Over UDP

UDP is a simple, unreliable datagram protocol: UDP sockets are connectionless. UDP address formats are identical to those used by TCP. In particular UDP provides a port identifier in addition to the normal Internet address format. The UDP port space is separate from the TCP port space (i.e. a UDP port may not be “connected” to a TCP port). In addition broadcast packets may be sent (assuming the underlying network supports this) by using a reserved “broadcast address”; this address is network interface dependent.

Client-side messages with SOAP-over-UDP endpoint URLs (soap.udp://...) will be automatically transmitted as datagrams. Server-side applications should set the SOAP_IO_UDP mode flag to accept UDP requests, e.g. using `soap_init1` or `soap_set_mode`.

The maximum message length for datagram packets is restricted by the buffer size SOAP_BUFLEN, which is 65536 by default, unless compiled with `WITH_LEAN` to support small-scale embedded systems. For UDP transport SOAP_BUFLEN must not exceed the maximum UDP packet size 65536 (the size of datagram messages is constrained by the UDP packet size $2^{16} = 65536$ as per UDP standard). You can use gzip compression to reduce the message size, but note that compressed SOAP-over-UDP is a gSOAP-specific feature because it is not part of the SOAP-over-UDP specification.

The SOAP-over-UDP specification relies on WS-Addressing. The `wsa.h` file in the `import` directory defines the WS-Addressing elements for client and server applications.

The gSOAP implementation conforms to the SOAP-over-UDP requirements:

- SOAP-over-UDP server endpoint URL format: `soap.udp://host:port/path`
- Support one-way message-exchange pattern (MEP) where a SOAP envelope is carried in a user datagram.
• Support request-response message-exchange pattern (MEP) where SOAP envelopes are carried in user datagrams.

• Support multicast transmission of SOAP envelopes carried in user datagrams.

• Support both SOAP 1.1 and SOAP 1.2 envelopes.

The following additional features are also available, but are not supported by the SOAP-over-UDP specification:

• Zlib/gzip message compression (compile -DWITH_GZIP).

• SOAP with DIME attachments over UDP.

• SOAP with MIME attachments (SwA) over UDP.

• Support for IPv6 (compile -DWITH_IPV6)

18.1 Using WS-Addressing with SOAP-over-UDP

A SOAP-over-UDP application MUST use WS-Addressing to control message delivery as per SOAP-over-UDP specification.

The wsa.h file in the import directory defines the WS-Addressing elements. To include the WS-Addressing elements in the SOAP Header for messaging, a struct SOAP_ENV__Header structure must be defined in your header file with the appropriate WS-Addressing elements. For example:

```c
#import "wsa.h"

struct SOAP_ENV__Header
{
    mustUnderstand wsa_MessageID wsa_MessageID 0;
    mustUnderstand wsa_RelatesTo *wsa_RelatesTo 0;
    mustUnderstand wsa_From *wsa_From 0;
    mustUnderstand wsa_ReplyTo *wsa_ReplyTo 0;
    mustUnderstand wsa_FaultTo *wsa_FaultTo 0;
    mustUnderstand wsa_To wsa_To 0;
    mustUnderstand wsa_Action wsa_Action 0;
};
```

We also included a //gsoap wsa schema import directive in the wsa.h file to enable the generation of WSDL specifications that import (instead of includes) the WS-Addressing elements. Note that the //gsoapopt w directive must not be present in your header file to enable WSDL generation.

One-way SOAP-over-UDP messages (see Section 7.3) should be declared to include the wsa:MessageID, wsa:To, and wsa:Action elements in the SOAP Header of the request message as follows:

```c
//gsoap ns service method-header-part: sendString wsa__MessageID
//gsoap ns service method-header-part: sendString wsa__To
//gsoap ns service method-header-part: sendString wsa__Action
int ns__sendString(char *str, void);
```
Request-response SOAP-over-UDP messages should be declared to include the \texttt{wsa:MessageID}, \texttt{wsa:To}, \texttt{wsa:Action}, and \texttt{wsa:ReplyTo} elements in the SOAP Header of the request message, and the the \texttt{wsa:MessageID}, \texttt{wsa:To}, \texttt{wsa:Action}, and \texttt{wsa:RelatesTo} elements in the SOAP Header of the response message:

\begin{verbatim}
//gsoap ns service method-header-part: echoString wsa._MessageID
//gsoap ns service method-header-part: echoString wsa._To
//gsoap ns service method-header-part: echoString wsa._Action
//gsoap ns service method-input-header-part: sendString wsa._ReplyTo
//gsoap ns service method-output-header-part: echoString wsa._RelatesTo
int ns_.echoString(char *str, char **res);
\end{verbatim}

For the content requirements of these elements, please consult the SOAP-over-UDP specification and/or read the next sections explaining SOAP-over-UDP unicast, multicast, one-way, and request-response client and server applications.

\section{Client-side One-way Unicast}

This example assumes that the gSOAP header file includes the SOAP Header with WS-Addressing elements and the \texttt{ns_.sendString} function discussed in Section 18.1

\begin{verbatim}
struct soap soap;
struct SOAP_ENV._Header header; // the SOAP Header
soap_init(&soap);
soap.send_timeout = 1; // 1s timeout
soap_default_SOAP_ENV._Header(&soap, &header); // init SOAP Header
header.wsa._MessageID = "message ID";
header.wsa._To = "server URL";
header.wsa._Action = "server action";
soap.header = &header; // bind the SOAP Header for transport
// Send the message over UDP:
if (soap_send_ns_.echoString(&soap, "soap.udp://...", NULL, "hello world!"))
    soap_print_fault(&soap, stderr); // report error
soap_end(&soap); // cleanup
soap_destroy(&soap); // cleanup
soap_done(&soap); // close connection (should not use soap struct after this)
\end{verbatim}

\section{Client-side One-way Multicast}

This example is similar to the one-way unicast example discussed above, but uses a broadcast address and the \texttt{SO_BROADCAST} socket option:

\begin{verbatim}
struct soap soap;
struct SOAP_ENV._Header header; // the SOAP Header
in_addr_t addr = inet_addr("1.2.3.4"); // optional
soap_init(&soap);
soap_send_timeout = 1; // 1s timeout
soap.connect_flags = SO_BROADCAST; // required for broadcast
\end{verbatim}
Please refer to the socket options for IPPROTO_IP IP_MULTICAST_IF to specify the default interface for multicast datagrams to be sent from. This is a struct in_addr (in_addr_t for sin6_scope_id) interface value. Otherwise, the default interface set by the system administrator will be used (if any).

Please refer to the socket options for IPPROTO_IP IP_MULTICAST_TTL to limit the lifetime of the packet. Multicast datagrams are sent with a default value of 1, to prevent them to be forwarded beyond the local network. This parameter can be set between 1 to 255.

18.4 Client-side Request-Response Unicast

This example assumes that the gSOAP header file includes the SOAP Header with WS-Addressing elements and the ns_echoString function discussed in Section 18.1

```c
struct soap soap;
struct SOAP_ENV__Header header; // the SOAP Header
struct wsa__EndpointReferenceType replyTo; // (anonymous) reply address
char *res; // server response
soap_init(&soap);
soap.send_timeout = 1; // 1s timeout
soap.recv_timeout = 1; // 1s timeout
soap_default_SOAP_ENV__Header(&soap, &header); // init SOAP Header
soap_default_wsa__EndpointReferenceType(&soap, &replyTo); // init reply address
replyTo.Address = "http://schemas.xmlsoap.org/ws/2004/08/addressing/role/anonymous";
header.wsa__MessageID = "message ID";
header.wsa__To = "server URL";
header.wsa__Action = "server action";
header.wsa__ReplyTo = &replyTo;
soap.header = &header; // bind the SOAP Header for transport
// Send and receive messages over UDP:
if (soap_call_ns__echoString(&soap, "soap.udp://...", NULL, "hello world!", &res))
{
    if (soap.error == SOAP_EOF && soap.errnum == 0)
        // Timeout: no response from server (message already delivered?)
    else
```
```c
else
    // UDP server response is stored in 'res'
    // check SOAP header received, if applicable
    check_header(&soap.header);
    soap_destroy(&soap); // cleanup
    soap_end(&soap); // cleanup
    soap_done(&soap); // close connection (should not use soap struct after this)
}

18.5 Client-side Request-Response Multicast

This example is similar to the request-response unicast example discussed above, but uses a broadcast address and the SO_BROADCAST socket option. Because we expect to receive multiple responses, we also need to use separate request-response messages to send one request and consume multiple responses. In this example we defined a bcastString request and a bcastStringResponse response message, which are essentially declared as one-way messages in the header file:

```c
int ns__bcastString(char *str, void);
int ns__bcastStringResponse(char *res, void);
```
soap_print_fault(&soap, stderr);
else
{
    for (; ;)
    {
        if (soap_recv_ns__bcastStringResponse(&soap, &res))
            break;
        // Got response 'res' from a server
    }
    if (soap.error == SOAP_EOF && soap.errnum == 0)
        // Timeout: no more messages received
    else
        soap_print_fault(&soap, stderr);
}
soap_destroy(&soap); // cleanup
soap_end(&soap); // cleanup
soap_done(&soap); // close connection (should not use soap struct after this)

Note that a server for the bcastString does not need to use two-one way messages. Thus, multicast request-response message pattern can be declared and implemented as request-response operations at the server side.

18.6 SOAP-over-UDP Server

The following example code illustrates a SOAP-over-UDP server for one-way sendString and request-response echoString messages. This example assumes that the gSOAP header file includes the SOAP Header with WS-Addressing elements and the ns__echoString function discussed in Section 18.1.

int main()
{
    struct soap soap;
    soap_init1(&soap, SOAP_IO_UDP); // must set UDP flag
    // bind to host (NULL=current host) and port:
    if (!soap_valid_socket(soap_bind(&soap, host, port, 100)))
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    for (; ;)
    {
        if (soap Serve(&soap))
            soap_print_fault(&soap, stderr); // report the problem
        soap_destroy(&soap);
        soap_end(&soap);
    }
    soap_done(&soap); // close connection
}

int ns__echoString(struct soap *soap, char *str, char **res)
{
    if (!soap->header)
The server binds to a host and port and accepts messages in a tight sequential loop. Because UDP does not have the equivalent of an accept the messages cannot be dispatched to threads, the soap_serve waits for a message and immediately accepts it. You can use a receive timeout to make soap_serve non-blocking.

To obtain response one-way operations from a WSDL, use the wsdl2h -b option. This produces additional one-way operations to support asynchronous handling of response messages in the same way requests are handled.

18.7 SOAP-over-UDP Multicast Receiving Server

For UDP multicast support, follow the suggestions in Section 18.6 and change the initialization parts of the code to enable UDP multicast port binding by to telling the kernel which multicast groups you are interested in:
int main()
{
    struct soap soap;
    struct ip_mreq mcast;
    soap_init1(&soap, SOAP_IO_UDP);
    if (!soap_valid_socket(soap_bind(&soap, host, port, 100)))
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    mcast.imr_multiaddr.s_addr = inet_addr("put IP multicast address of group here");
    mcast.imr_interface.s_addr = htonl(INADDR_ANY);
    if (setsockopt(soap.master, IPPROTO_IP, IP_ADD_MEMBERSHIP, &mcast, sizeof(mcast)))
        ... error ...
}

19 Advanced Features

19.1 Internationalization

gSOAP uses regular strings by default. Regular strings cannot be used to hold UCS characters outside of the character range [1,255]. gSOAP can handle wide-character content in two ways. First, applications can utilize wide-character strings (wchar_t*) instead of regular strings to store wide-character content. For example, the xsd:string string schema type can be declared as a wide-character string and used subsequently:

    typedef wchar_t *xsd_string;
    ...
    int ns_myMethod(xsd_string input, xsd_string *output);

Second, regular strings can be used to hold wide-character content in UTF-8 format. This is accomplished with the SOAP_C_UTFSTRING flag (for both input/output mode), see Section 9.12. With this flag set, gSOAP will deserialize XML into regular strings in UTF-8 format. An application is responsible for filling regular strings with UTF-8 content to ensure that strings can be correctly serialized XML. Third, the SOAP_C_MBSTRING flag (for both input/output mode) can be used to activate multibyte character support. Multibyte support depends on the locale settings for dealing with extended natural language encodings.

Both regular strings and wide-character strings can be used together within an application. For example, the following header file declaration introduces two string schema types:

    typedef wchar_t *xsd_string;
    typedef char *xsd_string;  // trailing '.' avoids name clash
    ...
    int ns_myMethod(xsd_string input, xsd_string *output);

The input string parameter is a wide-character string and the output string parameter is a regular string. The regular string has UCS character content in the range [1,255] unless the SOAP_C_UTFSTRING flag is set. With this flag, the string has UTF-8 encoded content.
Please consult the UTF-8 specification for details on the UTF-8 format. Note that the ASCII character set \[1-127\] is a subset of UTF-8. Therefore, with the `SOAP_C_UTFSTRING` flag set, strings may hold ASCII character data and UTF-8 extensions.

### 19.2 Customizing the WSDL and Namespace Mapping Table File Contents With gSOAP Directives

A header file can be augmented with directives for the gSOAP `soapcpp2` tool to automatically generate customized WSDL and namespace mapping tables contents. The WSDL and namespace mapping table files do not need to be modified by hand (Sections 7.2.9 and 10.4). In addition, the sample SOAP/XML request and response files generated by the compiler are valid provided that XML Schema namespace information is added to the header file with directives so that the gSOAP `soapcpp2` compiler can produce example SOAP/XML messages that are correctly namespace qualified. These compiler directive are specified as `//`-comments. (Note: blanks can be used anywhere in the directive, except between `//` and `gsoap`.)

Three directives are currently supported that can be used to specify details associated with namespace prefixes used by the service operation names in the header file. To specify the name of a Web Service in the header file, use:

```
//gsoap namespace-prefix service name: service-name
```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `service-name` is the name of a Web Service (only required to create new Web Services). The name may be followed by text up to the end of the line which is incorporated into the WSDL service documentation. Alternatively, the service documentation can be provided with the directive below.

To specify the name of the WSDL definitions in the header file, use:

```
//gsoap namespace-prefix service definitions: definitions-name
```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `definitions-name` is the name of the WSDL definitions. By default, the WSDL definitions name is the same as the service name.

To specify the documentation of a Web Service in the header file, use:

```
//gsoap namespace-prefix service documentation: text
```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `text` is the documentation text up to the end of the line. The text is incorporated into the WSDL service documentation.

To specify the portType of a Web Service in the header file, use:

```
//gsoap namespace-prefix service portType: portType-name
```

or just
or using WSDL 2.0 terms

```gsoap namespace-prefix service interface: portType-name```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `portType-name` is the portType name of the WSDL service portType.

To specify the port name of a Web Service in the header file, use:

```gsoap namespace-prefix service portName: port-name```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `port-name` is the name of the WSDL service port element. By default, the port name is the same as the service name.

To specify the binding name of a Web Service in the header file, use:

```gsoap namespace-prefix service binding: binding-name```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `binding-name` is the binding name of the WSDL service binding element. By default, the binding name is the same as the service name.

To specify the binding’s transport protocol of a Web Service in the header file, use:

```gsoap namespace-prefix service transport: transport-URL```

where `namespace-prefix` is a namespace prefix used by identifiers in the header file and `transport-URL` is the URL of the transport protocol such as `http://schemas.xmlsoap.org/soap/http` for HTTP. HTTP transport is assumed by default.

To specify the location (or port endpoint) of a Web Service in the header file, use:

```gsoap namespace-prefix service location: URL```

or alternatively

```gsoap namespace-prefix service endpoint: URL```

or

```gsoap namespace-prefix service port: URL```

where `URL` is the location of the Web Service (only required to create new Web Services). The `URL` specifies the path to the service executable (so `URL/service-executable` is the actual location of the executable when declared).

To specify the name of the executable of a Web Service in the header file, use:
**//gsoap namespace-prefix service executable: executable-name**

where *executable-name* is the name of the executable of the Web Service.

When doc/literal encoding is required for the entire service, the service encoding can be specified in the header file as follows:

**//gsoap namespace-prefix service encoding: literal**

or when the SOAP-ENV:encodingStyle attribute is different from the SOAP 1.1/1.2 encoding style:

**//gsoap namespace-prefix service encoding: encoding-style**

To specify the namespace URI of a Web Service in the header file, use:

**//gsoap namespace-prefix service namespace: namespace-URI**

where *namespace-URI* is the URI associated with the namespace prefix.

In addition, the schema namespace URI can be specified in the header file:

**//gsoap namespace-prefix schema namespace: namespace-URI**

where *namespace-URI* is the schema URI associated with the namespace prefix. If present, it defines the schema-part of the generated WSDL file and the URI in the namespace mapping table. This declaration is useful when the service declares its own data types that need to be associated with a namespace. Furthermore, the header file for client applications do not need the full service details and the specification of the schema namespaces for namespace prefixes suffices. In addition, a second namespace can be defined that is only used to match the namespaces of inbound XML:

**//gsoap namespace-prefix schema namespace2: namespace-URI-pattern**

If the first namespace does not match the inbound parsed XML, then the second will be tried. This pattern may contain '*' multichar wildcards and '-' single char wildcards. This allows two or more namespace versions to be handled by the same namespace prefix.

The directive above specifies a new schema and the gSOAP soapcpp2 compiler generates a schema files (.xsd) file for the schema. An existing schema namespace URI can be imported with:

**//gsoap namespace-prefix schema import: namespace-URI**

where *namespace-URI* is the schema URI associated with the namespace prefix. gSOAP does not produce XML Schema files for imported schemas and imports the schema namespaces in the generated WSDL file.

A schema namespace URI can be imported from a location with:

**//gsoap namespace-prefix schema namespace: namespace-URI**
**//gsoap namespace-prefix schema import: schema-location**

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The elementFormDefault and attributeFormDefault qualification of a schema can be defined with:

```xml
//gsoap namespace-prefix schema elementForm: qualified
//gsoap namespace-prefix schema attributeForm: qualified
```

or:

```xml
//gsoap namespace-prefix schema elementForm: unqualified
//gsoap namespace-prefix schema attributeForm: unqualified
```

A shortcut to define the default qualification of elements and attributes of a schema:

```xml
//gsoap namespace-prefix schema form: qualified
```

or:

```xml
//gsoap namespace-prefix schema form: unqualified
```

To include xsi:type attributes in the runtime XML element output for specific schemas, use:

```xml
//gsoap namespace-prefix schema typed: yes
```

Note that soapcpp2 -t enables xsi:type for all elements in the runtime XML output.

To document a data type, use:

```xml
//gsoap namespace-prefix schema type-documentation: type-name //text
```

where `type-name` is the unqualified name of the data type and `text` is a line of text terminated by a newline. Do not use any XML reserved characters in `text` such as `<` and `>`. Use well-formed XML and XHTML markup instead. For example:

```xml
//gsoap ns schema type-documentation: tdata stores <a href="transaction.html">transaction</a>
data
class ns_.tdata
{ ... }
```

To document a data type's fields and members, use:

```xml
//gsoap namespace-prefix schema type-documentation: type-name::field //text
```

where `type-name` is the unqualified name of the data type, `field` is a field, member, or enum name, and `text` is a line of text terminated by a newline. Do not use any XML reserved characters in `text` such as `<` and `>`. Use well-formed XML and XHTML markup instead. For example:

```xml
//gsoap ns schema type-documentation: tdata::id the transaction number
//gsoap ns schema type-documentation: tdata::state transaction state
//gsoap ns schema type-documentation: tstate::INIT initial state
//gsoap ns schema type-documentation: tstate::DONE final state
```
The documentation form above can also be used to document SOAP/XML message parts in the generated WSDL. For the type-name use the function name. For the field names, you can use the function name and/or the function argument names.

To document a method, use:

```gsoap namespace-prefix service method-documentation: method-name //text```

where `method-name` is the unqualified name of the method and `text` is a line of text terminated by a newline. Do not use any XML reserved characters in `text` such as `<` and `>`. Use well-formed XML and XHTML markup instead. For example:

```gsoap ns service method-documentation: getQuote returns a <i>stock quote</i>```

```int ns_.getQuote(char *symbol, float &result);```

To specify the SOAP Action for a SOAP method, use:

```gsoap namespace-prefix service method-action: method-name action```

where `method-name` is the unqualified name of the method and `action` is a string without spaces and blanks (the string can be quoted when preferred). For example:

```gsoap ns service method-action: getQuote ""
int ns_.getQuote(char *symbol, float &result);```

Or, alternatively for the input action (part of the request):

```gsoap ns service method-input-action: getQuote ""
int ns_.getQuote(char *symbol, float &result);```

To specify the HTTP “location” of REST methods to a perform POST/GET/PUT action, use:

```gsoap namespace-prefix service method-action: method-name action```

where `method-name` is the unqualified name of the method and `action` is a string without spaces and blanks (the string can be quoted when preferred). This directive requires that the `protocol` directive for this method is set to HTTP, POST, GET, or PUT.

A response action and fault action are defined by:

```gsoap namespace-prefix service method-output-action: method-name action```

```gsoap namespace-prefix service method-fault-action: method-name action```

To override the SOAP or REST protocol of an operation (SOAP by default), use:
namespace-prefix service method-protocol: method-name protocol

where protocol is one of

- SOAP default SOAP transport (supports 1.1 and 1.2)
- SOAP1.1 SOAP 1.1 only
- SOAP1.2 SOAP 1.2 only
- SOAP-GET one-way SOAP with HTTP GET
- SOAP1.1-GET one-way SOAP 1.1 with HTTP GET
- SOAP1.2-GET one-way SOAP 1.1 with HTTP GET
- HTTP REST HTTP (POST or one-way PUT)
- POST REST HTTP POST
- GET one-way REST HTTP GET
- PUT one-way REST HTTP PUT
- DELETE REST HTTP DELETE

When document style is preferred for a particular service method, use:

//gsoap namespace-prefix service method-style: method-name document

When SOAP RPC encoding is required for a particular service method, use:

//gsoap namespace-prefix service method-encoding: method-name encoded

When literal encoding is required for a particular service method, use:

//gsoap namespace-prefix service method-encoding: method-name literal

or when the SOAP-ENV:encodingStyle attribute is different from the SOAP 1.1/1.2 encoding style, use:

//gsoap namespace-prefix service method-encoding: method-name encoding-style

When SOAP RPC encoding is required for a particular service method response when the request message is literal, use:

//gsoap namespace-prefix service method-response-encoding: method-name encoded

When literal encoding is required for a particular service method response when the request message is encoded, use:

//gsoap namespace-prefix service method-response-encoding: method-name literal

or when the SOAP-ENV:encodingStyle attribute is different from the SOAP 1.1/1.2 encoding style, use:

//gsoap namespace-prefix service method-response-encoding: method-name encoding-style
Note that the method-response-encoding is set to the value of method-encoding by default.

When header processing is required, each method declared in the WSDL should provide a binding to the parts of the header that may appear as part of a method request message. Such a binding is given by:

```
//gsoap namespace-prefix service method-header-part: method-name header-part
```

For example:

```c
struct SOAP_ENV__Header
{
  char *h__transaction;
  struct UserAuth *h__authentication;
};
```

Suppose method `ns__login` uses both header parts (at most), then this is declared as:

```
//gsoap ns service method-header-part: login h__transaction
//gsoap ns service method-header-part: login h__authentication
int ns__login(...);
```

Suppose method `ns__search` uses only the first header part, then this is declared as:

```
//gsoap ns service method-header-part: search h__transaction
int ns__search(...);
```

Note that the method name and header part names MUST be namespace qualified. The headers MUST be present in all operations that declared the header parts.

To specify the header parts for the method input (method request message), use:

```
//gsoap namespace-prefix service method-input-header-part: method-name header-part
```

Similarly, to specify the header parts for the method output (method response message), use:

```
//gsoap namespace-prefix service method-output-header-part: method-name header-part
```

The declarations above only affect the WSDL. For example:

```c
struct SOAP_ENV__Header
{
  char *h__transaction;
  struct UserAuth *h__authentication;
};
//gsoap ns service method-input-header-part: login h__authentication
//gsoap ns service method-input-header-part: login h__transaction
//gsoap ns service method-output-header-part: login h__transaction
int ns__login(...);
```
The headers MUST be present in all operations that declared the header parts.

To specify MIME attachments for the method input and output (method request and response messages), use:

```c
//gsoap namespace-prefix service method-mime-type: method-name mime-type
```

You can repeat this directive for all multipartRelated MIME attachments you want to associate with the method.

To specify MIME attachments for the method input (method request message), use:

```c
//gsoap namespace-prefix service method-input-mime-type: method-name mime-type
```

Similarly, to specify MIME attachments for the method output (method response message), use:

```c
//gsoap namespace-prefix service method-output-mime-type: method-name mime-type
```

You can repeat these directives for all multipartRelated MIME attachments you want to associate with the method.

**19.2.1 Example**

The use of directives is best illustrated with an example. The example uses a hypothetical stock quote service and exchange rate service, actual services such as these are available for free on the web.

```c
//gsoap ns1 service namespace: urn:GetQuote
int ns1__getQuote(char *symbol, float &result);

//gsoap ns2 service namespace: urn:CurrencyExchange
int ns2__getRate(char *country1, char *country2, float &result);

//gsoap ns3 service name: quotex
//gsoap ns3 service style: rpc
//gsoap ns3 service encoding: encoded
//gsoap ns3 service port: http://www.mydomain.com/quotex.cgi
//gsoap ns3 service namespace: urn:quotex
int ns3__getQuote(char *symbol, char *country, float &result);
```

The quotex.h example is a new Web Service created by combining two existing Web Services: a Stock Quote service and a Currency Exchange service.

Namespace prefix ns3 is used for the new quotex Web Service with namespace URI urn:quotex, service name quotex, and endpoint port http://www.mydomain.com/quotex.cgi.

Since the new Web Service invokes the ns1__getQuote and ns2__getRate service operations, the service namespaces and other details such as style and encoding of these methods are given by directives.

After invoking the gSOAP soapcpp2 tool on the quotex.h header file:

```bash
> soapcpp2 quotex.h
```

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the WSDL of the new quotex Web Service is saved as quotex.wsdl. Since the service name, endpoint port, and namespace URI were provided in the header file, the generated WSDL file can be published together with the compiled Web Service installed as a CGI application.

The namespace mapping table for the quotex.cpp Web Service implementation is saved as quotex.nsmap. This file can be directly included in quotex.cpp instead of specified by hand in the source of quotex.cpp:

```cpp
#include "quotex.nsmap"
```

The automatic generation and inclusion of the namespace mapping table requires compiler directives for all namespace prefixes to associate each namespace prefix with a namespace URI. Otherwise, namespace URIs have to be manually added to the table (they appear as http://tempuri.org).

### 19.3 Transient Data Types

There are situations when certain data types have to be ignored by gSOAP for the compilation of (de)marshalling routines. For example, in certain cases only a few members of a class or struct need not be (de)serialized, or the base class of a derived class should not be (de)serialized. Certain built-in classes such as `ostream` cannot be (de)serialized. Data parts that should be kept invisible to gSOAP are called “transient”. Transient data types and transient struct/class members are declared with the `extern` keyword or are declared within `[ ]` blocks in the header file. The `extern` keyword has a special meaning to the gSOAP soapcpp2 compiler and won’t affect the generated codes. The special `[ ]` block construct can be used with data type declarations and within `struct` and `class` declarations. The use of `extern` or `[ ]` achieve the same effect, but `[ ]` may be more convenient to encapsulate transient types in a larger part of the header file. The use of `extern` with `typedef` is reserved for the declaration of user-defined external (de)serializers for data types, see Section 19.5.

First example:

```cpp
extern class ostream; // ostream can’t be (de)serialized, but need to be declared to make it visible to gSOAP
class ns_.myClass
{ ...
  virtual void print(ostream &s) const; // need ostream here
  ...
};
```

Second example:

```cpp
[ class myBase // base class need not be (de)serialized
{ ... }
]
class ns_.myDerived : myBase
{ ... }
```
Third example:

```cpp
[ typedef int transientInt; ]

class ns__myClass
{
    int a; // will be (de)serialized
    [ int b; // transient field
    char s[256]; // transient field
    ]
    extern float d; // transient field
    char *t; // will be (de)serialized
    transientInt *n; // transient field
    [
        virtual void method(char buf[1024]); // does not create a char[1024] (de)serializer
    ]
};
```

In this example, `class ns__myClass` has three transient fields: b, s, and n which will not be (de)serialized in SOAP. Field n is transient because the type is declared within a transient block. Pointers, references, and arrays of transient types are transient. The single class method is encapsulated within [ and ] to prevent gSOAP from creating (de)serializers for the `char[1024]` type. gSOAP will generate (de)serializers for all types that are not declared within a [ and ] transient block.

### 19.4 Serialization ”as is” with Volatile Data Types

Volatile-declared data types in gSOAP are assumed to be part of an existing non-modifiable software package, such as a built-in library. It would not make sense to redefine the data types in a gSOAP header file. In certain cases it could also be problematic to have classes augmented with serializer methods. When you need to (de)serialize such data types ”as is”, you must declare them in a gSOAP header file and use the `volatile` qualifier.

Consider for example `struct tm`, declared in `time.h`. The structure may actually vary between platforms, but the tm structure includes at least the following fields:

```c
volatile struct tm
{
    int tm_sec; /* seconds (0 - 60) */
    int tm_min; /* minutes (0 - 59) */
    int tm_hour; /* hours (0 - 23) */
    int tm_mday; /* day of month (1 - 31) */
    int tm_mon; /* month of year (0 - 11) */
    int tm_year; /* year - 1900 */
    int tm_wday; /* day of week (Sunday = 0) */
    int tm_yday; /* day of year (0 - 365) */
    int tm_isdst; /* is summer time in effect? */
    char *tm_zone; /* abbreviation of timezone name */
    long tm_gmtoff; /* offset from UTC in seconds */
};
```
Note that we qualified the structure `volatile` in the gSOAP header file to inform the gSOAP soapcpp2 compiler that it should not attempt to redeclare it. We can now readily serialize and deserialize the `tm` structure. The following program fragment serializes the local time stored in a `tm` structure to stdout:

```c
struct soap *soap = soap_new();
...
time_t T = time(NULL);
struct tm *t = localtime(&T);
struct soap *soap = soap_new();
soap_write_tm(soap, t);
soap_destroy(soap);
soap_end(soap);
soap_free(soap);  // detach and free context
```

It is also possible to serialize the `tm` fields as XML attributes using the `@` qualifier, see Section 11.6.7. If you must produce a schema file, say `time.xsd`, that defines an XML schema and namespace for the `tm` struct, you can add a `typedef` declaration to the header file:

```c
typedef struct tm time_struct_tm;
```

We used the `typedef` name `time_struct_tm` rather than `time_struct`, because a schema name clash will occur with the latter since taking off the `time` prefix will result in the same name being used.

Classes should be declared `volatile` to prevent modification of these classes by the gSOAP source code output. Note that gSOAP adds serialization methods to classes to support polymorphism. However, this is a problem when you can’t modify class declarations because they are part of a non-modifiable software package. The solution is to declare these classes `volatile`, similar to the `tm` structure example illustrated above. You can also use a `typedef` to associate a schema with a class.

### 19.5 How to Declare User-Defined Serializers and Deserializers

Users can declare their own (de)serializers for specific data types instead of relying on the gSOAP-generated (de)serializers. To declare a external (de)serializer, declare a type with `extern typedef`. gSOAP will not generate the (de)serializers for the type name that is declared. For example:

```c
extern typedef char *MyData;
struct Sample
{
    MyData s;  // use user-defined (de)serializer for this field
    char *t;   // use gSOAP (de)serializer for this field
};
```

The user is required to supply the following routines for each `extern typedef`ed name `T`:

```c
void soap_serialize_T(struct soap *soap, const T *a)
void soap_default_T(struct soap *soap, T *a)
```
The function prototypes can be found in soapH.h.

For example, the (de)serialization of MyData can be done with the following code:

```c
void soap_serialize_MyData(struct soap *soap, MyData *const *a)
{
    // no need to mark this node (for multi-ref and cycle detection)
}
void soap_default_MyData(&soap, MyData **a)
{
    *a = NULL
}

void soap_out_MyData(struct soap *soap, const char *tag, int id, MyData *const *a, const char *type)
{
    soap_element_begin_out(soap, tag, id, type); // print XML beginning tag
    soap_send(soap, *a); // just print the string (no XML conversion)
    soap_element_end_out(soap, tag); // print XML ending tag
}
MyData **soap_in_MyData(struct soap *soap, const char *tag, MyData **a, const char *type)
{
    if (soap_element_begin_in(soap, tag))
        return NULL;
    if (!a)
        a = (MyData**)soap_malloc(soap, sizeof(MyData*));
    if (soap->null)
        *a = NULL; // xsi:nil element
    if (*soap->type && soap_match_tag(soap, soap->type, type))
    {
        soap->error = SOAP_TYPE;
        return NULL; // type mismatch
    }
    if (*soap->href)
        a = (MyData**)soap_id_forward(soap, soap->href, a, SOAP_MyData, sizeof(MyData*))
    else if (soap->body)
    {
        char *s = soap_value(soap); // fill buffer
        *a = (char*)soap_malloc(soap, strlen(s)+1);
        strcpy(*a, s);
    }
    if (soap->body && soap_element_end_in(soap, tag))
        return NULL;
    return a;
}

More information on custom (de)serialization will be provided in this document or in a separate document in the future. The writing of the (de)serializer code requires the use of the low-level gSOAP API.

19.6 How to Serialize Data Without Generating XSD Type Attributes

gSOAP serializes data in XML with xsi:type attributes when the types are declared with namespace prefixes to indicate the schema type of the data contained in the elements. SOAP 1.1 and 1.2
requires xsi:type attributes in the presence of polymorphic data or when the type of the data cannot be deduced from the SOAP payload. The namespace prefixes are associated with the type names of typedefs (Section 11.3) for primitive data types, struct/class names, and enum names. To prevent the output of these xsi:type attributes in the XML serialization, you can simply use type declarations that do not include these namespace prefixes. That is, don’t use the typedefs for primitive types and use unqualified type names with structs, classes, and enums.

However, there are two issues. Firstly, if you want to use a primitive schema type that has no C/C++ counterpart, you must declare it as a typedef name with a leading underscore, as in:

```c
typedef char *xsd_date;
```

This will produce the necessary xsd:date information in the WSDL output by the gSOAP soapcpp2 compiler. But the XML serialization of this type at run time won’t include the xsi:type attribute. Secondly, to include the proper schema definitions in the WSDL produced by the gSOAP soapcpp2 compiler, you should use qualified struct, class, and enum names with a leading underscore, as in:

```c
struct ns_myStruct
{
...
};
```

This ensures that myStruct is associated with a schema, and therefore included in the appropriate schema in the generated WSDL. The leading underscore prevents the XML serialization of xsi:type attributes for this type in the SOAP/XML payload.

### 19.7 Function Callbacks for Customized I/O and HTTP Handling

gSOAP provides five callback functions for customized I/O and HTTP handling:

<table>
<thead>
<tr>
<th>Callback (function pointer)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SOAP_SOCKET (*soap.fopen)(struct soap *soap, const char *endpoint, const char *host, int port)</td>
<td>Called from a client proxy to open a connection to a Web Service located at endpoint. Input parameters host and port are micro-parsed from endpoint. Should return a valid file descriptor, or SOAP_INVALID_SOCKET and soap-&gt;error set to an error code. Built-in gSOAP function: tcp_connect</td>
</tr>
<tr>
<td>int (*soap.fclose)(struct soap *soap)</td>
<td>Called by client proxy multiple times, to close a socket connection before a new socket connection is established and at the end of communications when the SOAP_IO_KEEPALIVE flag is not set and soap.keep_alive≠0 (indicating that the other party supports keep alive). Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: tcp_disconnect</td>
</tr>
</tbody>
</table>
Callback (function pointer)

**int (*soap.fget)(struct soap *soap)**

Called by the main server loop upon an HTTP GET request. The SOAP_METHOD error is returned by default. This callback can be used to respond to HTTP GET methods with content, see Section 19.10. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_get`

**int (*soap.fput)(struct soap *soap)**

Called by the main server loop upon an HTTP PUT request. The SOAP_METHOD error is returned by default. This callback can be used to respond to HTTP PUT methods. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_put`

**int (*soap.fdel)(struct soap *soap)**

Called by the main server loop upon an HTTP DELETE request. The SOAP_METHOD error is returned by default. This callback can be used to respond to HTTP DELETE methods. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_del`

**int (*soap.fhead)(struct soap *soap)**

Called by the main server loop upon an HTTP HEAD request. The SOAP_METHOD error is returned by default. This callback can be used to respond to HTTP HEAD methods. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_get`

**int (*soap.fform)(struct soap *soap)**

Called by the main server loop when a user-defined fparsehdr callback returned SOAP_FORM to signal that the HTTP body must be processed by this form handler callback. The HTTP POST form data MUST be read, otherwise keep-alive messages will end up out of sync. Should return SOAP_OK or a gSOAP error code. Built-in gSOAP function: none.

**int (*soap.fpost)(struct soap *soap, const char *endpoint, const char *host, int port, const char *path, size_t count)**

Called from a client proxy to generate the HTTP header to connect to endpoint. Input parameters host, port, and path are micro-parsed from endpoint, action is the SOAP action, and count is the length of the SOAP message or 0 when SOAP_ENC_XML is set or when SOAP_IO_LENGTH is reset. Use function `soap.send(struct soap *soap, char *s)` to write the header contents. Should return SOAP_OK or a gSOAP error code. Built-in gSOAP function: `http_post`.

**int (*soap.fposthdr)(struct soap *soap, const char *key, const char *val)**

Called by `http_post` and `http_response` (through the callbacks). Emits HTTP key: val header entries. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_post_header`.

**int (*soap.fresponse)(struct soap *soap, int soap_error_code, size_t count)**

Called from a service to generate the response HTTP header. Input parameter soap_error_code is a gSOAP error code (see Section 10.2 and count is the length of the SOAP message or 0 when SOAP_ENC_XML is set or when SOAP_IO_LENGTH is reset. Use function `soap.send(struct soap *soap, char *s)` to write the header contents. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_response`.

**int (*soap.fparse)(struct soap *soap)**

Called by client proxy and service to parse an HTTP header (if present). When user-defined, this routine must at least skip the header. Use function `int soap.getline(struct soap *soap, char *buf, int len)` to read HTTP header lines into a buffer buf of length len (returns empty line at end of HTTP header). Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `http_parse`

**int (*soap.fparsehdr)(struct soap *soap, const char *key, const char *val)**

Called by `http_parse` (through the fparse callback). Handles HTTP key: val header entries to set gSOAP’s internals. Should return SOAP_OK, SOAP_STOP (see fstop) or a gSOAP error code. Built-in gSOAP function: `http_parse_header`
Callback (function pointer)

```c
int (*soap.fsend)(const struct soap *soap, const char *s, size_t n)
```
Called for all send operations to emit contents of `s` of length `n`. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: `fsend`

```c
size_t (*soap.frecv)(const struct soap *soap, char *s, size_t n)
```
Called for all receive operations to fill buffer `s` of maximum length `n`. Should return the number of bytes read or 0 in case of an error, e.g., EOF. Built-in gSOAP function: `recv`

```c
int (*soap.fignore)(const struct soap *soap, const char *tag)
```
Called when an unknown XML element was encountered on the input. The `tag` parameter is the offending XML element tag name. Should return SOAP_OK, or a gSOAP error code such as SOAP_TAG_MISMATCH to throw an exception. Built-in gSOAP function: none.

```c
int (*soap.fconnect)(const struct soap *soap, const char *endpoint, const char *host, int port)
```
When non-NULL, this callback is called for all client-to-server connect operations instead of the built-in socket connect code. Therefore, it can be used to override the built-in connection establishment. Parameter `endpoint` contains the server endpoint URL, `host` the domain name or IP, and `port` the port number. Should return SOAP_OK, or a gSOAP error code. Built-in gSOAP function: none.

```c
SOAP_SOCKET (*soap.faccept)(const struct soap *soap, SOAP_SOCKET s, struct sockaddr *a, int *n)
```
Called by `soap:accept`. This is a wrapper routine for `accept`. Given master socket `s` should return a valid socket descriptor or SOAP_INVALID_SOCKET and set `soap->error` to an error code. Built-in gSOAP function: `tcp_accept`

```c
int (*soap.fresolve)(const struct soap *soap, const char *addr, struct in_addr *inaddr)
```
Called by `soap:bind` if a host name is given and `soap:connect` to resolve a domain name `addr`. Should set in `addr` and return SOAP_OK or return SOAP_ERR upon failure.
Built-in gSOAP function: `tcp_gethost`

```c
int (*soap.fpoll)(const struct soap *soap)
```
Used by clients to check if the server is still responsive.
Built-in gSOAP function: `soap_poll`

```c
int (*soap.fserveloop)(const struct soap *soap)
```
Called after successful invocation of a server operation in the server loop, immediately after sending the response to a client. Can be used to clean up resources (e.g., using `soap:end()`) while serving a long sequence of keep-alive connections. Should return SOAP_OK, or set `soap->error` to a gSOAP error code and return `soap->error`. Built-in gSOAP function: none.

```c
void (*soap.fmalloc)(const struct soap *soap, size_t n)
```
Use to override memory allocation for deserialized C data. Memory allocated via this callback will not be automatically released by the gSOAP engine. The application must release this data by keeping track of the allocations. Note: it is not safe to traverse deserialized data structures and free each node, since data might be shared (SOAP multiref) and some allocated data such as the HTTP SOAPAction might not be part of the structure.
Built-in gSOAP function: none.

```c
int (*soap.fheader)(const struct soap *soap)
```
Called immediately after parsing a SOAP Header. The SOAP Header struct referenced by `soap->header` can be inspected and verified. The function should return SOAP_OK or a fault.
Built-in gSOAP function: none.

```c
void (*soap.fsvalidate)(const struct soap *soap, const char *pattern, const char *string)
```
Called to validate a non-NULL string against a non-NULL pattern. Patterns use XML schema regex syntax. Allows user-defined pattern validation. Should return SOAP_OK when the string matches the pattern or SOAP_PATTERN when the string does not match.
Built-in gSOAP function: none.

```c
void (*soap.fwvalidate)(const struct soap *soap, const char *pattern, const wchar_t *string)
```
Called to validate a non-NULL wide string against a non-NULL pattern. Patterns use XML schema regex syntax. Allows user-defined pattern validation. Should return SOAP_OK when the string matches the pattern or SOAP_PATTERN when the string does not match.
Built-in gSOAP function: none.

```c
void (*soap.fseterror)(const struct soap *soap, const char **code, const char **string)
```
Called to set the SOAP Fault code and string values based on the value of `soap->error`. Allows user-defined messages to be associated with gSOAP error codes to override gSOAP’s built-in error messages.
Built-in gSOAP function: none.
In addition, a `void*user` field in the `struct soap` data structure is available to pass user-defined data to the callbacks.

The following example uses I/O function callbacks for customized serialization of data into a fixed-size buffer and deserialization back into a datastructure:

```c
char buf[10000]; // XML buffer
int len1 = 0; // #chars written
int len2 = 0; // #chars read
// mysend: put XML in buf[]
int mysend(struct soap *soap, const char *s, size_t n)
{
    if (len1 + n > sizeof(buf))
        return SOAP_EOF;
    strcpy(buf + len1, s);
    len1 += n;
    return SOAP_OK;
}
// myrecv: get XML from buf[]
size_t myrecv(struct soap *soap, char *s, size_t n)
{
    if (len2 + n > len1)
        n = len1 - len2;
    strncpy(s, buf + len2, n);
    len2 += n;
    return n;
}
int main()
{
    struct soap soap;
    struct ns_person p;
    soap_init(&soap);
    len1 = len2 = 0; // reset buffer pointers
    p.name = "John Doe";
    p.age = 25;
    soap.fsend = mysend; // assign callback
    soap.frecv = myrecv; // assign callback
    soap.begin_send(&soap);
    soap.set_omode(&soap, SOAP_XML_TREE);
    soap.serialize_ns_person(&soap, &p);
    soap.put_ns_person(&soap, &p, "ns:person", NULL);
    soap.end_send(&soap);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
        exit(1);
    }
    soap.begin_recv(&soap);
    soap.get_ns_person(&soap, &p, "ns:person", NULL);
    soap.end_recv(&soap);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
        exit(1);
    }
    soap_free(&soap);
}
```

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A fixed-size buffer to store the outbound message sent is not flexible to handle large content. To store the message in an expanding buffer, use for example:

```c
struct buffer
{
    size_t len;
    size_t max;
    char *buf;
};

int main()
{
    struct buffer *h = malloc(sizeof(struct buffer));
    h->len = 0;
    h->max = 0;
    h->buf = NULL;
    soap.user = (void *)h; // pass buffer as a handle to the callback
    soap.fsend = mysend; // assign callback
    ...
    if (h->len)
    {
        ... // use h->buf[0..h->len-1] content
        // then cleanup:
        h->len = 0;
        h->max = 0;
        free(h->buf);
        h->buf = NULL;
    }
    }

int mysend(struct soap *soap, const char *s, size_t n)
{
    struct buffer *h = (struct buffer*)soap->user; // get buffer through handle
    int m = h->max, k = h->len + n;
    // need to increase space?
    if (m == 0)
        m = 1024;
    else
    
        while (k >= m)
        m *= 2;
    if (m != h->max)
    {
        char *buf = malloc(m);
        memcpy(buf, h->buf, h->len);
```
The `soap_done` function can be called to reset the callback to the default internal gSOAP I/O and HTTP handlers.

The following example illustrates customized I/O and (HTTP) header handling. The SOAP request is saved to a file. The client proxy then reads the file contents as the service response. To perform this trick, the service response has exactly the same structure as the request. This is declared by the `struct ns_.test` output parameter part of the service operation declaration. This struct resembles the service request (see the generated `soapStub.h` file created from the header file).

The header file is:

```c
//gsoap ns service name: callback
//gsoap ns service namespace: urn:callback
struct ns_.person
{
    char *name;
    int age;
};
int ns_.test(struct ns_.person in, struct ns_.test &out);
```

The client program is:

```c
#include "soapH.h"
...
SOAP_SOCKET myopen(struct soap *soap, const char *endpoint, const char *host, int port)
{
    if (strncmp(endpoint, "file:", 5))
    {
        printf("File name expected\n");
        return SOAP_INVALID_SOCKET;
    }
    if ((soap->sendfd = soap->recvfd = open(host, O_RDWR|O_CREAT, S_IWUSR|S_IRUSR)) < 0)
        return SOAP_INVALID_SOCKET;
    return soap->sendfd;
}
void myclose(struct soap *soap)
{
    if (soap->sendfd > 2) // still open?
        close(soap->sendfd); // then close it
    soap->recvfd = 0; // set back to stdin
    soap->sendfd = 1; // set back to stdout
```
```c
int mypost(struct soap *soap, const char *endpoint, const char *host, const char *path, const char *action, size_t count)
{
    return soap_send(soap, "Custom-generated file\n"); // writes to soap->sendfd
}

int myparse(struct soap *soap)
{
    char buf[256];
    if (lseek(soap->recvfd, 0, SEEK_SET) < 0 || soap_getline(soap, buf, 256)) // go to begin and skip custom header
        return SOAP_EOF;
    return SOAP_OK;
}

int main()
{
    struct soap soap;
    struct ns__test r;
    struct ns__person p;
    soap_init(&soap); // reset
    p.name = "John Doe";
    p.age = 99;
    soap=fopen = myopen; // use custom open
    soap.fpost = mypost; // use custom post
    soap.fparse = myparse; // use custom response parser
    soap.fclo = myclose; // use custom close
    soap_call_ns__test(&soap, "file://test.xml", ",", p, r);
    if (soap.error)
    {
        soap_print_fault(&soap, stdout);
        exit(1);
    }
    soap_end(&soap);
    soap_init(&soap); // reset to default callbacks
}
```

SOAP 1.1 and 1.2 specify that XML elements may be ignored when present in a SOAP payload on the receiving side. gSOAP ignores XML elements that are unknown, unless the XML attribute `mustUnderstand="true"` is present in the XML element. It may be undesirable for elements to be ignored when the outcome of the omission is uncertain. The `soap.fignore` callback can be set to a function that returns SOAP_OK in case the element can be safely ignored, or SOAP_MUSTUNDERSTAND to throw an exception, or to perform some application-specific action. For example, to throw an exception as soon as an unknown element is encountered on the input, use:

```c
int myignore(struct soap *soap, const char *tag)
{
    return SOAP_MUSTUNDERSTAND; // never skip elements (secure)
}
```

...soap.fignore = myignore;
soap_call_ns__method(&soap, ...); // or soap_serve(&soap);

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To selectively throw an exception as soon as an unknown element is encountered but element ns:xyz can be safely ignored, use:

```c
int myignore(struct soap *soap, const char *tag)
{
    if (soap_match_tag(soap, tag, "ns:xyz") != SOAP_OK)
        return SOAP.MustUnderstand;
    return SOAP_OK;
}
...
soap.ign(mynice); soap.call("ns:method(&soap, ..."); // or soap.serve(&soap)
...
struct Namespace namespaces[] = {
    {"SOAP-ENV", "http://schemas.xmlsoap.org/soap/envelope/"},
    {"SOAP-ENC", "http://schemas.xmlsoap.org/soap/encoding/"},
    {"xsi", "http://www.w3.org/2001/XMLSchema-instance"},
    {"xsd", "http://www.w3.org/2001/XMLSchema"},
    {"ns", "some-URI"}, // the namespace of element ns:xyz
    {NULL, NULL}
};
```

Function soap_match_tag compares two tags. The third parameter may be a pattern where * is a wildcard and - is a single character wildcard. So for example soap_match_tag(tag, "ns:*") will match any element in namespace ns or when no namespace prefix is present in the XML message.

The callback can also be used to keep track of unknown elements in an internal data structure such as a list:

```c
struct Unknown
{
    char *tag;
    struct Unknown *next;
};
int myignore(struct soap *soap, const char *tag)
{
    char *s = (char*)soap_malloc(soap, strlen(tag)+1);
    struct Unknown *u = (struct Unknown*)soap_malloc(soap, sizeof(struct Unknown));
    if (s & u)
    {
        strcpy(s, tag);
        u->tag = s;
        u->next = ulist;
        ulist = u;
    }
}
...
struct soap *soap;
struct Unknown *ulist = NULL;
soap_init(&soap);
```
soap.fignore = myignore;
soap_call_ns_method(&soap, ...); // or soapserve(&soap)
// print the list of unknown elements
soap_end(&soap); // clean up

19.8 HTTP 1.0 and 1.1

gSOAP uses HTTP 1.1 by default. You can revert to HTTP 1.0 as follows:

```c
struct soap soap;
soap_init(&soap);
...
soap.http_version = "1.0”;
```

This sets the HTTP version and reconfigures the engine to revert to HTTP 1.0. Note that you cannot use HTTP chunking with HTTP 1.0.

19.9 HTTP 307 Temporary Redirect Support

The client-side handling of HTTP 307 code "Temporary Redirect" and any of the redirect codes 301, 302, and 303 are not automated in gSOAP. Client application developers may want to consider adding a few lines of code to support redirects. It was decided not to automatically support redirects for the following reasons:

- Redirecting a secure HTTPS address to a non-secure HTTP address via 307 creates a security vulnerability.
- Cyclic redirects must be detected (e.g. allowing only a limited number of redirect levels).
- Redirecting HTTP POST will result in re-serialization and re-post of the entire SOAP request. The SOAP request message must be re-posted in its entirety when re-issuing the SOAP operation to a new address.

To implement client-side 307 redirect, add the following lines of code:

```c
char *endpoint = NULL; // use default endpoint given in WSDL (or add another one here)
int n = 10; // max redirect count
while (n--)
{
    if (soap_call_ns1_myMethod(soap, endpoint, ...))
    {
        if ((soap->error >= 301 && soap->error <= 303) || soap->error == 307)
            endpoint = soap_strdup(soap, soap->endpoint); // endpoint from HTTP 301, 302, 303, 307
        Location header
    } else
    { ... report and handle error
        break;
    }
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19.10 HTTP GET Support

To implement your own HTTP (HTTPS) GET request responses, you need to set the `soap.fget` callback. The callback is required to produce a response to the request in textual form, such as a Web page or a SOAP/XML response. This method does not work with CGI.

The following example produces a Web page upon a HTTP GET request (e.g. from a browser):

```c
struct soap *soap = soap_new();
soap->fget = http_get;
...
soap Serve(soap);
...
int http_get(struct soap *soap)
{
    soap_response(soap, SOAP_HTML); // HTTP response header with text/html
    soap_send(soap, "¡HTML¡My Web server is operational¡/HTML¡");
    soap_end_send(soap);
    return SOAP_OK;
}
```

The example below produces a WSDL file upon a HTTP GET with path ?wsdl:

```c
int http_get(struct soap *soap)
{
    FILE *fd = NULL;
    char *s = strchr(soap->path, '?');
    if (s && strcmp(s, '?wsdl'))
        return SOAP_GET_METHOD;
    fd = fopen("myservice.wsdl", "rb"); // open WSDL file to copy
    if (!fd)
        return 404; // return HTTP not found error
    soap->http_content = "text/xml"; // HTTP header with text/xml content
    soap_response(soap, SOAP_FILE);
    for (;;)
    {
        size_t r = fread(soap->tmpbuf, 1, sizeof(soap->tmpbuf), fd);
        if (r)
            break;
        if (soap_send_raw(soap, soap->tmpbuf, r))
            break; // can't send, but little we can do about that
    }
    fclose(fd);
    soap_end_send(soap);
    return SOAP_OK;
}
```
Using one-way SOAP/XML message, you can also return a SOAP/XML response:

```c
int http_get(struct soap *soap)
{
    if ((soap->omode & SOAP_IO) != SOAP_IO_CHUNK)
        soap_set_omode(soap, SOAP_IO_STORE); // if not chunking we MUST buffer entire content
to determine content length
    soap_response(soap, SOAP_OK);
    return soap_send_ns1__mySendMethodResponse(soap, "", NULL, ... params ...);
}
```

where `ns1__mySendMethodResponse` is a one-way message declared in a gSOAP header file as:

```c
int ns1__mySendMethodResponse(... params ..., void);
```

The generated `soapClient.cpp` includes the sending-side stub function.

### 19.11 TCP and HTTP Keep-Alive

gSOAP supports keep-alive socket connections. To activate keep-alive support, set the SOAP_IO_KEEPALIVE flag for both input and output modes, see Section 9.12. For example

```c
struct soap soap;
soap_init2(&soap, SOAP_IO_KEEPALIVE, SOAP_IO_KEEPALIVE);
```

When a client or a service communicates with another client or service that supports keep alive, the attribute `soap.keep_alive` will be set to 1, otherwise it is reset to 0 (indicating that the other party will close the connection). The connection maybe terminated on either end before the communication completed, for example when the server keep-alive connection has timed out. This generates a "Broken Pipe" signal on Unix/Linux platforms. This signal can be caught with a signal handler:

```c
signal(SIGPIPE, sigpipe_handle);
```

where, for example:

```c
void sigpipe_handle(int x) { }
```

Alternatively, broken pipes can be kept silent by setting:

```c
soap.socket_flags = MSG_NOSIGNAL;
```

This setting will not generate a sigpipe but read/write operations return SOAP_EOF instead. Note that Win32 systems do not support signals and lack the MSG_NOSIGNAL flag. The sigpipe handling and flags are not very portable.

A connection will be kept open only if the request contains an HTTP 1.0 header with "Connection: Keep-Alive" or an HTTP 1.1 header that does not contain "Connection: close". This means
that a gSOAP client method call should use "http://" in the endpoint URL of the request to the stand-alone service to ensure HTTP headers are used.

If the client does not close the connection, the server will wait forever when no recv_timeout is specified. In addition, other clients will be denied service as long as a client keeps the connection to the server open. To prevent this from happening, the service should be multi-threaded such that each thread handles the client connection:

```c
int main(int argc, char **argv)
{
    struct soap soap, *tsoap;
    pthread_t tid;
    int m, s;
    soap_init2(&soap, SOAP_IO_KEEPALIVE, SOAP_IO_KEEPALIVE);
    soap.max_keep_alive = 100; // at most 100 calls per keep-alive session
    soap.accept_timeout = 600; // optional: let server time out after ten minutes of inactivity
    m = soap_bind(&soap, NULL, 18000, BACKLOG); // use port 18000 on the current machine
    if (m < 0)
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    fprintf(stderr, "Socket connection successful %d\n", m);
    for (count = 0; count >= 0; count++)
    {
        soap.socket_flags = MSG_NOSIGNAL; // use this
        soap.accept_flags = SO_NOSIGPIPE; // or this to prevent sigpipe
        s = soap_accept(&soap);
        if (s < 0)
        {
            if (soap.ernum)
                soap_print_fault(&soap, stderr);
            else
                fprintf(stderr, "Server timed out\n"); // Assume timeout is long enough for threads to
                complete serving requests
                break;
        }
        fprintf(stderr, "Accepts socket %d connection from IP %d.%d.%d.%d\n", s, (int)(soap.ip>>24)&0xFF,
        (int)(soap.ip>>16)&0xFF, (int)(soap.ip>>8)&0xFF, (int)soap.ip&0xFF);
        tsoap = soap_copy(&soap);
        pthread_create(&tid, NULL, (void(*)(void*))process_request, (void*)tsoap);
    }
    return 0;
}

void *process_request(void *soap)
{
    pthread_detach(pthread_self());
    ((struct soap*)soap)->recv_timeout = 300; // Timeout after 5 minutes stall on recv
    ((struct soap*)soap)->send_timeout = 60; // Timeout after 1 minute stall on send
    soap_serve((struct soap*)soap);
    soap_destroy((struct soap*)soap);
    soap_end((struct soap*)soap);
    ```
soap_free((struct soap*)soap);
return NULL;
}

To prevent a malicious client from keeping a thread waiting forever by keeping the connection open, timeouts are set in the `process_request` routine as shown. See Section 19.19 for more details on timeout settings.

A gSOAP client call will automatically attempt to re-establish a connection to a server when the server has terminated the connection for any reason. This way, a sequence of calls can be made to the server while keeping the connection open. Client stubs will poll the server to check if the connection is still open. When the connection was terminated by the server, the client will automatically reconnect.

A client should reset `SOAP_IO_KEEPALIVE` just before the last call to a server to close the connection after this last call. This will close the socket after the call and also informs the server to gracefully close the connection.

The client-side can also set the TCP keep-alive socket properties, using the `soap.tcp KEEP alive` flag (set to 1 to enable), `soap.tcp KEEP idle` to set the TCP_KEEPIDLE value, `soap.tcp KEEP intvl` to set the TCP_KEEPINTVL value, and `soap.tcp KEEP cnt` to set the TCP_KEEPCNT value.

If a client is in the middle of a soap call that might take a long time and the server goes away/down the caller does not get any feedback until the `soap.recv timeout` is reached. Enabling TCP keep alive on systems that support it allows for a faster connection teardown detection for applications that need it.

### 19.12 HTTP Chunked Transfer Encoding

gSOAP supports HTTP chunked transfer encoding. Un-chunking of inbound messages takes place automatically. Outbound messages are never chunked, except when the `SOAP_IO_CHUNK` flag is set for the output mode. Most Web services, however, will not accept chunked inbound messages.

### 19.13 HTTP Buffered Sends

The entire outbound message can be stored to determine the HTTP content length rather than the two-phase encoding used by gSOAP which requires a separate pass over the data to determine the length of the outbound message. Setting the flag `SOAP_IO_STORE` for the output mode will buffer the entire message. This can speed up the transmission of messages, depending on the content, but may require significant storage space to hold the verbose XML message.

Zlib compressed transfers require buffering. The `SOAP_IO_STORE` flag is set when the `SOAP_ENC_ZLIB` flag is set to send compressed messages. The use of chunking significantly reduces memory usage and may speed up the transmission of compressed SOAP/XML messages. This is accomplished by setting the `SOAP_IO_CHUNK` flag with `SOAP_ENC_ZLIB` for the output mode.
19.14 HTTP Authentication

HTTP authentication (basic) is enabled at the client-side by setting the `soap.userid` and `soap.passwd` strings to a username and password, respectively. A server may request user authentication and denies access (HTTP 401 error) when the client tries to connect without HTTP authentication (or with the wrong authentication information).

Here is an example client code fragment to set the HTTP authentication username and password:

```c
struct soap soap;
soap_init(&soap);
soap.userid = "guest";
soap.passwd = "visit";
...
```

A client SOAP request will have the following HTTP header:

```
POST /XXX HTTP/1.0
Host: YYY
User-Agent: gSOAP/2.2
Content-Type: text/xml; charset=utf-8
Content-Length: nnn
Authorization: Basic Z3Vlc3Q6Z3Vlc3Q=
...
```

A client MUST set the `soap.userid` and `soap.passwd` strings for each call that requires client authentication. The strings are reset after each successful or unsuccessful call.

When present, the value of the `WWW-Authenticate` HTTP header with the authentication realm can be obtained from the `soap.authrealm` string. This is useful for clients to respond intelligently to authentication requests.

A stand-alone gSOAP Web Service can enforce HTTP authentication upon clients, by checking the `soap.userid` and `soap.passwd` strings. These strings are set when a client request contains HTTP authentication headers. The strings SHOULD be checked in each service method (that requires authentication to execute).

Here is an example service method implementation that enforced client authentication:

```c
int ns_method(struct soap *soap, ...)
{
    if (!soap->userid || !soap->passwd || strcmp(soap->userid, "guest") || strcmp(soap->passwd, "visit"))
        return 401;
    ...
}
```

When the authentication fails, the service response with a SOAP Fault message and a HTTP error code "401 Unauthorized”. The HTTP error codes are described in Section 10.2.
19.15 HTTP NTLM Authentication

HTTP NTLM authentication is enabled at the client-side by installing libntlm from http://www.nongnu.org/libntlm and compiling all project source codes with -DWITH_NTLM.

In your application code set the soap.userid, soap.passwd, and soap.authrealm strings to a username, password, and the authentication domain respectively. A server may request NTLM authentication and denies access (HTTP 401 authentication required or HTTP 407 HTTP proxy authentication required) when the client tries to connect without HTTP authentication (or with the wrong authentication information).

Here is an example client code fragment to set the NTLM authentication username and password:

```c
struct soap soap;
soap_init1(&soap, SOAP_IO_KEEPALIVE);
if (soap_call_ns_method(&soap, ...))
{
    if (soap.error == 401)
    {
        soap.userid = "Zaphod";
        soap.passwd = "Beeblebrox";
        soap.authrealm = "Ursa-Minor";
        if (soap_call_ns_method(&soap, ...))
        ...
    }
}
```

The following NTLM handshake between the client C and server S is performed:

1: C --> S POST ...
   Content-Type: text/xml; charset=utf-8

2: C <-- S 401 Unauthorized
   WWW-Authenticate: NTLM

3: C --> S GET ...
   Authorization: NTLM <base64-encoded type-1-message>

4: C <-- S 401 Unauthorized
   WWW-Authenticate: NTLM <base64-encoded type-2-message>

5: C --> S POST ...
   Content-Type: text/xml; charset=utf-8
   Authorization: NTLM <base64-encoded type-3-message>

6: C <-- S 200 OK

where stages 1 and 2 indicates a client attempting to connect without authorization information, which is the first method call in the code above. Stage 3 to 6 happen with the proper client authentication set with soap.userid, soap.passwd, and soap.authrealm provided. NTLM authenticates connections, not requests. When the connection is kept alive, subsequent messages can be exchanged without re-authentication.

To avoid the overhead of the first rejected call, use:

```c
struct soap soap;
soap_init1(&soap, SOAP_IO_KEEPALIVE);
```
soap.userid = "Zaphod";
soap.passwd = "Beeblebrox";
soap.authrealm = "Ursa-Minor";
soap.ntlm_challenge = "";
if (soap_call_ns_method(&soap, ...))
    ...

When the authentication fails (stage 1 and 2), the service response with a SOAP Fault message and a HTTP error code "401 Unauthorized". The HTTP error codes are described in Section 10.2. On windows, an alternative is to use the WinInet module, which has built-in NTLM support. The WinInet for gSOAP module is available in the mod_gsoap directory of the gSOAP package. Instructions for WinInet use are included there.

19.16 HTTP Proxy NTLM Authentication

For HTTP 407 Proxy Authentication Required, set the proxy userid and passwd:

```
struct soap soap;
soap_init1(&soap, SOAP_IO_KEEPALIVE);
soap.proxy_host = "...";
soap.proxy_port = ...
if (soap_call_ns_method(&soap, ...))
    { if (soap.error == 407)
        { soap.proxy_userid = "Zaphod";
        soap.proxy_passwd = "Beeblebrox";
        soap.authrealm = "Ursa-Minor";
        if (soap_call_ns_method(&soap, ...))
            ...
```

To avoid the overhead of the first rejected call, use:

```
struct soap soap;
soap_init1(&soap, SOAP_IO_KEEPALIVE);
soap.proxy_host = "...";
soap.proxy_port = ...
soap.proxy_userid = "Zaphod";
soap.proxy_passwd = "Beeblebrox";
soap.authrealm = "Ursa-Minor";
soap.ntlm_challenge = "";
if (soap_call_ns_method(&soap, ...))
    ...
```

19.17 HTTP Proxy Basic Authentication

HTTP proxy authentication (basic) is enabled at the client-side by setting the soap.proxy_userid and soap.proxy_passwd strings to a username and password, respectively. For example, a proxy server may request user authentication. Otherwise, access is denied by the proxy (HTTP 407 error). Example client code fragment to set proxy server, username, and password:
```c
struct soap soap;
soap_init(&soap);
soap.proxy_host = "xx.xx.xx.xx";  // IP or domain
soap.proxy_port = 8080;
soap.proxy_userid = "guest";
soap.proxy_passwd = "guest";
...
```

A client SOAP request will have the following HTTP header:

```
POST /XXX HTTP/1.0
Host: YYY
User-Agent: gSOAP/2.2
Content-Type: text/xml; charset=utf-8
Content-Length: nnn
Proxy-Authorization: Basic Z3Vlc3Q6Z3Vlc3Q=
...
```

When X-Forwarded-For headers are returned by the proxy, the header can be accessed in the `soap.proxy_from_string`.

The CONNECT method is used for HTTP proxy authentication:

```
CONNECT server.example.com:80 HTTP/1.1
```

In some cases, it may be necessary to use the Host HTTP header with the CONNECT protocol:

```
CONNECT server.example.com:80 HTTP/1.1
Host: server.example.com:80
```

If so, compile the gSOAP code with `-DWITH_CONNECT_HOST` to include the Host HTTP header with the CONNECT protocol.

### 19.18 Messaging Speed and Performance Improvement Tips

Here are some tips you can use to speed up gSOAP. gSOAP’s default settings are chosen to maximize portability and compatibility. The settings can be tweaked to optimize the performance as follows:

- Increase the buffer size `SOAP_BUFSIZE` by changing the `SOAP_BUFSIZE` macro in `stdsoap2.h`. Use buffer size $2^{18} = 262144$ for example.

- Use HTTP keep-alive at the client-side, see 19.11, when the client needs to make a series of calls to the same server. Server-side keep-alive support can greatly improve performance of both client and server. But be aware that clients and services under Unix/Linux require signal handlers to catch dropped connections.

- Use HTTP chunked transfers, see 19.12.
- Do NOT use gzip compression, since the overhead of compression is typically higher than the bandwidth gains.

- Set the SOAP\_XML\_TREE flag to disable id-ref multi-ref object (de)serialization. This boosts performance significantly and works with SOAP document/literal style (i.e. no id-ref graph serialization as required with SOAP encoding style).

- Compile stdsoap2.c and stdsoap2.cpp with -DWITH\_NOIDREF to improve performance even better by permanently disabling id-ref multi-ref object (de)serialization.

- Do NOT use DEBUG mode, since the overhead of logging is significant.

### 19.19 Timeout Management for Non-Blocking Operations

Socket connect, accept, send, and receive timeout values can be set to manage socket communication timeouts. The \texttt{soap.connect\_timeout}, \texttt{soap.accept\_timeout}, \texttt{soap.send\_timeout}, and \texttt{soap.recv\_timeout} attributes of the current gSOAP runtime context \texttt{soap} can be set to the appropriate user-defined socket send, receive, and accept timeout values. A positive value measures the timeout in seconds. A negative timeout value measures the timeout in microseconds ($10^{-6}$ sec).

The \texttt{soap.connect\_timeout} specifies the timeout for \texttt{soap.call\_ns\_method} calls.

The \texttt{soap.accept\_timeout} specifies the timeout for \texttt{soap.accept(&soap)} calls.

The \texttt{soap.send\_timeout} and \texttt{soap.recv\_timeout} specify the timeout for non-blocking socket I/O operations.

Example:

```c
struct soap soap;
soap.init(&soap);
soap.send\_timeout = 10;
soap.recv\_timeout = 10;
```

This will result in a timeout if no data can be send in 10 seconds and no data is received within 10 seconds after initiating a send or receive operation over the socket. A value of zero disables timeout, for example:

```c
soap.send\_timeout = 0;
soap.recv\_timeout = 0;
```

When a timeout occurs in send/receive operations, a SOAP\_EOF exception will be raised (“end of file or no input”). Negative timeout values measure timeouts in microseconds, for example:

```c
#define uSec \texttt{-1}
#define mSec \texttt{-1000}
soap.accept\_timeout = 10 uSec;
soap.send\_timeout = 20 mSec;
soap.recv\_timeout = 20 mSec;
```
The macros improve readability.

**Caution:** many Linux versions do not support non-blocking `connect()`. Therefore, setting `soap.connect_timeout` for non-blocking `soap_call_ns_method` calls may not work under Linux.

**Caution:** interrupts (EINTR) can affect the blocking time in I/O operations. The maximum number of EINTR that will not trigger an error is set by `SOAP_MAXEINTR` in stdsoap2.h, which is 10 by default. Each EINTR may increase the blocking time by up to one second, up to `SOAP_MAXEINTR` seconds total.

19.20 Socket Options and Flags

gSOAP’s socket communications can be controlled with socket options and flags. The gSOAP run-time context `struct soap` flags are: `int soap.socket_flags` to control socket `send()` and `recv()` calls, `int soap.connect_flags` to set client connection socket options, `int soap.bind_flags` to set server-side port bind socket options, `int soap.accept_flags` to set server-side request message accept socket options. See the manual pages of `send` and `recv` for `soap.socket_flags` values and see the manual pages of `setsockopt` for `soap.connect_flags`, `soap.bind_flags`, and `soap.accept_flags` (SOL_SOCKET) values. These `SO` socket option flags (see `setsockopt` manual pages) can be bit-wise or-ed to set multiple socket options at once. The client-side flag `soap.connect_flags=SO_LINGER` is supported with values `l_onoff=1` and `l_linger=soap.linger_time`. The `soap.linger_time` determines the wait time (the time resolution is system dependent, though according to some experts only zero and nonzero values matter). The linger option can be used to manage the number of connections that remain in TIME_WAIT state at the server side.

For example, to disable sigpipe signals on Unix/Linux platforms use: `soap.socket_flags = MSG_NOSIGNAL` and/or `soap.connect_flags = SO_NOSIGPIPE` (i.e. client-side connect) depending on your platform.

Use `soap.bind_flags=SO_REUSEADDR` to enable server-side port reuse and local port sharing (but be aware of the possible security implications such as port hijacking).

Note that multiple socket options can be explicitly set with `setsockopt` as follows:

```c
int sock = soap_bind(soap, host, port, backlog);
if (soap_valid_socket(sock))
{
    setsockopt(sock, ..., ..., ...);
    setsockopt(sock, ..., ..., ...);
}
```

19.21 Secure Web Services with HTTPS/SSL

When a Web Service is installed as CGI, it uses standard I/O that is encrypted/decrypted by the Web server that runs the CGI application. HTTPS/SSL support must be configured for the Web server (not CGI-based Web Service application itself).

To enable SSL for stand-alone gSOAP servers, first install OpenSSL and use option `-DWITH_OPENSSL` to compile the sources with your C or C++ compiler (or use `-DWITH_GNUTLS` if you prefer GNUTLS), for example:
SSL support for stand-alone gSOAP Web services is enabled by calling `soap_ssl_accept` to perform the SSL/TLS handshake after `soap_accept`. In addition, a key file, a CA file (or path to certificates), DH file (if RSA is not used), and password need to be supplied. Instructions on how to do this can be found in the OpenSSL documentation [http://www.openssl.org](http://www.openssl.org). See also Section 19.24.

Let’s take a look at an example SSL secure multi-threaded stand-alone SOAP Web Service:

```c
int main()
{
    int m, s;
    pthread_t tid;
    struct soap *soap, *tsoap;
    soap_ssl_init(); /* init OpenSSL (just once) */
    if (CRYPTO_thread_setup()) // OpenSSL
    {
        fprintf(stderr, "Cannot setup thread mutex\n");
        exit(1);
    }
    soap_init(&soap);
    if (soap_ssl_server_context(&soap,
        SOAP_SSL_DEFAULT,
        "server.pem", /* keyfile: required when server must authenticate to clients (see SSL docs on how to obtain this file) */
        "password", /* password to read the key file (not used with GNUTLS) */
        "cacert.pem", /* optional cacert file to store trusted certificates */
        NULL, /* optional capath to directory with trusted certificates */
        "dh512.pem", /* DH file name or DH key len bits (minimum is 512, e.g. "512") to generate DH param, if NULL use RSA */
        NULL, /* if randfile!=NULL: use a file with random data to seed randomness */
        NULL /* optional server identification to enable SSL session cache (must be a unique name) */
    )
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    m = soap_bind(&soap, NULL, 18000, 100); // use port 18000
    if (m < 0)
    {
        soap_print_fault(&soap, stderr);
        exit(1);
    }
    fprintf(stderr, "Socket connection successful: master socket = %d\n", m);
    for (;;)
    {
        s = soap_accept(&soap);
        fprintf(stderr, "Socket connection successful: slave socket = %d\n", s);
        if (s < 0)
        {
            soap_print_fault(&soap, stderr);
        }
    }
}
```

250
break;
}
tsoap = soap_copy(&soap); /* should call soap_ssl_accept on a copy */
if (!tsoap)
    break;
pthread_create(&tid, NULL, &process_request, (void*)tsoap);
}
soap_done(&soap); /* deallocates SSL context */
CRYPTO_thread_cleanup(); // OpenSSL
return 0;
}
void *process_request(void *soap)
{
    pthread_detach(pthread_self());
    if (soapssl_accept((struct soap*)soap))
        soap_print_fault(tsoap, stderr);
    else
        soapserve((struct soap*)soap);
    soapdestroy((struct soap*)soap);
    soapend((struct soap*)soap);
    soapfree((struct soap*)soap); // done and free context
    return NULL;
}

The soap_ssl_server_context function initializes the server-side SSL context. The server.pem key file is the server’s private key concatenated with its certificate. The cacert.pem is used to authenticate clients and contains the client certificates. Alternatively a directory name can be specified. This directory is assumed to contain the certificates. The dh512.pem file specifies that DH will be used for key agreement instead of RSA. A numeric value greater than 512 can be provided instead as a string constant (e.g. "512") to allow the engine to generate the DH parameters on the fly (this can take a while) rather than retrieving them from a file. The randfile entry can be used to seed the PRNG. The last entry enable server-side session caching. A unique server name is required.

The GNUTLS mutex lock setup is automatically performed in the gSOAP engine, but only when POSIX threads are detected and available.

OpenSSL requires mutex locks to be explicitly setup in your code for multithreaded applications, for which we need to call CRYPTO_thread_setup() and CRYPTO_thread_cleanup(). These routines can be found in openssl/crypto/threads/th-lock.c and are also used in the SSL example codes samples/ssl. These routines are required to setup locks for multi-threaded applications that use SSL.

We give a Windows and POSIX threads implementation of these here:

```c
#include <unistd.h> /* defines _POSIX_THREADS if pthreads are available */
#ifdef _POSIX_THREADS
#include <pthread.h>
#endif
#if defined(WIN32)
#define MUTEX_TYPE HANDLE
#define MUTEX_SETUP(x) (x) = CreateMutex(NULL, FALSE, NULL)
#define MUTEX_CLEANUP(x) CloseHandle(x)
```
# define MUTEX
# define LOCK(x) WaitForSingleObject((x), INFINITE)
# define UNLOCK(x) ReleaseMutex(x)
# define THREAD_ID GetCurrentThreadID()
#if defined(_POSIX_THREADS)
# define MUTEX_TYPE pthread_mutex_t
# define SETUP(x) pthread_mutex_init(&(x), NULL)
# define CLEANUP(x) pthread_mutex_destroy(&(x))
# define LOCK(x) pthread_mutex_lock(&(x))
# define UNLOCK(x) pthread_mutex_unlock(&(x))
# define THREAD_ID pthread_self()
#else
# error "You must define mutex operations appropriate for your platform"
# error "See OpenSSL /threads/th-lock.c on how to implement mutex on your platform"
#endif

struct CRYPTO_dynlock_value {
    MUTEX_TYPE mutex;
};

static MUTEX_TYPE *mutex_buf;

static struct CRYPTO_dynlock_value *dyn_create_function(const char *file, int line)
{
    struct CRYPTO_dynlock_value *value;
    value = (struct CRYPTO_dynlock_value*)malloc(sizeof(struct CRYPTO_dynlock_value));
    if (value)
        MUTEX_SETUP(value->mutex);
    return value;
}

static void dyn_lock_function(int mode, struct CRYPTO_dynlock_value *l, const char *file, int line)
{
    if (mode & CRYPTO_LOCK)
        MUTEX_LOCK(l->mutex);
    else
        MUTEX_UNLOCK(l->mutex);
}

static void dyn_destroy_function(struct CRYPTO_dynlock_value *l, const char *file, int line)
{
    MUTEX_CLEANUP(l->mutex);
    free(l);
}

void locking_function(int mode, int n, const char *file, int line)
{
    if (mode & CRYPTO_LOCK)
        MUTEX_LOCK(mutex_buf[n]);
    else
        MUTEX_UNLOCK(mutex_buf[n]);
}

unsigned long id_function()
{
    return (unsigned long)THREAD_ID;
}

int CRYPTO_thread_setup()
{ 
    int i;
mutex_buf = (MUTEX_TYPE*)malloc(CRYPTO_num_locks() * sizeof(MUTEX_TYPE));
if (!mutex_buf)
    return SOAP_EOM;
for (i = 0; i < CRYPTO_num_locks(); i++)
    MUTEX_SETUP(mutex_buf[i]);
CRYPTO_set_id_callback(id_function);
CRYPTO_set_locking_callback(locking_function);
CRYPTO_set_dynlock_create_callback(dyn_create_function);
CRYPTO_set_dynlock_lock_callback(dyn_lock_function);
CRYPTO_set_dynlock_destroy_callback(dyn_destroy_function);
return SOAP_OK;
}

void CRYPTO_thread_cleanup()
{
    int i;
    if (!mutex_buf)
        return;
    CRYPTO_set_id_callback(NULL);
    CRYPTO_set_locking_callback(NULL);
    CRYPTO_set_dynlock_create_callback(NULL);
    CRYPTO_set_dynlock_lock_callback(NULL);
    CRYPTO_set_dynlock_destroy_callback(NULL);
    for (i = 0; i < CRYPTO_num_locks(); i++)
        MUTEX_CLEANUP(mutex_buf[i]);
    free(mutex_buf);
    mutex_buf = NULL;
}

For Unix and Linux, make sure you have signal handlers set in your service and/or client applications to catch broken connections (SIGPIPE):

    signal(SIGPIPE, sigpipe_handler);

where, for example:

    void sigpipe_handler(int x) { }

By default, clients are not required to authenticate. To support client authentication use the following:

    if (soap_ssl_server_context(&soap,
        SOAP_SSL_REQUIRE_CLIENT_AUTHENTICATION,
        "server.pem",
        "password",
        "cacert.pem",
        NULL,
        "dh512.pem",
        NULL,
        NULL)
    }}
{  
    soap_printFault(&soap, stderr);  
    exit(1);  
}

This requires each client to authenticate with its certificate.

Since release version 2.8.20 SSL v3 is disabled. To enable SSL v3 together with TLS v1 use SOAP_SSLv3_TLSv1 in soap_ssl_server_context.

The cacert file and capath are optional. Either one can be specified when clients must run on non-trusted systems (capath is not used with GNUTLS). We want to avoid storing trusted certificates in the default location on the file system when that is not secure. Therefore, a flat cacert.pem file or directory can be specified to store trusted certificates.

The gSOAP distribution includes a cacerts.pem file with the certificates of all certificate authorities such as Verisign. You can use this file to verify the authentication of servers that provide certificates issued by these CAs.

The cacert.pem, client.pem, and server.pem files in the gSOAP distribution are examples of self-signed certificates. The client.pem and server.pem contain the client/server private key concatenated with the certificate. The keyfiles (client.pem and server.pem) are created by concatenating the private key PEM with the certificate PEM. The keyfile SHOULD NEVER be shared with any party. With OpenSSL, you can encrypt the keyfiles with a password to offer some protection and the password is used in the client/server code to read the keyfile. GNUTLS does not support this feature and cannot encrypt or decrypt a keyfile.

**Caution:** it is important that the \texttt{WITH\_OPENSSL} macro MUST be consistently defined to compile the sources, such as stdsoap2.cpp, soapC.cpp, soapClient.cpp, soapServer.cpp, and all application sources that include stdsoap2.h or soapH.h. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP context.

### 19.22 Secure Clients with HTTPS/SSL

To utilize HTTPS/SSL, you need to install the OpenSSL library on your platform or GNUTLS for a light-weight SSL/TLS library. After installation, compile all the sources of your application with option \texttt{-DWITH\_OPENSSL} (or \texttt{-DWITH\_GNUTLS} when using GNUTLS). For example on Linux:

```bash
> c++ -DWITH\_OPENSSL myclient.cpp stdsoap.cpp soapC.cpp soapClient.cpp -lssl -lcrypto
```

or Unix:

```bash
> c++ -DWITH\_OPENSSL myclient.cpp stdsoap.cpp soapC.cpp soapClient.cpp -lxnet -lsocket -lnsl -lssl -lcrypto
```

or you can add the following line to soapdefs.h:

```c
#define WITH\_OPENSSL
```

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and compile with option -DWITH_SOAPDEFS_H to include soapdefs.h in your project. A client program simply uses the prefix https: instead of http: in the endpoint URL of a service operation call to a Web Service to use encrypted transfers (if the service supports HTTPS). You need to specify the client-side key file and password of the keyfile:

```c
soap_ssl_init(); /* init OpenSSL (just once) */
if (soap_ssl_client_context(&soap, SOAP_SSL_DEFAULT,
    "client.pem", /* keyfile: required only when client must authenticate to server (see SSL docs on how to obtain this file) */
    "password", /* password to read the key file (not used with GNUTLS) */
    "cacerts.pem", /* cacert file to store trusted certificates (needed to verify server) */
    NULL, /* capath to directory with trusted certificates */
    NULL, /* if randfile!=NULL: use a file with random data to seed randomness */
))
{ 
    soap_print_fault(&soap, stderr);
    exit(1);
}
soap_call_ns_mymethod(&soap, "https://domain/path/secure.cgi", "", ...);
```

By default, server authentication is enabled and the cacerts.pem or capath (not used with GNUTLS) must be set so that the CA certificates of the server(s) are accessible at run time. The cacerts.pem file included in the package contains the certificates of common CAs. This file must be supplied with the client, if server authentication is required. Alternatively, you can use the plugin/cacerts.h and plugin/cacerts.c code to embed CA certificates in your client code. Other client-side SSL options are SOAP_SSL_SKIP_HOST_CHECK to skip the host name verification check and SOAP_SSL_ALLOW_EXPIRED_CERTIFICATE to allow connecting to a host with an expired certificate. For example,

```c
soap_ssl_init(); /* init OpenSSL (just once) */
if (soap_ssl_client_context(&soap, SOAP_SSL_REQUIRE_SERVERAUTHENTICATION
    — SOAP_SSL_SKIP_HOST_CHECK, — SOAP_SSL_ALLOW_EXPIRED_CERTIFICATE,
    "client.pem", /* keyfile: required only when client must authenticate to server (see SSL docs on how to obtain this file) */
    "password", /* password to read the key file (not used with GNUTLS) */
    "cacerts.pem", /* cacert file to store trusted certificates (needed to verify server) */
    NULL, /* capath to directory with trusted certificates */
    NULL, /* if randfile!=NULL: use a file with random data to seed randomness */
))
{ 
    soap_print_fault(&soap, stderr);
    exit(1);
}
soap_call_ns_mymethod(&soap, "https://domain/path/secure.cgi", "", ...);
```

For systems based on Microsoft windows, the WinInet module can be used instead, see mod_gsoap/gsoap_win/wininet.
Since release version 2.8.20 SSL v3 is disabled. To enable SSL v3 together with TLS v1 use SOAP_SSLv3_TLSv1 in soap_ssl_client_context.

To disable server authentication for testing purposes, use the following:

```c
if (soap_ssl_client_context(&soap,
   SOAP_SSL_NO_AUTHENTICATION,
   NULL,
   NULL,
   NULL,
   NULL,
   NULL,
   NULL))
{
   soap_print_fault(&soap, stderr);
   exit(1);
}
```

This also assumes that the server does not require clients to authenticate (the keyfile is absent).

Make sure you have signal handlers set in your application to catch broken connections (SIGPIPE):

```c
signal(SIGPIPE, sigpipe_handle);
```

where, for example:

```c
void sigpipe_handle(int x) { }
```

**Caution:** it is important that the WITH_OPENSSL macro MUST be consistently defined to compile the sources, such as stdsoap2.cpp, soapC.cpp, soapClient.cpp, soapServer.cpp, and all application sources that include stdsoap2.h or soapH.h. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP context. **Caution:** concurrent client calls MUST be made using separate soap structs copied with soap_copy from an originating struct initialized with soap_ssl_client_context. In addition, the thread initialization code discussed in Section 19.21 MUST be used to properly setup OpenSSL in a multi-threaded client application.

### 19.23 SSL Authentication Callback

gSOAP provides a callback function for authentication initialization:

```c

Callback (function pointer)

int (*soap_fsslauth)(struct soap *soap)
```

Initialize the authentication information for clients and services, such as the certificate chain, password, read the key and/or DH file, generate an RSA key, and initialization of the RNG. Should return a gSOAP error code or SOAP_OK. Built-in gSOAP function: ssl_auth_init
19.24 SSL Certificates and Key Files

The gSOAP distribution includes a cacerts.pem file with the certificates of all certificate authorities (such as Verisign). You can use this file to verify the authentication of servers that provide certificates issued by these CAs. Just set the cafile parameter to the location of this file on your file system. Therefore, when you obtain a certificate signed by a trusted CA such as Verisign, you can simply use the cacerts.pem file to develop client applications that can verify the authenticity of your server.

Alternatively, you can use the plugin/cacerts.h and plugin/cacerts.c code to embed CA certificates in your client code.

For systems based on Microsoft Windows, the WinInet module can be used instead, see the README.txt located in the package under \mod_gsoap\gsoap_win\wininet.

The other .pem files in the gSOAP distribution are examples of self-signed certificates for testing purposes (cacert.pem, client.pem, server.pem). The client.pem and server.pem contain the private key and certificate of the client or server, respectively. The keyfiles (client.pem and server.pem) are created by concatenating the private key PEM with the certificate PEM. The keyfile SHOULD NEVER be shared with any party. With OpenSSL, you can encrypt the keyfiles with a password to offer some protection and the password is used in the client/server code to read the keyfile. GNUTLS does not support this feature and cannot encrypt or decrypt a keyfile.

You can also create your own self-signed certificates. There is more than one way to generate the necessary files for clients and servers. See http://www.openssl.org for information on OpenSSL and http://sial.org/howto/openssl/ca/ on how to setup and manage a local CA and http://sial.org/howto/openssl/self-signed/ on how to setup self-signed test certificates.

It is possible to convert IIS-generated certificates to PEM format with the openssl library and openssl command-line tool:

    openssl x509 -in mycert.cer -inform DER -out mycert.pem -outform PEM

This converts the CRT-formatted mycert.cer to PEM-formatted mycert.pem.

Here is the simplest way to setup self-signed certificates. First you need to create a private Certificate Authority (CA). The CA is used in SSL to verify the authenticity of a given certificate. The CA acts as a trusted third party who has authenticated the user of the signed certificate as being who they say. The certificate is signed by the CA, and if the client trusts the CA, it will trust your certificate. For use within your organization, a private CA will probably serve your needs. However, if you intend use your certificates for a public service, you should probably obtain a certificate from a known CA (e.g. VeriSign). In addition to identification, your certificate is also used for encryption.

Creating certificates should be done through a CA to obtain signed certificates. But you can create your own certificates for testing purposes as follows.

- Go to the OpenSSL bin directory (/usr/local/ssl by default and /System/Library/OpenSSL on Mac OS X)
- There should be a file called openssl.cnf
• Create a new directory in your home account, e.g. $HOME/CA, and copy the openssl.cnf file to this directory

• Modify openssl.cnf by changing the ‘dir’ value to HOME/CA

• Copy the README.txt, root.sh, and cert.sh scripts from the gSOAP distribution package located in the samples/ssl directory to HOME/CA

• Follow the README.txt instructions

You now have a self-signed CA root certificate cacert.pem and a server.pem (or client.pem) certificate in PEM format. The cacert.pem certificate is used in the cafile parameter of the soap_ssl_client_context (or soap_ssl_server_context) at the client (or server) side to verify the authenticity of the peer. You can also provide a capath parameter to these trusted certificates. The server.pem (or client.pem) must be provided with the soap_ssl_server_context at the server side (or soap_ssl_client_context at the client side) together with the password you entered when generating the certificate using cert.sh to access the file. These certificates must be present to grant authentication requests by peers. In addition, the server.pem (and client.pem) include the host name of the machine on which the application runs (e.g. localhost), so you need to generate new certificates when migrating a server (or client).

Finally, you need to generate Diffie-Hellmann (DH) parameters for the server if you wish to use DH instead of RSA. There are two options:

1. Set the dhfile parameter to the numeric DH prime length in bits required (for example ”1024”) to let the engine generate DH parameters at initialization. This can be time consuming.

2. Provide a file name for the dhfile parameter of soap_ssl_server_context. The file should be generated beforehand. To do so with the OpenSSL command line tool, use:

   ```
   > openssl dhparam -outform PEM -out dh.pem 512
   ```

   File dh512.pem is the output file and 512 is the number of bits used.

19.25 SSL Hardware Acceleration

You can specify a hardware engine to enable hardware support for cryptographic acceleration. This can be done once in a server or client with the following statements:

```c
static const char *engine = "cswift"; /* engine name */
int main()
{
    ...
    ENGINE *e;
    if (!e = ENGINE_by_id(engine))
        fprintf(stderr, "Error finding engine \%s
\n", engine);
    else if (!ENGINE_set_default(e, ENGINE_METHOD_ALL))
        fprintf(stderr, "Error using engine \%s\n", engine);
    ...
```

The following table lists the names of the hardware and software engines:
<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>openssl</td>
<td>The default software engine for cryptographic operations</td>
</tr>
<tr>
<td>openbsd_dev_crypto</td>
<td>OpenBSD supports kernel level cryptography</td>
</tr>
<tr>
<td>cswift</td>
<td>CryptoSwift acceleration hardware</td>
</tr>
<tr>
<td>chil</td>
<td>nCipher CHIL acceleration hardware</td>
</tr>
<tr>
<td>atalla</td>
<td>Compaq Atalla acceleration hardware</td>
</tr>
<tr>
<td>nuron</td>
<td>Nuron acceleration hardware</td>
</tr>
<tr>
<td>ubsec</td>
<td>Broadcom uBSec acceleration hardware</td>
</tr>
<tr>
<td>aep</td>
<td>Aep acceleration hardware</td>
</tr>
<tr>
<td>sureware</td>
<td>SureWare acceleration hardware</td>
</tr>
</tbody>
</table>

19.26 SSL on Windows

Set the full path to libssl.lib and libcrypto.lib under the MSVC++ "Projects" menu, then choose "Link": "Object/Modules". Please make sure libssl32.dll and libeay32.dll can be loaded by gSOAP applications, thus they must be installed properly on the target machine.

If you’re using compilation settings such as /MTd then link to the correct libeay32MTd.lib and ssleay32MTd.lib libraries.

Alternatively, you can use the WinInet interface available in the mod_gsoap directory of the gSOAP package. API instructions are included in the source.

19.27 Zlib Compression

To enable deflate and gzip compression with Zlib, install Zlib from http://www.zlib.org if not already installed on your system. Compile stdsoap2.cpp (or stdsoap2.c) and all your sources that include stdsoap2.h or soapH.h with compiler option -DWITH_GZIP and link your code with the Zlib library, e.g. -lz on Unix/Linux platforms.

The gzip compression is orthogonal to all transport encodings such as HTTP, SSL, DIME, and can be used with other transport layers. You can even save and load compressed XML data to/from files.

gSOAP supports two compression formats: deflate and gzip. The gzip format is used by default. The gzip format has several benefits over deflate. Firstly, gSOAP can automatically detect gzip compressed inbound messages, even without HTTP headers, by checking for the presence of a gzip header in the message content. Secondly, gzip includes a CRC32 checksum to ensure messages have been correctly received. Thirdly, gzip compressed content can be decompressed with other compression software, so you can decompress XML data saved by gSOAP in gzip format.

Gzip compression is enabled by compiling the sources with -DWITH_GZIP. To transmit gzip compressed SOAP/XML data, set the output mode flags to SOAP_ENC_ZLIB. For example:

```c
soap_init(&soap);
...
soap_set_omode(&soap, SOAP_ENC_ZLIB); // enable Zlib's gzip
if (soap_call_ns__myMethod(&soap, ...))
   ...
```

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This will send a compressed SOAP/XML request to a service, provided that Zlib is installed and linked with the application and the -DWITH_GZIP option was used to compile the sources. Receiving compressed SOAP/XML over HTTP either in gzip or deflate formats is automatic. The SOAP_ENC_ZLIB flag does not have to be set at the server side to accept compressed messages. Reading and receiving gzip compressed SOAP/XML without HTTP headers (e.g. with other transport protocols) is also automatic.

To control the level of compression for outbound messages, you can set the soap.z_level to a value between 1 and 9, where 1 is the best speed and 9 is the best compression (default is 6). For example

```c
soap_init(&soap);
... 
soap_set_omode(&soap, SOAP_ENC_ZLIB);
soap.z_level = 9; // best compression
...
```

To verify and monitor compression rates, you can use the values soap.z_ratio_in and soap.z_ratio_out. These two float values lie between 0.0 and 1.0 and express the ratio of the compressed message length over uncompressed message length.

```c
soap_call ns_myMethod(&soap, ...);
...
printf("Compression ratio: %f%% (in) %f%% (out)\n", 100*soap.z_ratio_out, 100*soap.z_ratio_in);
...
```

Note: lower ratios mean higher compression rates.

Compressed transfers require buffering the entire output message to determine HTTP message length. This means that the SOAP_IO_STORE flag is automatically set when the SOAP_ENC_ZLIB flag is set to send compressed messages. The use of HTTP chunking significantly reduces memory usage and may speed up the transmission of compressed SOAP/XML messages. This is accomplished by setting the SOAP_IO_CHUNK flag with SOAP_ENC_ZLIB for the output mode. However, some Web servers do not accept HTTP chunked request messages (even when they return HTTP chunked messages!). Stand-alone gSOAP services always accept chunked request messages.

To restrict the compression to the deflate format only, compile the sources with -DWITH_ZLIB. This limits compression and decompression to the deflate format. Only plain and deflated messages can be exchanged, gzip is not supported with this option. Receiving gzip compressed content is automatic, even in the absence of HTTP headers. Receiving deflate compressed content is not automatic in the absence of HTTP headers and requires the flag SOAP_ENC_ZLIB to be set for the input mode to decompress deflated data.

Caution: it is important that the WITH_GZIP and WITH_ZLIB macros MUST be consistently defined to compile the sources, such as stdsoap2.cpp, soapC.cpp, soapClient.cpp, soapServer.cpp, and all application sources that include stdsoap2.h or soapH.h. If the macros are not consistently used, the application will crash due to a mismatches in the declaration and access of the gSOAP context.
19.28 Client-Side Cookie Support

Client-side cookie support is optional. To enable cookie support, compile all sources with option -DWITH_COOKIES, for example:

```bash
> c++ -DWITH_COOKIES -o myclient stdsoap2.cpp soapC.cpp soapClient.cpp
```

or add the following line to stdsoap.h:

```c
#define WITH_COOKIES
```

Client-side cookie support is fully automatic. So just (re)compile stdsoap2.cpp with -DWITH_COOKIES to enable cookie-based session control in your client.

A database of cookies is kept and returned to the appropriate servers. Cookies are not automatically saved to a file by a client. An example cookie file manager is included as an extras in the distribution. You should explicitly remove all cookies before terminating a gSOAP context by calling `soap_free_cookies(soap)` or by calling `soap.done(soap)`.

To avoid "cookie storms" caused by malicious servers that return an unreasonable amount of cookies, gSOAP clients/servers are restricted to a database size that the user can limit (32 cookies by default), for example:

```c
struct soap soap;
soap_init(&soap);
soap.cookie_max = 10;
```

The cookie database is a linked list pointed to by `soap.cookies` where each node is declared as:

```c
struct soap_cookie
{
    char *name;
    char *value;
    char *domain;
    char *path;
    long expire; /* client-side: local time to expire; server-side: seconds to expire */
    unsigned int version;
    short secure;
    short session; /* server-side */
    short env; /* server-side: 1 = got cookie from client */
    short modified; /* server-side: 1 = client cookie was modified */
    struct soap_cookie *next;
};
```

Since the cookie database is linked to a `soap` struct, each thread has a local cookie database in a multi-threaded implementation.

19.29 Server-Side Cookie Support

Server-side cookie support is optional. To enable cookie support, compile all sources with option -DWITH_COOKIES, for example:
gSOAP provides the following cookie API for server-side cookie session control:

**Function**

```c
struct soap_cookie *soap_set_cookie(struct soap *soap, const char *name, const char *value, const char *domain, const char *path);
```

Add a cookie to the database with name `name` and value `value`. Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns pointer to a cookie node in the linked list, or NULL otherwise.

```c
struct soap_cookie *soap_cookie(struct soap *soap, const char *name, const char *domain, const char *path);
```

Find a cookie in the database with name `name` and value `value`. Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns pointer to a cookie node in the linked list, or NULL otherwise.

```c
char *soap_cookie_value(struct soap *soap, const char *name, const char *domain, const char *path);
```

Get value of a cookie in the database with name `name`. Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns the string pointer to the value, or NULL otherwise.

```c
long soap_cookie_expire(struct soap *soap, const char *name, const char *domain, const char *path);
```

Get expiration value of the cookie in the database with name `name` (in seconds). Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. Returns the expiration value, or -1 if cookie does not exist.

```c
int soap_set_cookie_expire(struct soap *soap, const char *name, long expire, const char *domain, const char *path);
```

Set expiration value `expire` of the cookie in the database with name `name` (in seconds). Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns `SOAP_OK`, or `SOAP_EOF` otherwise.

```c
int soap_set_cookie_session(struct soap *soap, const char *name, const char *domain, const char *path);
```

Set cookie in the database with name `name` to be a session cookie. This means that the cookie will be returned to the client. (Only cookies that are modified are returned to the client). Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns `SOAP_OK`, or `SOAP_EOF` otherwise.

```c
int soap_clr_cookie_session(struct soap *soap, const char *name, const char *domain, const char *path);
```

Clear cookie in the database with name `name` to be a session cookie. Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns `SOAP_OK`, or `SOAP_EOF` otherwise.

```c
void soap_clr_cookie(struct soap *soap, const char *name, const char *domain, const char *path);
```

Remove cookie from the database with name `name`. Domain and path may be NULL to use the current domain and path given by `soap_cookie_domain` and `soap_cookie_path`. If successful, returns `SOAP_OK`, or `SOAP_EOF` otherwise.

```c
int soap_getenv_cookies(struct soap *soap);
```

Initializes cookie database by reading the 'HTTP_COOKIE' environment variable. This provides a means for a CGI application to read cookies send by a client. If successful, returns `SOAP_OK`, or `SOAP_EOF` otherwise.

```c
void soap_free_cookies(struct soap *soap);
```

Release cookie database.

The following global variables are used to define the current domain and path:
<table>
<thead>
<tr>
<th>Attribute</th>
<th>value</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>const char *cookie_domain</code></td>
<td>MUST be set to the domain (host) of the service</td>
</tr>
<tr>
<td><code>const char *cookie_path</code></td>
<td>MAY be set to the default path to the service</td>
</tr>
<tr>
<td><code>int cookie_max</code></td>
<td>maximum cookie database size (default=32)</td>
</tr>
</tbody>
</table>

The `cookie_path` value is used to filter cookies intended for this service according to the path prefix rules outlined in RFC2109.

The following example server adopts cookies for session control:

```c
int main()
{
    struct soap soap;
    int m, s;
    soap_init(&soap);
    soap.cookie_domain = "...";
    soap.cookie_path = "/"; // the path which is used to filter/set cookies with this destination
    if (argc < 2)
    {
        soap.getenv_cookies(&soap); // CGI app: grab cookies from 'HTTP_COOKIE' env var
        soap.serve(&soap);
    }
    else
    {
        m = soap.bind(&soap, NULL, atoi(argv[1]), 100);
        if (m < 0)
            exit(1);
        for (int i = 1; ; i++)
        {
            s = soap.accept(&soap);
            if (s < 0)
                exit(1);
            soap.serve(&soap);
            soap.end(&soap); // clean up
            soap.free_cookies(&soap); // remove all old cookies from database so no interference occurs
            with the arrival of new cookies
        }
    }
    return 0;
}
int ck_demo(struct soap *soap, ...)
{
    int n;
    const char *s;
    s = soap_cookie_value(soap, "demo", NULL, NULL); // cookie returned by client?
    if (!s)
        s = "init-value"; // no: set initial cookie value
    else
        ... // modify 's' to reflect session control
    soap_set_cookie(soap, "demo", s, NULL, NULL);
    soap_set_cookie_expire(soap, "demo", 5, NULL, NULL); // cookie may expire at client-side in 5 seconds
} 263
return SOAP_OK;
}

19.30 Connecting Clients Through Proxy Servers

When a client needs to connect to a Web Service through a proxy server, set the soap.proxy.host string and soap.proxy.port integer attributes of the current soap runtime context to the proxy's host name and port, respectively. For example:

```
struct soap soap;
soap_init(&soap);
soap.proxy_host = "proxyhostname";
soap.proxy_port = 8080;
if (soap_call_ns_method(&soap, "http://host:port/path", "action", ...))
  soap_print_fault(&soap, stderr);
else
  ...
```

The attributes soap.proxy.host and soap.proxy.port keep their values through a sequence of service operation calls, so they only need to be set once.

When X-Forwarded-For headers are returned by the proxy, the header can be accessed in the soap.proxy.from string.

19.31 FastCGI Support

To enable FastCGI support, install FastCGI and compile all sources (do not use libgsoap but compile stdsoap2.c) and your application sources with option -DWITH_FASTCGI or add

```
#define WITH_FASTCGI
```

to stdsoap2.h and recompile the project code.

Caution: Do not link against the libgsoap libraries as these are not suitable for FastCGI. Compile stdsoap2.c (or stdsoap2.cpp) instead.

19.32 How to Create gSOAP Applications With a Small Memory Footprint

To compile gSOAP applications intended for small memory devices, you may want to remove all non-essential features that consume precious code and data space. To do this, compile the gSOAP sources with -DWITH_LEAN (i.e. #define WITH_LEAN) to remove many non-essential features. The features that will be disabled are:

- No I/O timeouts. Note that many socket operations already obey some form of timeout handling, such as a connect timeout for example.
- No UDP support
• No HTTP keep alive
• No HTTP cookies
• No HTTP authentication
• No HTTP chunked output (but input is OK)
• No HTTP compressed output (but input is OK when compiled with WITH_GZIP)
• No send/recv timeouts
• No socket flags (no soap.socket_flag, soap.connect_flag, soap.bind_flag, soap.accept_flag)
• No canonical XML output
• No logging
• Limited TCP/IP and HTTP error diagnostic messages
• No support for time_t serialization
• No support for hexBinary XML attribute serialization (remap hexBinary to strings by adding a remap entry to typemap.dat)

Use -DWITH_LEANER to make the executable even smaller by removing DIME and MIME attachment handling, LONG64 (64 bit) serialization, wchar_t* serialization, and support for XML DOM operations. Note that DIME/MIME attachments are not essential to achieve SOAP/XML interoperability. DIME attachments are a convenient way to exchange non-text-based (i.e. binary) content, but are not required for basic SOAP/XML interoperability. Attachment requirements are predictable. That is, applications won’t suddenly decide to use DIME or MIME instead of XML to exchange content.

It is safe to try to compile your application with -DWITHLEAN, provided that your application does not rely on I/O timeouts. When no linkage error occurs in the compilation process, it is safe to assume that your application will run just fine.

19.33 How to Eliminate BSD Socket Library Linkage

The stdsoap2.c and stdsoap2.cpp gSOAP runtime libraries should be linked with a BSD socket library in the project build, e.g. winsock2 for Win32. To eliminate the need to link a socket library, you can compile stdsoap2.c (for C) and stdsoap2.cpp (for C++) with the -DWITH_NOIO macro set (i.e. #define WITH_NOIO). This eliminates the dependency on the BSD socket API, IO streams, FILE type, and errno.

As a consequence, you MUST define callbacks to replace the missing socket stack. To do so, add to your code the following definitions:

```c
struct soap soap;
soap_init(&soap);
/* fsend is used to transmit data in blocks */
```
These functions are supposed to provide a (minimal) transport stack. See Section 19.7 for more details on the use of these callbacks. All callback function pointers should be non-NULL, except fpoll.

You cannot use soap_print_fault and soap_print_fault_location to print error diagnostics. Instead, the value of soap.error, which contains the gSOAP error code, can be used to determine the cause of a fault.

19.34 How to Combine Multiple Client and Server Implementations into one Executable

The wsdl2h tool can be used to import multiple WSDLs and schemas at once. The service definitions are combined in one header file to be parsed by soapcpp2. It is important to assign namespace prefixes to namespace URLs using the typemap.dat file. Otherwise, wsdl2h will assign namespace prefixes ns1, ns2, and so on to the service operations and schema types. Thus, any change to a WSDL or schema may result in a new prefix assignment. For more details, please see Section 8.2.

Another approach to combine multiple client and service applications into one executable is by using C++ namespaces to structurally separate the definitions or by creating C libraries for the client/server objects as explained in subsequent sections. This is automated with wsdl2h option -q.

Both approaches are demonstrated by example in the gSOAP distribution, the samples/link (C only) and samples/link++ (C++ with C++ namespaces) examples.

19.35 How to Build a Client or Server in a C++ Code Namespace

You can use a C++ code namespace of your choice in your header file to build a client or server in that code namespace. In this way, you can create multiple clients and servers that can be combined and linked together without conflicts, which is explained in more detail in the next section (which also shows an example combining two client libraries defined in two C++ code namespaces).

Use wsdl2h option -qname to generate definitions in the C++ name namespace. This option can also be used in combination with C++ proxy and server object generation, using soapcpp2 options...
At most one namespace can be defined for the entire gSOAP header file. The code namespace MUST completely encapsulate the entire contents of the header file:

```cpp
namespace myNamespaceName {
  ... gSOAP header file contents ...
}
```

When compiling this header file with the gSOAP soapcpp2 compiler, all type definitions, the (de)serializers for these types, and the stub/skeleton codes will be placed in this namespace. The XML namespace mapping table (saved in a .nsmap file) will not be placed in the code namespace to allow it to be linked as a global object. You can use option -n to create local XML namespace tables, see Section 9.1 (but remember that you explicitly need to initialize the soap.namespaces to point to a table at run time). The generated files are prefixed with the code namespace name instead of the usual soap file name prefix to enable multiple client/server codes to be build in the same project directory (a code namespace automatically sets the -p compiler option, see Section 9.1 for options).

Because the SOAP Header and Fault serialization codes will also be placed in the namespace, they cannot be called from the stdsoap2.cpp run time library code and are therefore rendered unusable. Therefore, these serializers are not compiled at all (enforced with #define WITH_NOGLOBAL). To add SOAP Header and Fault serializers, you MUST compile them separately as follows. First, create a new header file env.h with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```bash
> soapcpp2 -penv env.h
```

The generated envC.cpp file holds the SOAP Header and Fault serializers and you can link this file with your client or server application.

### 19.36 How to Create Client/Server Libraries

The gSOAP soapcpp2 compiler produces soapClientLib.cpp and soapServerLib.cpp codes that are specifically intended for building static or dynamic client/server libraries. These codes export the stubs and skeletons, but keep all marshaling code (i.e. parameter serializers and deserializers) local (i.e. as static functions) to avoid link symbol conflicts when combining multiple clients and/or servers into one executable. Note that it is far simpler to use the wsdl2h tool on multiple WSDL files to generate a header file that combines all service definitions. However, the approach presented in this section is useful when creating (dynamic) libraries for client and server objects, such as DLLs as described in Section 19.37.

Do not link soapClientLib.cpp or soapServerLib.cpp together with soapC.cpp, soapClient.cpp, and soapServer.cpp. The library versions already include all of the necessary definitions.

To build multiple libraries in the same project directory, you can define a C++ code namespace in your header file (see Section 19.35) or you can use soapcpp2 with option -p to rename the generated soapClientLib.cpp and soapServerLib.cpp (and associated) files. The -p option specifies the file name prefix to replace the soap prefix. The libraries don’t have to be C++ codes. You can use option -c to
generate C code. A clean separation of libraries can also be achieved with C++ code namespaces, see Section 19.35.

The library codes do not define SOAP Header and Fault serializers. You MUST add SOAP Header and Fault serializers to your application, which are compiled separately as follows. First, create a new header file env.h with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```
> soapcpp2 -penv env.h
```

The generated envC.cpp file holds the SOAP Header and Fault serializers and you can create a (dynamic) library for it to link this code with your client or server application.

You MUST compile the stdsoap2.cpp library using -DWITH_NONAMESPACES:

```
> c++ -DWITH_NONAMESPACES -c stdsoap2.cpp
```

This omits the reference to the global namespaces table, which is nowhere to be defined since we will use XML namespaces for each client/service separately. Therefore, you MUST explicitly set the namespaces value of the gSOAP context in your code every time after initialization of the soap struct with the soap_set_namespaces(struct soap*, const struct Namespace*) function.

For example, suppose we have two clients defined in header files client1.h and client2.h. We first generate the envH.h file for the SOAP Header and Fault definitions:

```
> soapcpp2 -c -penv env.h
```

Then we generate the code for client1 and client2:

```
> soapcpp2 -c -n -pmyClient1 client1.h
> soapcpp2 -c -n -pmyClient2 client2.h
```

This generates myClient1ClientLib.c and myClient2ClientLib.c (among many other files). These two files should be compiled and linked with your application. The source code of your application should include the generated envH.h, myClient1H.h, myClient2H.h files and myClient1.nsmap, myClient2.nsmap files:

```c
#include "envH.h"  // include this file first!
#include "myClient1H.h"  // include client 1 stubs
#include "myClient2H.h"  // include client 2 stubs
...
#include "myClient1H.nsmap"  // include client 1 nsmap
#include "myClient2H.nsmap"  // include client 2 nsmap
...
soap_init(&soap);
soap_set_namespaces(&soap, myClient1_namespaces);
... make Client 1 invocations ...
...
soap_set_namespaces(&soap, myClient2_namespaces);
... make Client 2 invocations ...
```
It is important to use `soapcpp2` option `-n`, see Section 9.1, to rename the namespace tables so we can include them all without running into redefinitions.

Note: Link conflicts may still occur in the unlikely situation that identical service operation names are defined in two or more client stubs or server skeletons when these methods share the same XML namespace prefix. You may have to use C++ code namespaces to avoid these link conflicts or rename the namespace prefixes used by the service operation defined in the header files.

### 19.36.1 C++ Clients Example

As an example we will build a Delayed Stock Quote client library and a Currency Exchange Rate client library.

First, we create an empty header file `env.h` (which may contain optional SOAP Header and Fault definitions), and compile it as follows:

```
> soapcpp2 -penv env.h
> c++ -c envC.cpp
```

We also compile `stdsoap2.cpp` without namespaces:

```
> c++ -c -DWITH_NONAMESPACES stdsoap2.cpp
```

Note: when you forget to use `-DWITH_NONAMESPACES` you will get an unresolved link error for the global `namespaces` table. You can define a dummy table to avoid having to recompile `stdsoap2.cpp`.

Second, we create the Delayed Stock Quote header file specification, which may be obtained using the WSDL importer. If you want to use C++ namespaces then you need to manually add the namespace declaration to the generated header file:

```
namespace quote {
    //gsoap ns service name: Service
    //gsoap ns service style: rpc
    //gsoap ns service encoding: encoded
    //gsoap ns service location: http://services.xmethods.net/soap
    //gsoap ns schema namespace: urn:xmethods-delayed-quotes
    //gsoap ns service method-action: getQuote ""
    int ns__getQuote(char *symbol, float &Result);
}
```

We then compile it as a library and we use option `-n` to rename the namespace table to avoid link conflicts later:

```
> soapcpp2 -n quote.h
> c++ -c quoteClientLib.cpp
```

If you don’t want to use a C++ code namespace, you should compile `quote.h` “as is” with `soapcpp2` option `-pquote`:

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Third, we create the Currency Exchange Rate header file specification:

```cpp
namespace rate {
    // gsoap ns service name: Service
    // gsoap ns service style: rpc
    // gsoap ns service encoding: encoded
    // gsoap ns service location: http://services.xmethods.net/soap
    // gsoap ns schema namespace: urn:xmethods-CurrencyExchange
    // gsoap ns service method-action: getRate ""
    int ns_getRate(char *country1, char *country2, float &Result);
}
```

Similar to the Quote example above, we compile it as a library and we use option `-n` to rename the namespace table to avoid link conflicts:

```bash
> soapcpp2 -n rate.h
```

Fourth, we consider linking the libraries to the main program. The main program can import the `quoteServiceProxy.h` and `rateServiceProxy.h` files to obtain client proxies to invoke the services. The proxy implementations are defined in `quoteClient.cpp`. The `-n` option also affects the generation of the C++ proxy codes to ensure that the gSOAP context is properly initialized with the appropriate namespace table (so you don’t have to initialize explicitly – this feature is only available with C++ proxy and server object classes).

```cpp
#include "quoteServiceProxy.h" // get quote Service proxy
#include "rateServiceProxy.h" // get rate Service proxy
#include "quote.nsmap" // get quote namespace bindings
#include "rate.nsmap" // get rate namespace bindings
int main(int argc, char *argv[]) {
    if (argc <= 1)
    {
        std::cerr << "Usage: main ticker [currency]" << std::endl
        exit(0);
    }
    quote::Service quote;
    float q;
    if (quote.getQuote(argv[1], q)) // get quote
        soap_print_fault(quote.soap, stderr);
    else
    {
        if (argc > 2)
        {
            rate::Service rate;
            float r;
            if (rate.getRate("us", argv[2], r)) // get rate in US dollars
```
soap_print_fault(rate.soap, stderr);
else
    q *= r; // convert the quote
} std::cout << argv[1] << ": " << q << std::endl;
return 0;
}

Compile and link this application with stdsoap2.o, envC.o, quoteServerProxy.o, and rateServerProxy.o.

To compile and link a server object is very similar. For example, assume that we need to implement a calculator service and we want to create a library for it.

namespace calc {
    //gsoap ns service name: Service
    //gsoap ns service style: rpc
    //gsoap ns service encoding: encoded
    //gsoap ns service location: http://www.cs.fsu.edu/~engelen/calc.cgi
    //gsoap ns schema namespace: urn:calc
    int ns__add(double a, double b, double &result);
    int ns__sub(double a, double b, double &result);
    int ns__mul(double a, double b, double &result);
    int ns__div(double a, double b, double &result);
}

We compile this with:

> soapcpp2 -n calc.h

The effect of the -n option is that it creates local namespace tables, and a modified calcServiceObject.h server class definitions that properly initialize the gSOAP run time with the table.

#include "calcServiceObject.h" // get Service object
#include "calc.nsmap" // get calc namespace bindings
...
calc::Service calc;
calc.serve(); // calls request dispatcher to invoke one of the functions below
...
int calc::Service::add(double a, double b, double &result);
{ result = a + b; return SOAP_OK; }
int calc::Service::sub(double a, double b, double &result);
{ result = a - b; return SOAP_OK; }
int calc::Service::mul(double a, double b, double &result);
{ result = a * b; return SOAP_OK; }
int calc::Service::div(double a, double b, double &result);
{ result = a / b; return SOAP_OK; }

In fact, the calc::Service class is derived from the struct soap. So the context is available as this, which can be passed to all gSOAP functions that require a soap struct context.
The example above serves requests over stdin/out. Use the bind and accept calls to create a stand-alone server to service inbound requests over sockets, see 7.2.3.

19.36.2 C Clients Example

This is the same example as above, but the clients are built with pure C.

We create a env.h that contains the joint SOAP Header and SOAP Fault definitions. You may have to copy-paste these from the other header files. Then, compile it as follows:

```bash
> soapcpp2 -c -penv env.h
> cc -c envC.c
```

We also compile stdsoap2.c without namespaces:

```bash
> cc -c - DwITh_NONAMESPACES stdsoap2.c
```

Second, we create the Delayed Stock Quote header file specification, which may be obtained using the WSDL importer.

```c
//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-delayed-quotes
//gsoap ns service method-action: getQuote ""
int ns__getQuote(char *symbol, float *Result);
```

We compile it as a library and we use options -n and -p to rename the namespace table to avoid link conflicts:

```bash
> soapcpp2 -c -n -pquote quote.h
> cc -c quoteClientLib.c
```

Third, we create the Currency Exchange Rate header file specification:

```c
//gsoap ns service name: Service
//gsoap ns service style: rpc
//gsoap ns service encoding: encoded
//gsoap ns service location: http://services.xmethods.net/soap
//gsoap ns schema namespace: urn:xmethods-CurrencyExchange
//gsoap ns service method-action: getRate ""
int ns__getRate(char *country1, char *country2, float *Result);
```

We compile it as a library and we use options -n and -p to rename the namespace table to avoid link conflicts:

```bash
> soapcpp2 -c -n -prate rate.h
> cc -c rateClientLib.c
```
The main program is:

```c
#include "quoteStub.h" // get quote Service stub
#include "rateStub.h" // get rate Service stub
#include "quote.nsmap" // get quote namespace bindings
#include "rate.nsmap" // get rate namespace bindings
int main(int argc, char *argv[])
{
    if (argc <= 1)
    {
        fprintf(stderr, "Usage: main ticker [currency]\n");
        exit(0);
    }
    struct soap soap;
    float q;
    soap_init(&soap);
    soap_set_namespaces(&soap, quote_namespaces);
    if (soap_call_ns__getQuote(&soap, "http://services.xmethods.net/soap", ",", argv[1], &q)) // get quote
        soap_print_fault(&soap, stderr);
    else
    {
        if (argc > 2)
        {
            soap_set_namespaces(&soap, rate_namespaces);
            float r;
            if (soap_call_ns__getRate(&soap, "http://services.xmethods.net/soap", ",", "us", argv[2], &r)) // get rate in US dollars
                soap_print_fault(&soap, stderr);
            else
                q *= r; // convert the quote
        }
        printf("%s: %f \n", argv[1], q);
    }
    return 0;
}
```

Compile and link this application with stdsoap2.o, envC.o, quoteClientLib.o, and rateClientLib.o.

To compile and link a server library is very similar. Assuming that the server is named “calc” (as specified with options -n and -p), the application needs to include the calcStub.h file, link the calcServerLib.o file, and call calcServe(&soap) function at run time.

### 19.36.3 C Services Chaining Example

We build a C application for multiple services served on one port.

We create an env.h that contains the joint SOAP Header and SOAP Fault definitions. You may have to copy-paste these from the other header files. Then, compile it as follows:

```bash
> soapcpp2 -c -penv env.h
```
We also compile stdsoap2.c without namespaces:

```bash
c -c envC.c
```

Say we have a service definition in `quote.h`. We compile it as a library and we use options -n and -p to rename the namespace table to avoid link conflicts:

```bash
soapcpp2 -c -n -pquote quote.h
c -c quoteClientLib.c
```

We do the same for a service definition in `rate.h`:

```bash
soapcpp2 -c -n -prate rate.h
c -c rateClientLib.c
```

To serve both the quote and rate services on the same port, we chain the service dispatchers as follows:

```c
struct soap *soap = soap_new();
soap_bind(soap, NULL, 8080, 100);
soap_accept(soap);
if (soap_begin_serve(soap))
  soap_send_fault(&abc); // send fault to client
else if (quote_serve_request(soap) == SOAP_NO_METHOD)
  {
    if (rate_serve_request(soap)) soap_send_fault(soap); // send fault to client
  }
else if (soap.error)
  soap_send_fault(soap); // send fault to client
soap_destroy(soap);
soap_end(soap);
soap_free(soap);
```

This chaining can be arbitrarily deep. When the previous request fails with a SOAP_NO_METHOD then next request dispatcher can be tried.

The server should also define the service operations:

```c
int ns__getQuote(struct soap *soap, char *symbol, float *Result);
{ *Result = ... ;
  return SOAP_OK;
}
int ns__getRate(struct soap *soap, char *country1, char *country2, float *Result);
{ *Result = ... ;
  return SOAP_OK;
}
```
19.37 How to Create DLLs

19.37.1 Create the Base stdsoap2.dll

First, create a new header file env.h with the SOAP Header and Fault definitions. You can leave this header file empty if you want to use the default SOAP Header and Fault. Then compile this header file with:

```
> soapcpp2 -penv env.h
```

The generated envC.cpp file holds the SOAP Header and Fault serializers, which need to be part of the base library functions.

The next step is to create stdsoap2.dll which consists of the file stdsoap2.cpp and envC.cpp. This DLL contains all common functions needed for all other clients and servers based on gSOAP. Compile envC.cpp and stdsoap2.cpp into stdsoap2.dll using the C++ compiler option -DWITH_NONAMESPACES and the MSVC Pre-Processor definitions SOAP_FMAC1=declspec(dllexport) and SOAP_FMAC3=declspec(dllexport) (or you can compile with -DWITH_SOAPDEFS_H and put the macro definitions in soapdefs.h). This exports all functions which are preceded by the macro SOAP_FMAC1 in the soapcpp2.cpp source file and macro SOAP_FMAC3 in the envC.cpp source file.

19.37.2 Creating Client and Server DLLs

Compile the soapClientLib.cpp and soapServerLib.cpp sources as DLLs by using the MSVC Pre-Processor definitions SOAP_FMAC5=declspec(dllexport) and SOAP_CMAC=declspec(dllexport), and by using the C++ compiler option -DWITH_NONAMESPACES. This DLL links to stdsoap2.dll.

To create multiple DLLs in the same project directory, you SHOULD use option -p to rename the generated soapClientLib.cpp and soapServerLib.cpp (and associated) files. The -p option specifies the file name prefix to replace the soap prefix. A clean separation of libraries can also be achieved with C++ namespaces, see Section 19.35.

Unless you use the client proxy and server object classes (soapXProxy.h and soapXObject.h where X is the name of the service), all client and server applications MUST explicitly set the namespaces value of the gSOAP context:

```c
soap_init(&soap);
soap_set_namespaces(&soap, namespaces);
```

where the namespaces[] table should be defined in the client/server source. These tables are generated in the .nsmap files. You can rename the tables using option -n, see Section 9.1.

19.38 gSOAP Plug-ins

The gSOAP plug-in feature enables a convenient extension mechanism of gSOAP capabilities. When the plug-in registers with gSOAP, it has full access to the run-time settings and the gSOAP function callbacks. Upon registry, the plug-in’s local data is associated with the gSOAP run-time. By overriding gSOAP’s function callbacks with the plug-in’s function callbacks, the plug-in can
extend gSOAP’s capabilities. The local plug-in data can be accessed through a lookup function, usually invoked within a callback function to access the plug-in data. The registry and lookup functions are:

```c
int soap_register_plugin_arg(struct soap *soap, int (*fcreate)(struct soap *, struct soap_plugin *p, void *arg), void *arg)
void* soap_lookup_plugin(struct soap*, const char*);
```

Other functions that deal with plug-ins are:

```c
int soap_copy(struct soap *soap);
void soap_done(struct soap *soap);
```

The `soap_copy` function returns a new dynamically allocated gSOAP context that is a copy of another, such that no data is shared between the copy and the original context. The `soap_copy` function invokes the plug-in copy callbacks to copy the plug-ins’ local data. The `soap_copy` function returns a gSOAP error code or `SOAP_OK`. The `soap_done` function de-registers all plugin-ins, so this function should be called to cleanly terminate a gSOAP run-time context.

An example will be used to illustrate these functions. This example overrides the send and receive callbacks to copy all messages that are sent and received to the terminal (stderr).

First, we write a header file `plugin.h` to define the local plug-in data structure(s) and we define a global name to identify the plug-in:

```c
#include "stdsoap2.h"
#define PLUGIN_ID "PLUGIN-1.0" // some name to identify plugin
struct plugin_data // local plugin data
{
    int (*fsend)(struct soap*, const char*, size_t); // to save and use send callback
    size_t (*frecv)(struct soap*, char*, size_t); // to save and use recv callback
};
int plugin(struct soap *soap, struct soap_plugin *plugin, void *arg);
```

Then, we write the plugin registry function and the callbacks:

```c
#include "plugin.h"

static const char plugin_id[] = PLUGIN_ID; // the plugin id
static int plugin_init(struct soap *soap, struct plugin_data *data);
static int plugin_copy(struct soap *soap, struct soap_plugin *dst, struct soap_plugin *src);
static void plugin_delete(struct soap *soap, struct soap_plugin *p);
static int plugin_send(struct soap *soap, const char *buf, size_t len);
static size_t plugin_recv(struct soap *soap, char *buf, size_t len);
// the registry function:
int plugin(struct soap *soap, struct soap_plugin *p, void *arg)
{
    p->id = plugin_id;
    p->data = (void*)malloc(sizeof(struct plugin_data));
    p->copy = plugin_copy; /* optional: when set the plugin must copy its local data */
    p->fdelete = plugin_delete;
```
if (p->data)
  if ((plugin_init(soap, (struct plugin_data*)p->data))
  {
    free(p->data); // error: could not init
    return SOAP_EOM; // return error
  }
  return SOAP_OK;
}

static int plugin_init(struct soap *soap, struct plugin_data *data)
{
  data->fsend = soap->fsend; // save old recv callback
  data->frecv = soap->frecv; // save old send callback
  soap->fsend = plugin_send; // replace send callback with new
  soap->frecv = plugin_recv; // replace recv callback with new
  return SOAP_OK;
}

// copy plugin data, called by soap_copy() // This is important: we need a deep copy to avoid data sharing by two run-time contexts
static int plugin_copy(struct soap *soap, struct soap_plugin *dst, struct soap_plugin *src)
{
  if (!(dst->data = (struct plugin_data*)malloc(sizeof(struct plugin_data)))))
    return SOAP_EOM;
  *dst->data = *src->data;
  return SOAP_OK;
}

// plugin deletion, called by soap_done()
static void plugin_delete(struct soap *soap, struct soap_plugin *p)
{ free(p->data); // free allocated plugin data
}

// the new send callback
static int plugin_send(struct soap *soap, const char *buf, size_t len)
{
  struct plugin_data *data = (struct plugin_data*)soap_lookup_plugin(soap, plugin_id); // fetch plugin’s local data
  fwrite(buf, len, 1, stderr); // write message to stderr
  return data->fsend(soap, buf, len); // pass data on to old send callback
}

// the new receive callback
static size_t plugin_recv(struct soap *soap, char *buf, size_t len)
{
  struct plugin_data *data = (struct plugin_data*)soap_lookup_plugin(soap, plugin_id); // fetch plugin’s local data
  size_t res = data->frecv(soap, buf, len); // get data from old recv callback
  fwrite(buf, res, 1, stderr);
  return res;
}

The fdelete callback of struct soap_plugin MUST be set to register the plugin. It is the responsibility of the plug-in to handle registry (init), copy, and deletion of the plug-in data and callbacks.

A plugin is copied with the soap_copy() call. This function copies a soap struct and the chain of plugins. It is up to the plugin implementation to share the plugin data or not:
1. if the `fcopy()` callback is set by the plugin initialization, this callback will be called to allow the plugin to copy its local data upon a `soap_copy()` call. When `soap_done()` is called on the soap struct copy, the `fdelete()` callback is called for deallocation and cleanup of the local data.

2. if the `fcopy()` callback is not set, then the plugin data will be shared (i.e. the data pointer points to the same address). The `fdelete()` callback will not be called upon a `soap_done()` on a copy of the soap struct. The `fdelete()` callback will be called for the original soap struct with which the plugin was registered.

The example plug-in should be used as follows:

```c
struct soap soap;
soap_init(&soap);
soap_register_plugin(&soap, plugin);
...
soap_done(&soap);
```

Note: `soap_register_plugin(...)` is an alias for `soap_register_plugin_arg(..., NULL)`. That is, it passes NULL as an argument to plug-in’s registry callback.

A number of example plug-ins are included in the gSOAP package’s plugin directory. Some of these plug-ins are discussed.

### 19.38.1 The Message Logging and Statistics Plug-in

The message logging and access statistics plug-in can be used to selectively log inbound and outbound messages to a file or stream. It also keeps access statistics to log the total number of bytes sent and received.

To use the plug-in, compile and link your application with `logging.c` located in the plugin directory of the package. To enable the plug-in in your code, register the plug-in and set the streams as follows:

```c
#include "logging.h"
size_t bytes_in;
size_t bytes_out;
...
if (soap_register_plugin(&soap, logging))
    soap_print_fault(&soap, stderr); // failed to register
...
soap_set_logging_inbound(&soap, stdout);
soap_set_logging_outbound(&soap, stdout);
... process messages ...
soap_set_logging_inbound(&soap, NULL); // disable logging
soap_set_logging_outbound(&soap, NULL); // disable logging
soap_get_logging_stats(&soap, &bytes_out, &bytes_in);
```

If you use `soap_copy` to copy the soap struct with the plug-in, the plug-in’s data will be shared by the copy. Therefore, the statistics are not 100% guaranteed to be accurate for multi-threaded services since race conditions on the counters may occur. Mutex is not used to update the counters to avoid introducing expensive synchronization points. If 100% server-side accuracy is required, add mutex at the points indicated in the `logging.c` code.
19.38.2 RESTful Interface: The HTTP GET Plug-in

Client-side and server-side use of RESTful HTTP GET operations are supported with the HTTP GET plug-in plugin/httpget.c. The HTTP GET plug-in allows your server to handle RESTful HTTP GET requests and at the same time still serve SOAP-based POST requests. The plug-in provides support to client applications to issue HTTP GET operations to a server.

Note that HTTP GET requests can also be handled at the server side with the fget callback, see Section 19.7. However, the HTTP GET plug-in also keeps statistics on the number of successful POST and GET exchanges and failed operations (HTTP faults, SOAP Faults, etc.). It also keeps hit histograms accumulated for up to a year of runtime.

To use the plug-in, compile and link your application with httpget.c located in the plugin directory of the package. To enable the plug-in in your code, register the plug-in with your HTTP GET handler function as follows:

```c
#include "httpget.h"
...
if (soap_register_plugin_arg(&soap, httpget, (void*)my_http_get_handler))
    soap_print_fault(&soap, stderr); // failed to register
...
struct http_get_data *httpgetdata;
httpgetdata = (struct http_get_data*)soap_lookup_plugin(&soap, http.get.id);
if (!httpgetdata)
    ... // if the plug-in registered OK, there is certainly data but can't hurt to check
    ... process messages ...
size_t get_ok = httpgetdata->stat_get;
size_t post_ok = httpgetdata->stat_post;
size_t errors = httpgetdata->stat_fail;
...

const struct tm *T;
T = localtime(&now);
size_t hitsthisminute = httpgetdata->min[T->tm_min];
size_t hitsthishour = httpgetdata->hour[T->tm_hour];
size_t hitstoday = httpgetdata->day[T->tm_yday];
```

An HTTP GET handler can simply produce some HTML content, or any other type of content by sending data:

```c
int my_http_get_handler(struct *soap)
{
    soap->http_content = "text/html";
    soap_response(soap, SOAP_FILE);
    soap_send(soap, "¡htmlHello¡/html");
    soap_end_send(soap);
    return SOAP_OK; // return SOAP_OK or HTTP error code, e.g. 404
}
```

If you use soap_copy to copy the soap struct with the plug-in, the plug-in’s data will be shared by the copy. Therefore, the statistics are not 100% guaranteed to be accurate for multi-threaded services.
since race conditions on the counters may occur. Mutex is not used to update the counters to avoid introducing expensive synchronization points. If 100% server-side accuracy is required, add mutex at the points indicated in the httpget.c code.

The client-side use of HTTP GET is provided by the soap.get_connect operation. To receive a SOAP/XML (response) message ns:methodResponse, use:

```c
#include "httpget.h"
... soap_register_plugin(&soap, http_get);
... if (soap_get_connect(&soap, endpoint, action))
    ... connect error ...
else if (soap_recv_ns__methodResponse(&soap, ... params ...))
    ... error ...
else
    ... ok ...
soap_destroy(&soap);
soap_end(&soap);
soap_done(&soap);
```

To receive any HTTP Body data into a buffer, use:

```c
#include "httpget.h"
... char *response = NULL;
soap_register_plugin(&soap, http_get);
... if (soap_get_connect(&soap, endpoint, NULL))
    ... connect error ...
else if (soap_begin_recv(&soap))
    ... error ...
else
    response = soap_get_http_body(&soap);
soap_end_recv(&soap);
... use the 'response' string (NULL indicates no body or error)
soap_destroy(&soap);
soap_end(&soap);
soap_done(&soap);
```

19.38.3 RESTful Interface: The HTTP POST Plug-in

Client-side and server-side use of RESTful HTTP POST, PUT, and DELETE operations are supported with the HTTP POST plug-in plugin/httppost.c.

The HTTP POST plug-in allows your server to handle RESTful HTTP POST requests and at the same time still serve SOAP-based POST requests. The plug-in also provides support for client applications to issue HTTP POST operations to a server.

To simplify the server-side handling of POST requests, handlers can be associated with media types:
struct http_post_handlers my_handlers[] =
{
    {"image/jpg", jpeg_handler },
    {"image/ *", image_handler },
    {"text/html", html_handler },
    {"text/ *", text_handler },
    {"text/ *;*", text_handler },
    { "POST", generic_POST_handler },
    { "PUT", generic_PUT_handler },
    { "DELETE", generic_DELETE_handler },
    { NULL }
};

Note that ‘*’ can be used as a wildcard and some media types may have optional parameters (after ‘;’). The handlers are functions that will be invoked when a POSTed request message matching media type is send to the server.

An example image handler that checks the specific image type:

```c
int image_handler(struct soap *soap)
{
    const char *buf;
    size_t len;
    // if necessary, check type in soap-¡http_content
    if (soap-¡http_content && !soap_tag_cmp(soap-¡http_content, "image/gif")
        return 404; // HTTP error 404
    if (soap_http_body(soap, &buf, &len) != SOAP_OK)
        return soap-¡error;
    // ... now process image in buf
    // reply with empty HTTP OK response:
    soap_response(soap, SOAP_OK);
    soap_end_send(soap);
    return SOAP_OK;
}
```

The HTTP POST plug-in provides a soap_http_body operation as illustrated above to copy the HTTP Body content into a buffer.

The above example returns HTTP OK. If content is supposed to be returned, then use:

```c
soap-¡http_content = "image/jpeg"; // a jpeg image to return back
soap_response(soap, SOAP_FILE); // SOAP_FILE sets custom http content
soap_send_raw(soap, buf, len); // send image
soap_end_send(soap);
```

For client applications to use HTTP POST, use the soap_post_connect operation:

```c
char *buf; // holds the HTTP request/response body data
size_t len; // length of data
...
if (soap_post_connect(soap, "URL", "SOAP action or NULL", "media type")
    || soap_send_raw(soap, buf, len);
    || soap_end_send(soap))
```
... error ...
if (soap_begin_recv(&soap)
    || soap_http_body(&soap, &buf, &len)
    || soap_end_recv(&soap))
... error ...
// ... use buf[0..len-1]
soap_end(soap);

Similarly, soap_put_connect and soap_delete_connect commands are provided for PUT and DELETE handling.

19.38.4 The HTTP MD5 Checksum Plug-in

The HTTP MD5 plug-in works in the background to automatically verify the content of messages using MD5 checksums. With the plug-in, messages can be transferred over (trusted but) unreliable connections. The plug-in can be used on the client side and server side.

To use the plug-in, compile and link your application with httpmd5.c and md5evp.c located in the plugin directory of the package. The md5evp.c implementation uses the EVP interface to compute MD5 checksums with OpenSSL (compiled with -DWITH_OPENSSL).

To enable the plug-in in your code, register the plug-in as follows:

```
#include "httpmd5.h"
...
if (soap_register_plugin(&soap, http_md5))
    soap_print_fault(&soap, stderr); // failed to register
```

Once registered, MD5 checksums are produced for all outbound messages. Inbound messages with MD5 checksums in the HTTP header are automatically verified.

The plug-in requires you to set the SOAP_IO_STORE flag when sending SOAP with attachments:

```
#include "httpmd5.h"
...
struct soap soap;
soap_init1(&soap, SOAP_IO_STORE);
if (soap_register_plugin(&soap, http_md5)
    soap_print_fault(&soap, stderr); // failed to register
    ... now safe to send SOAP with attachments ...
```

Unfortunately, this eliminates streaming.

19.38.5 The HTTP Digest Authentication Plug-in

The HTTP digest authentication plug-in enables a more secure authentication scheme compared to basic authentication. HTTP basic authentication sends unencrypted userids and passwords over the net, while digest authentication does not exchange passwords but exchanges checksums of passwords (and other data such as nonces to avoid replay attacks). For more details, please see RFC 2617.

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The HTTP digest authentication can be used next to the built-in basic authentication, or basic authentication can be rejected to tighten security. The server must have a database with userid’s and passwords (in plain text form). The client, when challenged by the server, checks the authentication realm provided by the server and sets the userid and passwords for digest authentication. The client application can temporarily store the userid and password for a sequence of message exchanges with the server, which is faster than repeated authorization challenges and authentication responses.

At the client side, the plug-in is registered and service invocations are checked for authorization challenges (HTTP error code 401). When the server challenges the client, the client should set the userid and password and retry the invocation. The client can determine the userid and password based on the authentication realm part of the server’s challenge. The authentication information can be temporarily saved for multiple invocations.

Client-side example:

```c
#include "httpda.h"
...
if soap_register_plugin(&soap, http_da))
    soap_print_fault(&soap, stderr); // failed to register
...
if (soap_call_ns_method(&soap, ...) != SOAP_OK)
{
    if (soap.error == 401) // challenge: HTTP authentication required
    {
        if (!strcmp(soap.authrealm, authrealm)) // determine authentication realm
        {
            struct http_da_info info; // to store userid and passwd
            http_da_save(&soap, &info, authrealm, userid, passwd); // set userid and passwd for this realm
            if (soap_call_ns_method(&soap, ...) == SOAP_OK) // retry
            {
                soap_end(&soap); // userid and passwd were deallocated
                http_da_restore(&soap, &info); // restore userid and passwd
            }
            if (!soap_call_ns_method(&soap, ...) == SOAP_OK) // another call
            {
                ...
                http_da_release(&soap, &info); // remove userid and passwd
            }
        }
    }
}
```

This code supports both basic and digest authentication.

The server can challenge a client using HTTP code 401. With the plug-in, HTTP digest authentication challenges are sent. Without the plug-in, basic authentication challenges are sent.

Each server method can implement authentication as desired and may enforce digest authentication or may also accept basic authentication responses. To verify digest authentication responses, the server should compute and compare the checksums using the plug-in’s `http_da_verify_post` function for HTTP POST requests (and `http_da_verify_get` for HTTP GET requests with the HTTP GET plugin) as follows:

```c
#include "httpda.h"
...
if (soap_register_plugin(&soap, http_da))
```
soap_print_fault(&soap, stderr); // failed to register
...
soap_server(&soap);
...

int ns_method(struct soap *soap, ...)
{
  if (soap->userid && soap->passwd) // client used basic authentication
  { // may decide not to handle, but if ok then go ahead and compare info:
    if (!strcmp(soap->userid, userid) && !strcmp(soap->passwd, passwd))
    { ... handle request ...
      return SOAP_OK;
    }
  }
  else if (soap->authrealm && soap->userid) // Digest authentication
  {
    passwd = ... // database lookup on userid and authrealm to find passwd
    if (!strcmp(soap->authrealm, authrealm) && !strcmp(soap->userid, userid))
    {
      if (!http_da_verify_post(soap, passwd))
      { ... handle request ...
        return SOAP_OK;
      }
    }
  }
  soap->authrealm = authrealm; // set realm for challenge
  return 401; // Not authorized, challenge digest authentication
}

For more details, including how to configure HTTP Digest authentication for proxies, please see the doc/httpda/html/index.html documentation in the gSOAP package.

19.38.6 The WS-Addressing Plug-in

The WSA WS-Addressing plug-in and the source code are extensively documented in the doc/wsa directory of the gSOAP package. Please refer to the documentation included in the package.

The plug-in code is located in the plugin directory:

wsaapi.h and wsaapi.c  WS-Addressing plugin (C and C++)

To enable WS-Addressing 2005 (and support for 8/2004), the service definitions header file for soapcpp2 should include the following imports:

#include "import/wsa5.h"

This imports the SOAP header elements required by WS-Addressing.

For more details, please see the doc/wsa/html/index.html documentation in the gSOAP package.
19.38.7 The WS-ReliableMessaging Plug-in

The WSRM WS-ReliableMessaging plug-in and the source code are extensively documented in the doc/wsrm directory of the gSOAP package. Please refer to the documentation included in the package.

The plug-in code is located in the plugin directory:

   wsrmapi.h and wsrmapi.c   WS-ReliableMessaging plugin (C and C++)

Also needed are:

   threads.h and threads.c   Multithreading and locking support

To enable WS-ReliableMessaging, the service definitions header file for soapcpp2 should include the following imports:

   #import "import/wsrm.h"
   #import "import/wsa5.h"

This imports the SOAP header elements required by WS-ReliableMessaging.  
For more details, please see the doc/wsrm/html/index.html documentation in the gSOAP package.

19.38.8 The WS-Security Plug-in

The WSSE WS-Security plug-in and the source code are extensively documented in the doc/wsse directory of the gSOAP package. Please refer to the documentation included in the package for details.

The plug-in code is located in the plugin directory:

   wsseapi.h and wsseapi.c   WS-Security plugin (C and C++)

Also needed are:

   smdevp.h and smdevp.c   Streaming XML signature and message digest engine
   mecevp.h and mecevp.c   Streaming XML encryption engine
   threads.h and threads.c   Multithreading and locking support

To enable WS-Security, the service definitions header file for soapcpp2 should include the following imports:

   #import "import/wsse.h"

This imports the SOAP header elements required by WS-Security.
For more details, please see the doc/wsse/html/index.html documentation in the gSOAP package.
19.38.9  WS-Discovery

The WS-Discovery implementation is documented in the doc/wsdd directory of the gSOAP package. Please refer to the documentation included in the package for details.

Basically, to add WS-Discovery support the following event handlers must be defined and linked:

```c
void wsdd_event_Hello(struct soap *soap,
unsigned int InstanceId,
const char *Sequenceld,
unsigned int MessageNumber,
const char *MessageID,
const char *RelatesTo,
const char *EndpointReference,
const char *Types,
const char *Scopes,
const char *MatchBy,
const char *XAddrs,
unsigned int MetadataVersion)

void wsdd_event_Bye(struct soap *soap,
unsigned int InstanceId,
const char *Sequenceld,
unsigned int MessageNumber,
const char *MessageID,
const char *RelatesTo,
const char *EndpointReference,
const char *Types,
const char *Scopes,
const char *MatchBy,
const char *XAddrs,
unsigned int MetadataVersion)

soap_wsdd_mode wsdd_event_Probe(struct soap *soap,
const char *MessageID,
const char *ReplyTo,
const char *Types,
const char *Scopes,
const char *MatchBy,
struct wsdd_ProbeMatchesType *ProbeMatches)

void wsdd_event_ProbeMatches(struct soap *soap,
unsigned int InstanceId,
const char *Sequenceld,
unsigned int MessageNumber,
const char *MessageID,
const char *RelatesTo,
struct wsdd_ProbeMatchesType *ProbeMatches)

soap_wsdd_mode wsdd_event_Resolve(struct soap *soap,
const char *MessageID,
```
const char *ReplyTo,
const char *EndpointReference,
struct wsdd__ResolveMatchesType *ResolveMatches)

void wsdd_event.ResolveMatches(struct soap *soap,
unsigned int InstanceId,
const char *SequenceId,
const char *InstanceId,
unsigned int MessageNumber,
const char *MessageID,
const char *RelatesTo,
const char *EndpointReference,
const char *Types,
const char *Scopes,
const char *MatchBy,
const char *XAddrs,
unsigned int MetadataVersion)

These event handlers will be invoked when inbound WS-Discovery messages arrive using:

    if (!soap_valid_socket(soap_bind(soap, NULL, port, 100)))
        .. error
    if (soap_wsdwalletenListen(soap, timeout))
        ... error

which will listen for timeout seconds to inbound WS-Discovery messages on a port and dispatches
them to the event handlers. A negative timeout is measured in ns.